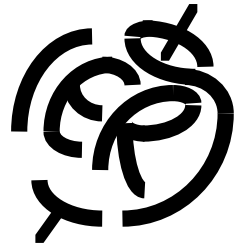


Tests of IGS Reference Frame Stability



Zuheir Altamimi
Institut Géographique National, France

Jim Ray
Bureau International des Poids et Mesures & National Geodetic Survey



Study of IGS TRF long-term stability on:

- **Frame Parameters: Origin, Scale, Orientation**
- **Polar Motion**

When:

- **changing the RS from 54 to 99**
- **using different sets of RS, but still globally distributed**

Analyzed Data: Weekly IGS combined SINEX files over 1999-2003

- **Impact of station discontinuities on Polar Motion**
- **Re-open the question about GPS Geocenter and TRF scale**

IGS 2004 Workshop, 01 March 2004, Berne, Switzerland

TRF & EOP time series Combination

CATREF Software

INPUT: $X(t)$, **EOP(t)** in daily/weekly/monthly SINEX files

OUTPUT: $X(t_0)$, \dot{X} , **EOP(t)**, $(\underbrace{T_x, T_y, T_z}_\text{Geocenter}, D, R_x, R_y, R_z)$

$$\left\{ \begin{array}{l} X_s^i = X_{itr f}^i + (t_s^i - t_0) \dot{X}_{itr f}^i + T_k + D_k X_{itr f}^i + R_k X_{itr f}^i \\ \quad + (t_s^i - t_k) \left[\dot{T}_k + \dot{D}_k X_{itr f}^i + \dot{R}_k X_{itr f}^i \right] \\ \dot{X}_s^i = \dot{X}_{itr f}^i + \dot{T}_k + \dot{D}_k X_{itr f}^i + \dot{R}_k X_{itr f}^i \end{array} \right.$$

$$\left\{ \begin{array}{l} x_s^p = x^p + R2_k \\ y_s^p = y^p + R1_k \\ UT_s = UT - \frac{1}{f} R3_k \\ \dot{x}_s^p = \dot{x}^p + \dot{R}2_k \\ \dot{y}_s^p = \dot{y}^p + \dot{R}1_k \\ LOD_s = LOD + \frac{\Lambda_0}{f} \dot{R}3_k \end{array} \right.$$

- Matching common parameters at UT noon
- Propagate at UT noon if rates are available
- **EOP's follow the adopted combined TRF**

Datum Definition

The combined TRF is aligned to IGS00 using Minimum Constraints equation applied over the 7 transformation parameters:

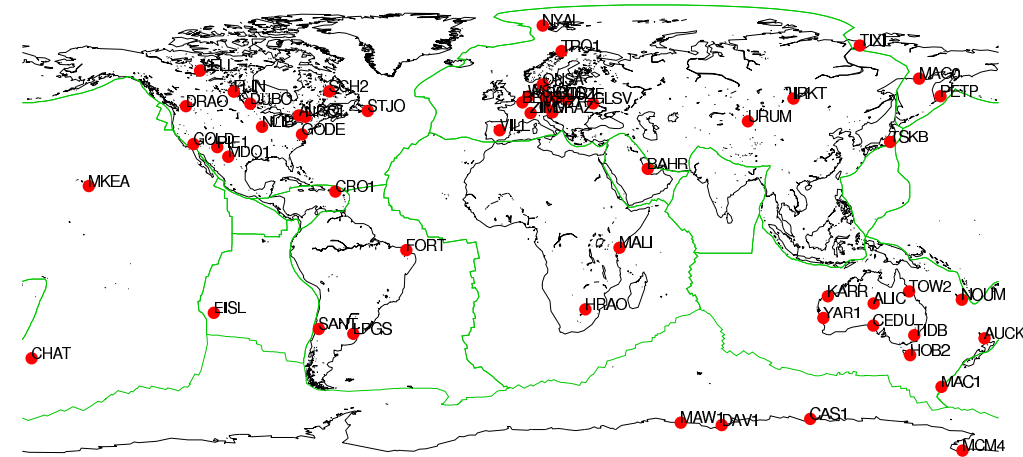
$$(A^T A)^{-1} A^T (X_{RS} - X_c) = 0$$

where A is a design matrix given by:

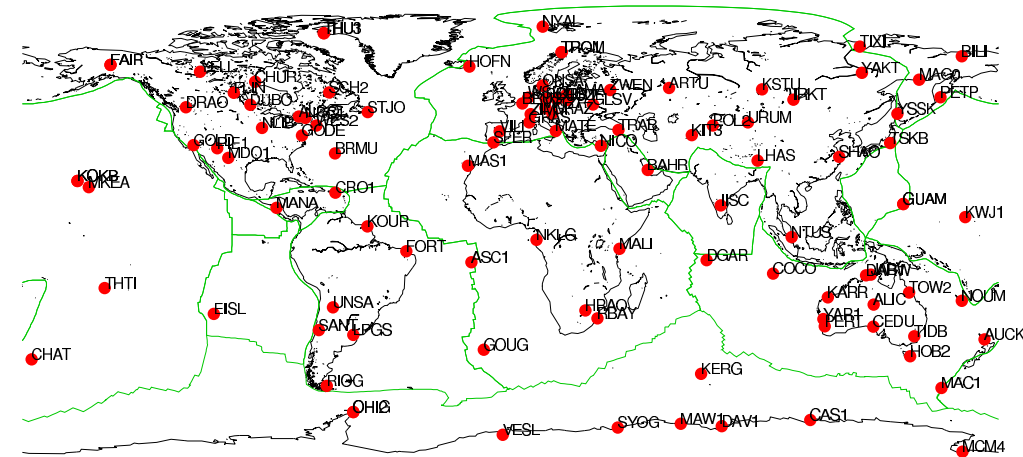
$$A = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 1 & 0 & 0 & x_0^i & 0 & z_0^i & -y_0^i \\ 0 & 1 & 0 & y_0^i & -z_0^i & 0 & x_0^i \\ 0 & 0 & 1 & z_0^i & y_0^i & -x_0^i & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

and x_0^i, y_0^i, z_0^i are approximate station positions.

54 Reference Stations Set



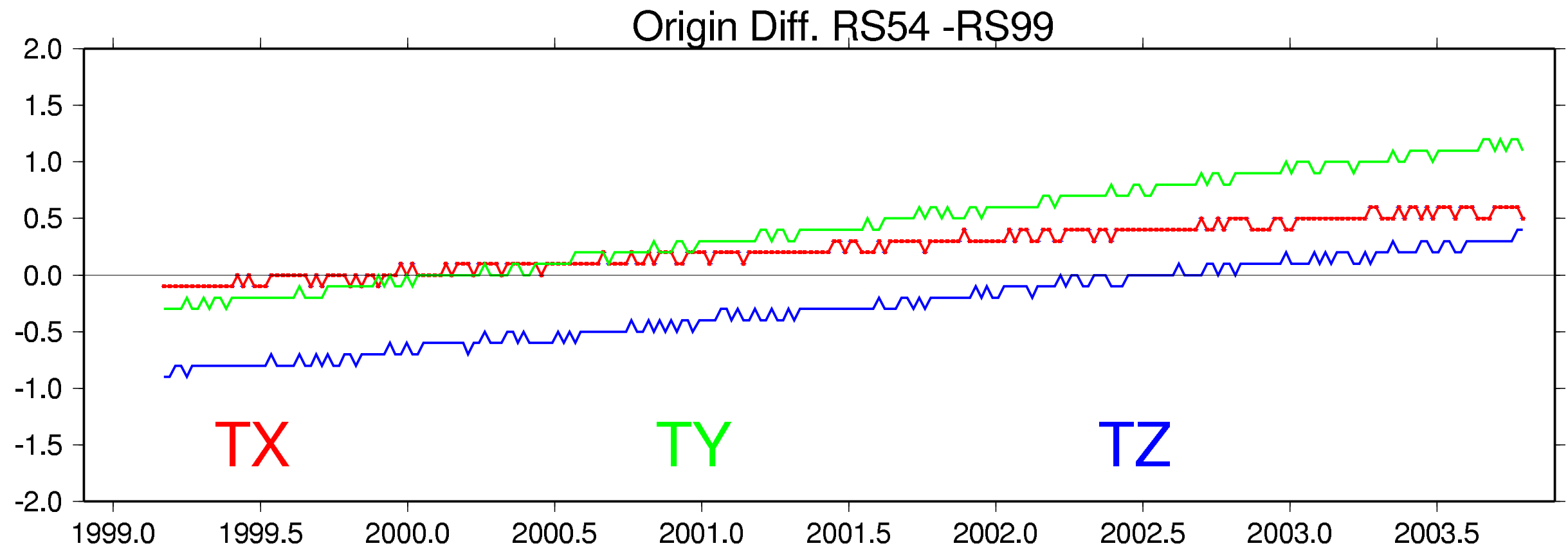
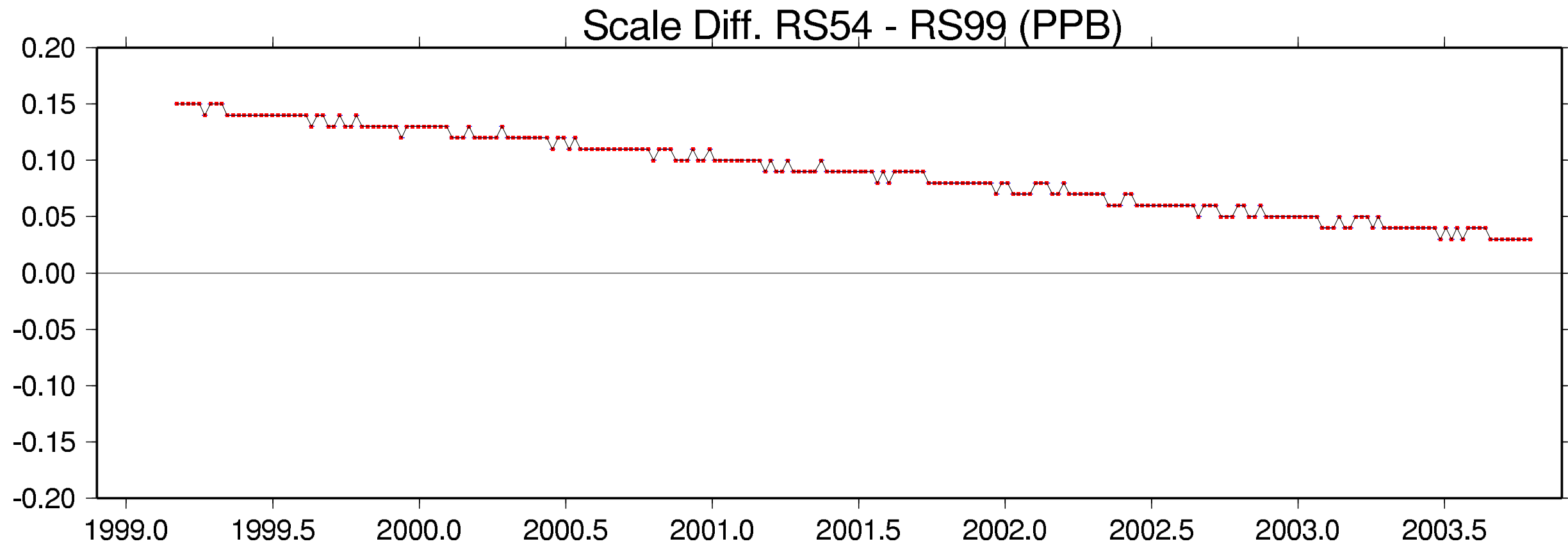
99 Reference Stations Set



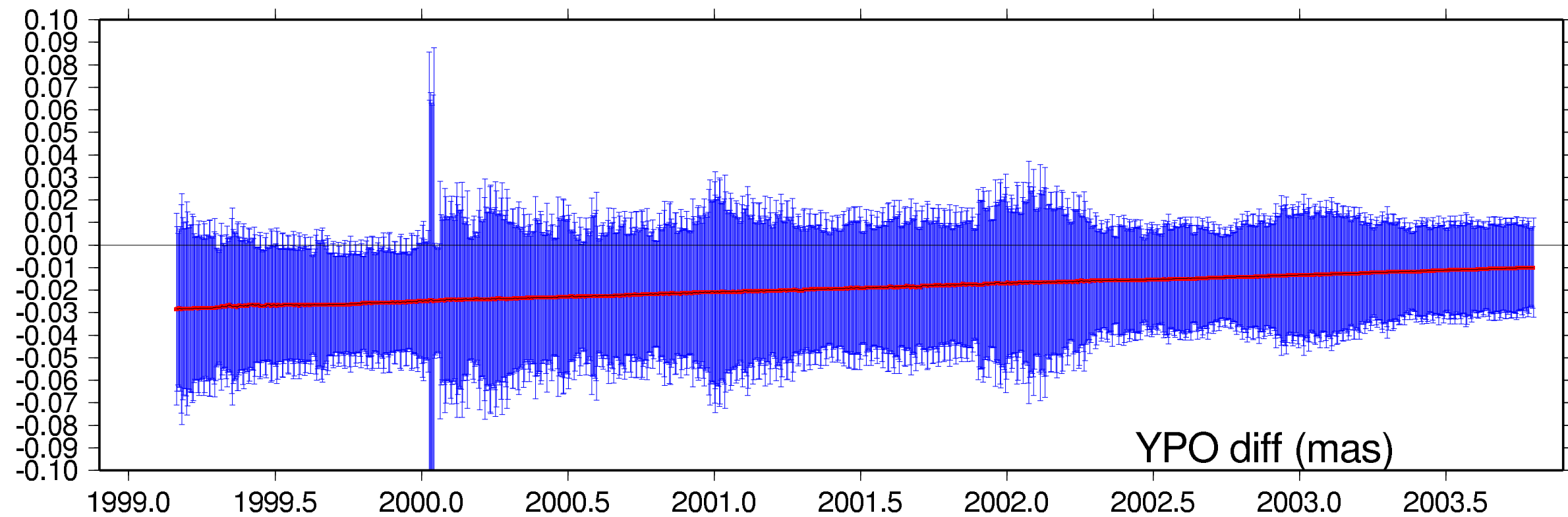
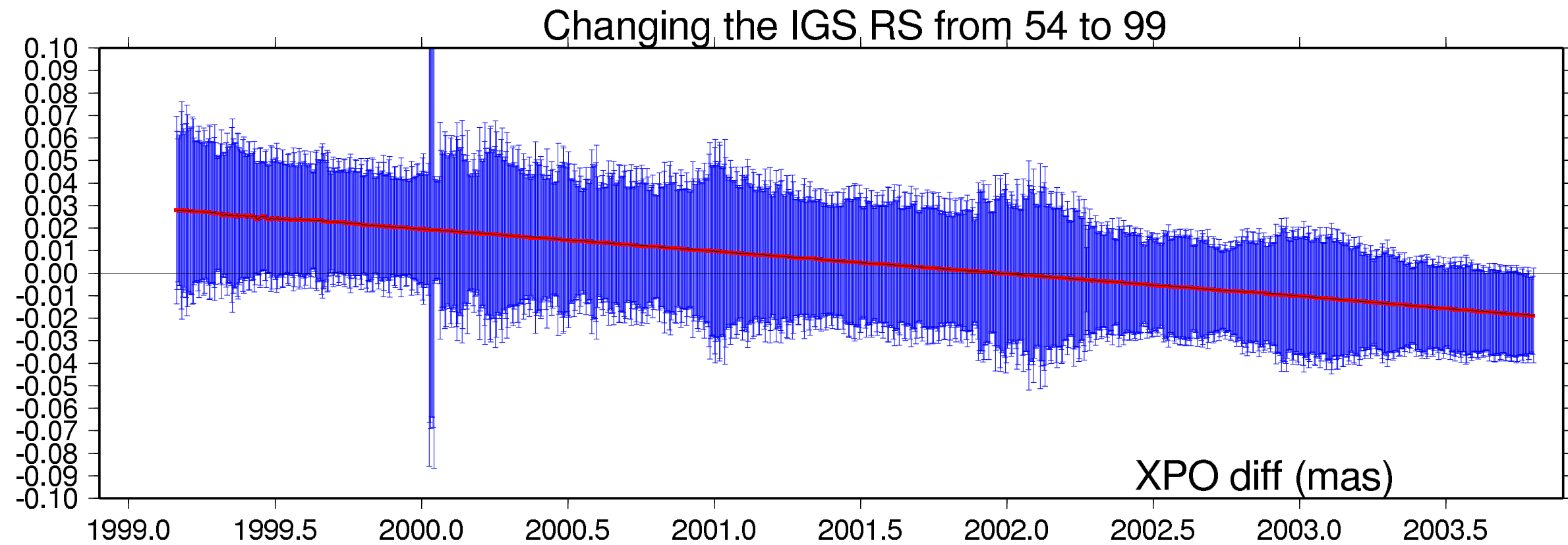
Using IGS00 RS, 10 sets were selected, but still globally distributed:

- 4 sets with ≈ 25 stations each
- 6 sets with ≈ 50 stations each

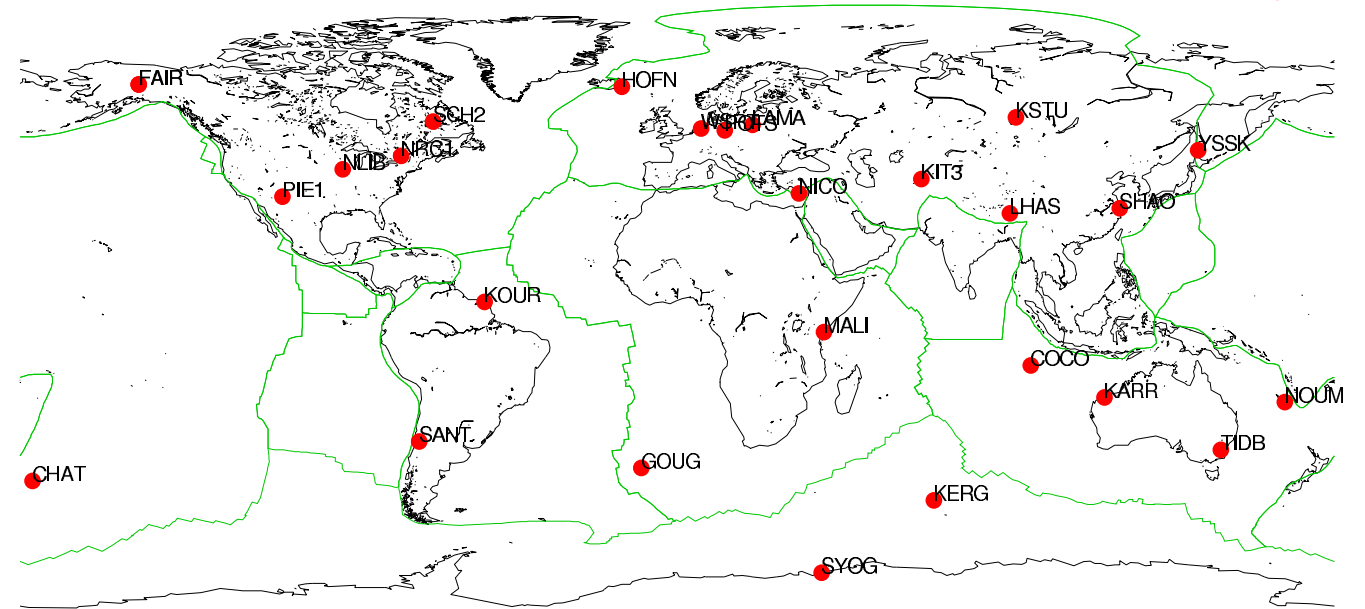
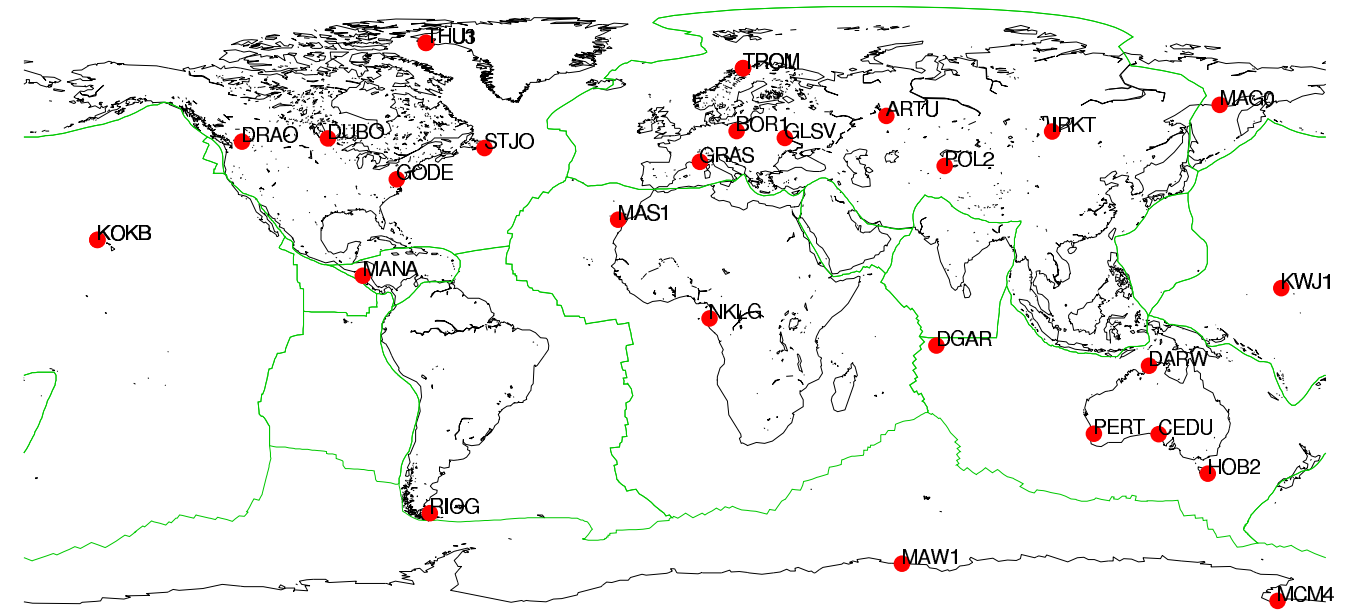
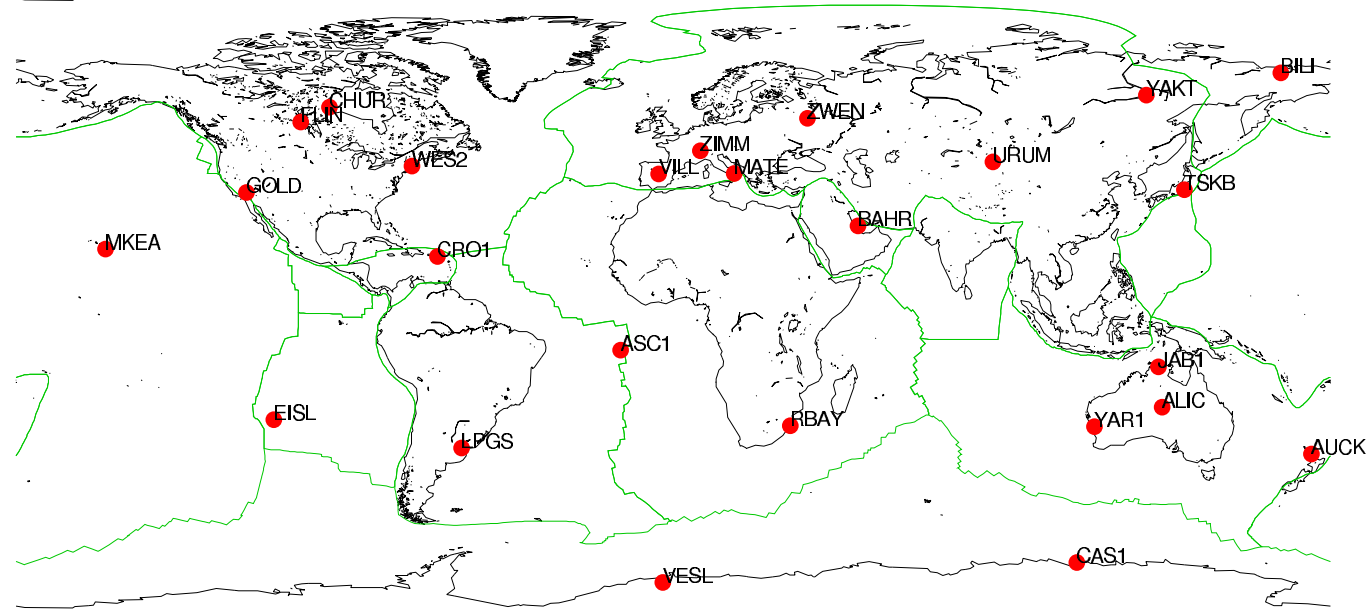
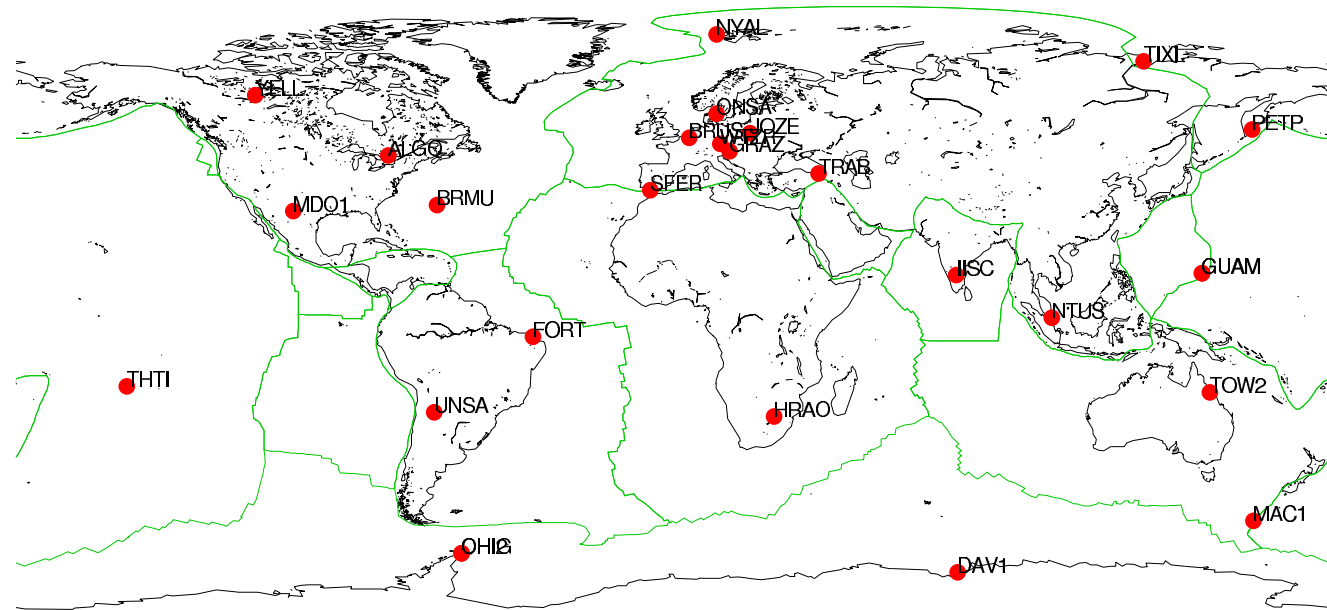
Scale & origin differences when changing the IGS RS from 54 to 99



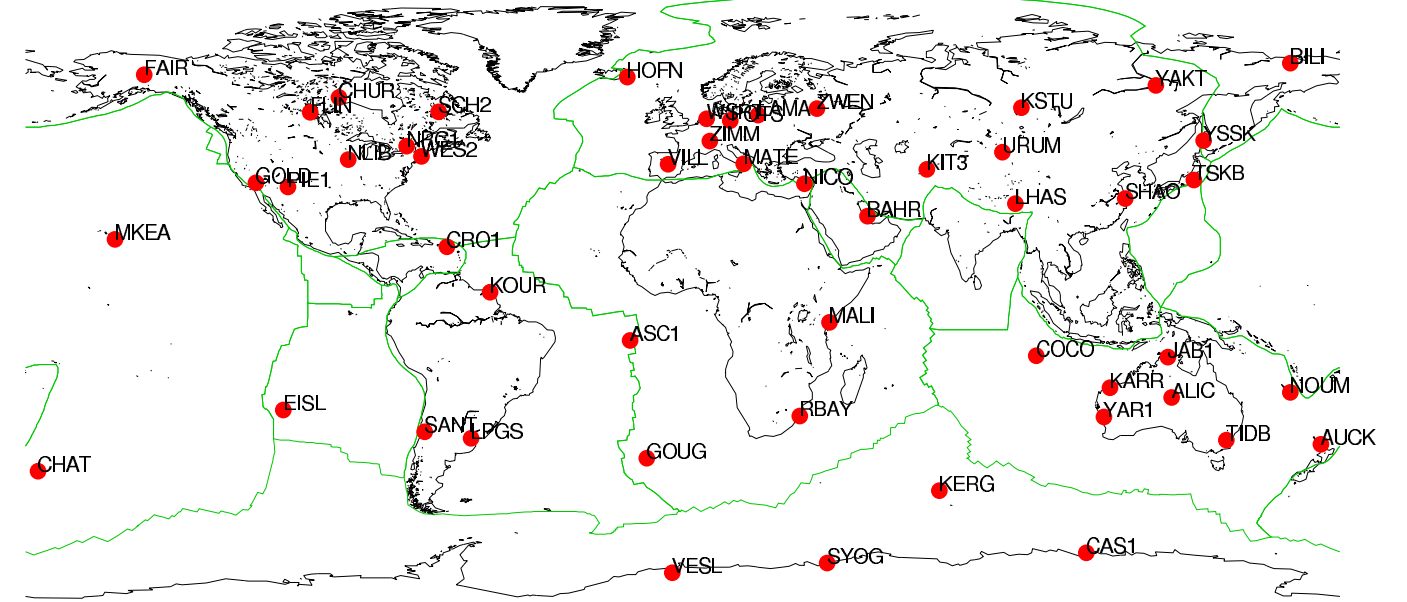
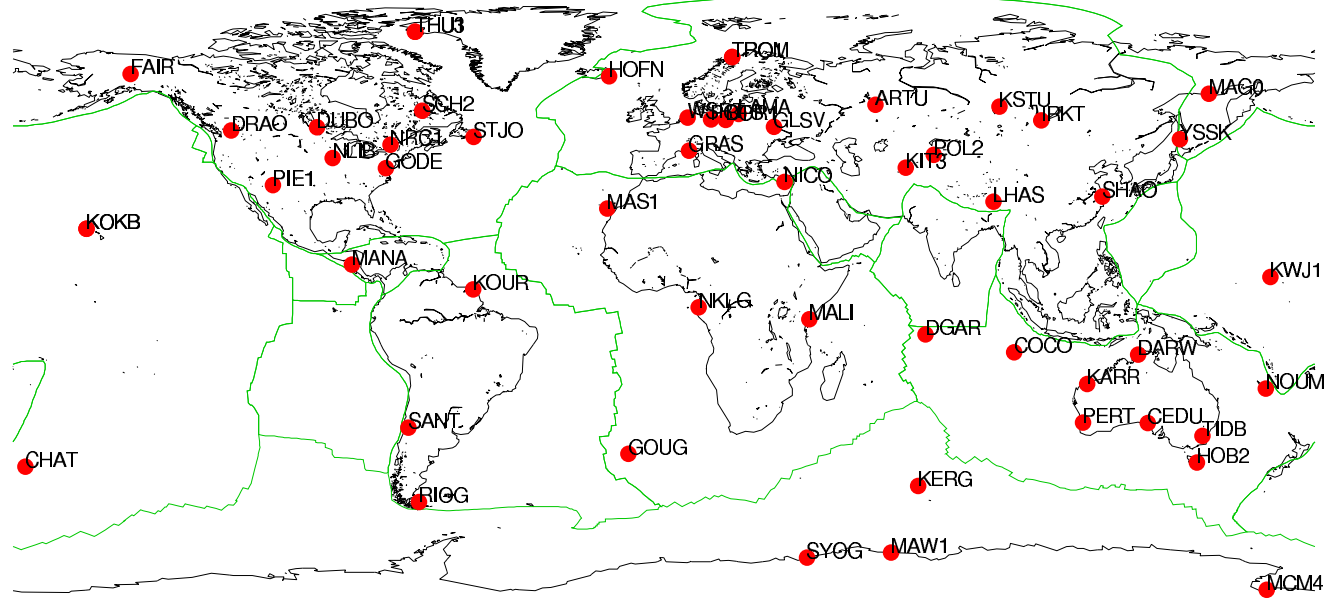
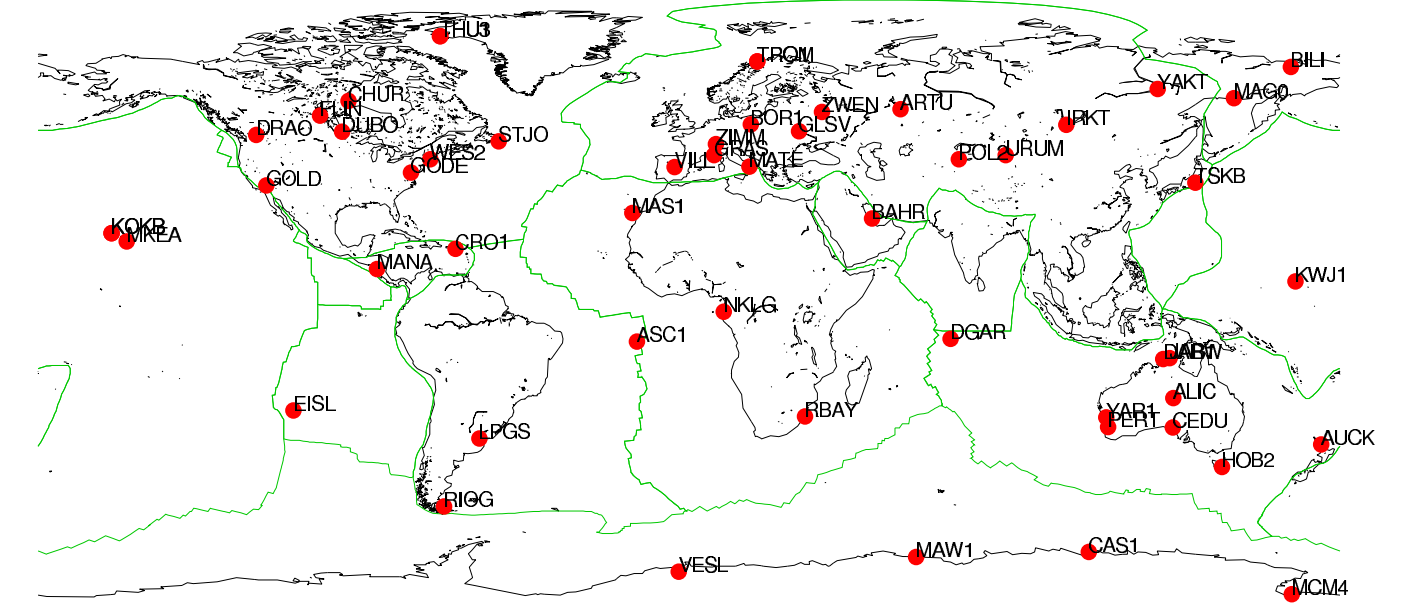
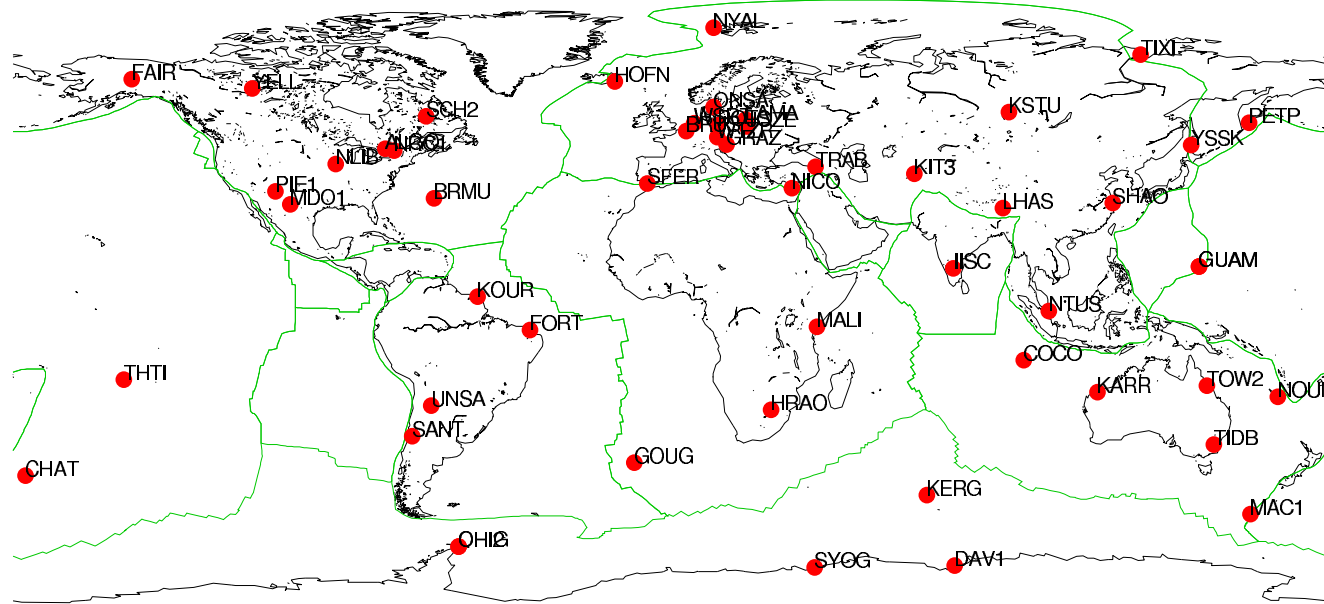
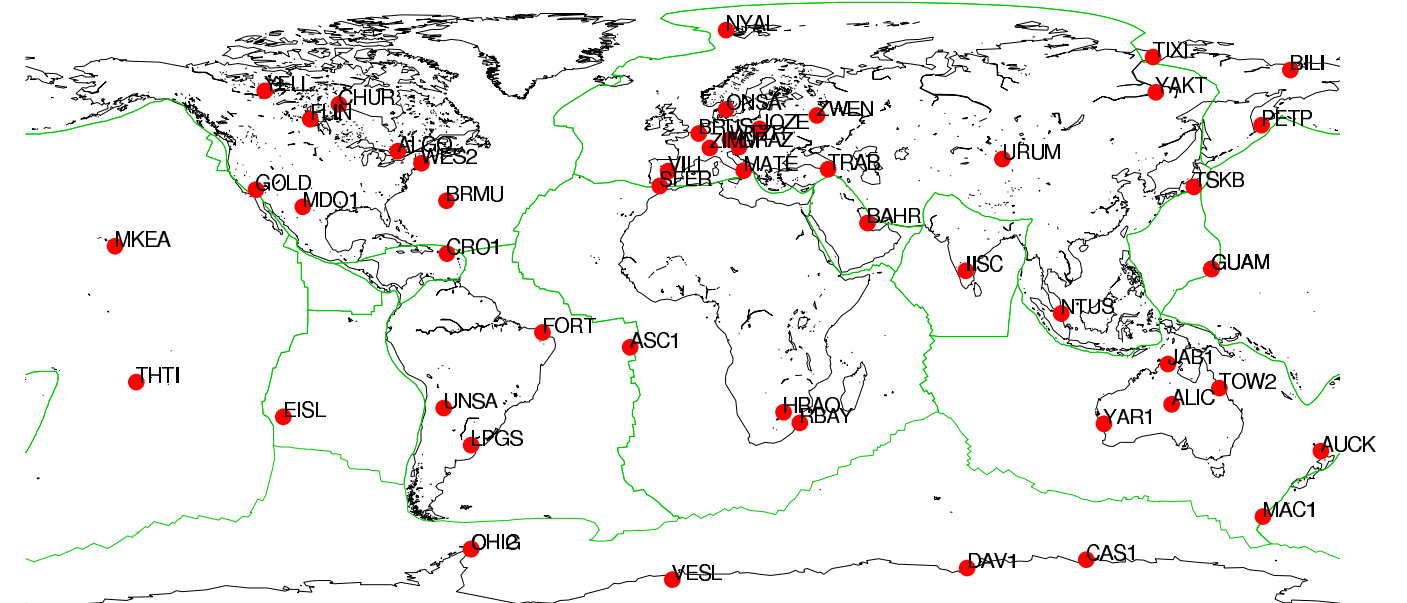
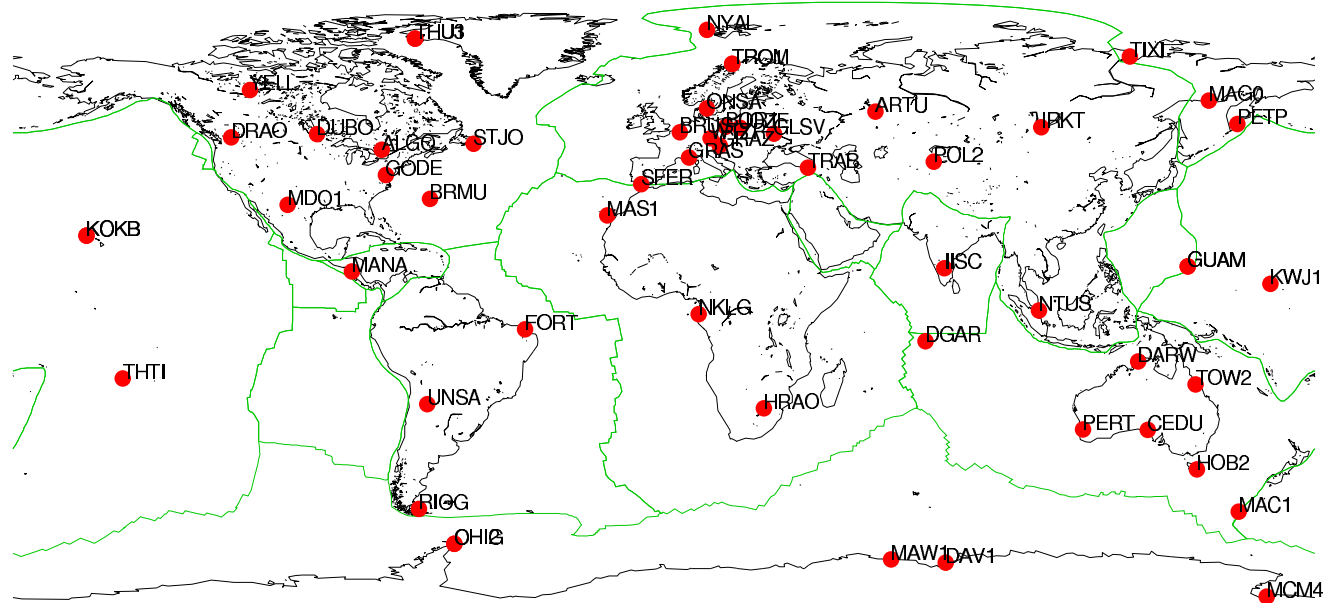
Polar Motion differences when changing the IGS RS from 54 to 99



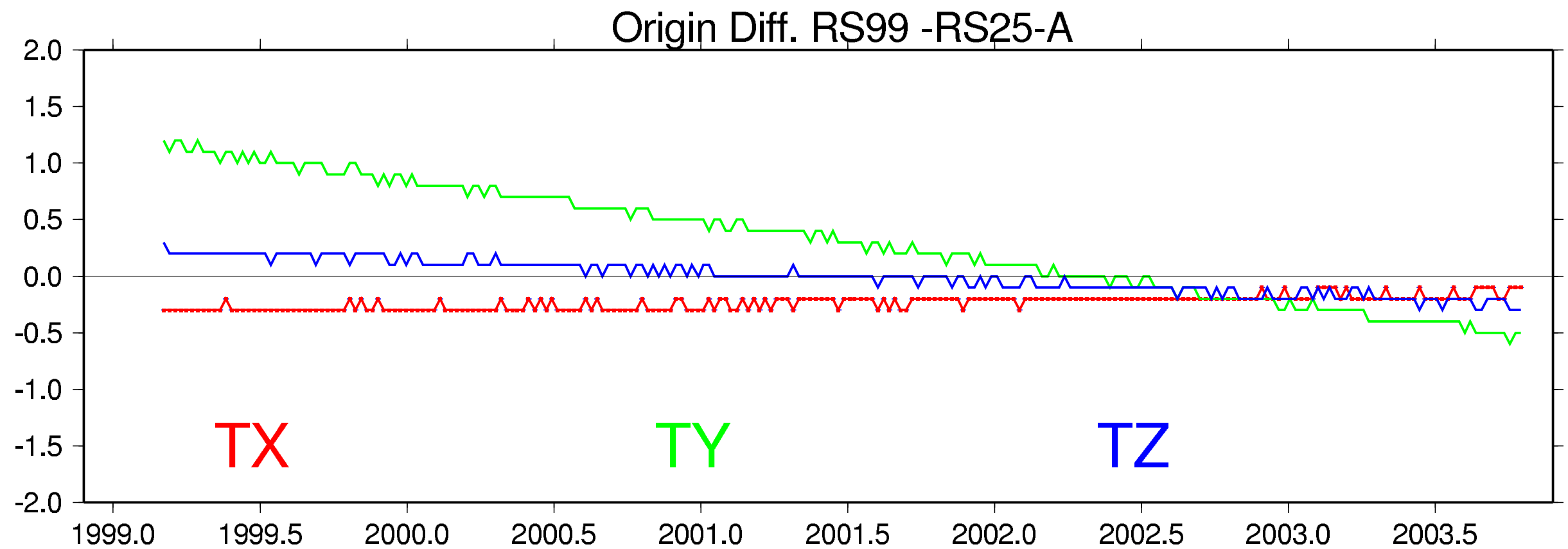
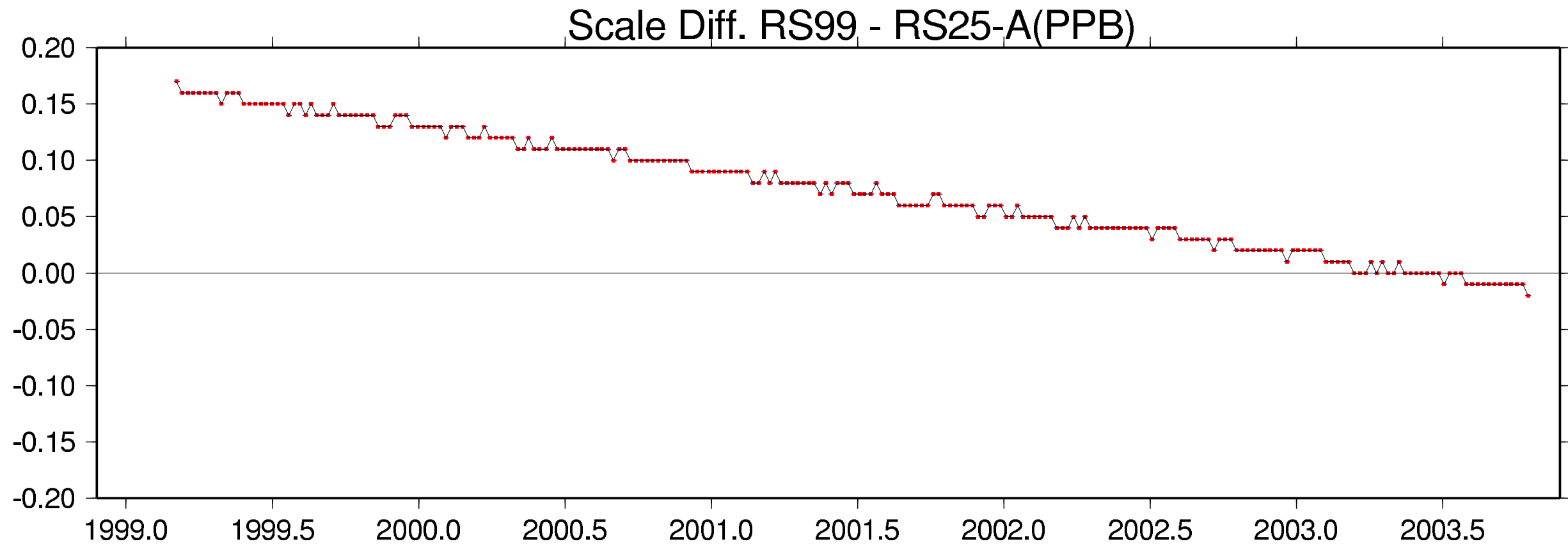
4 Networks of ~ 25 stations



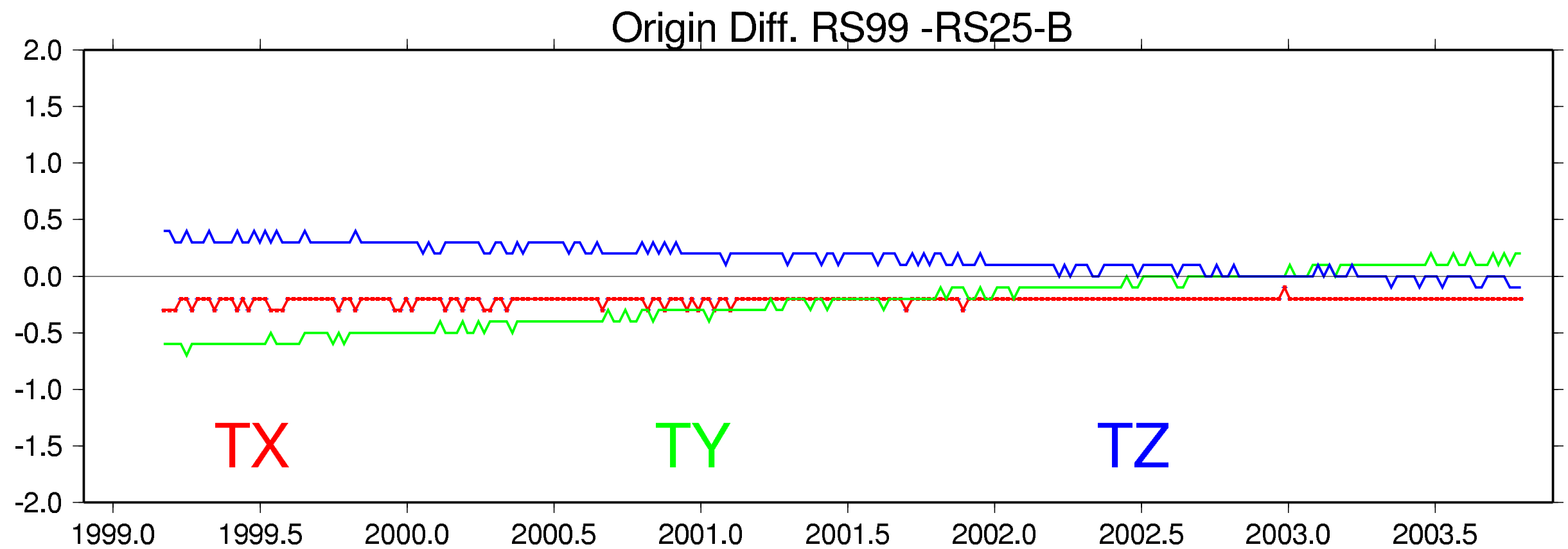
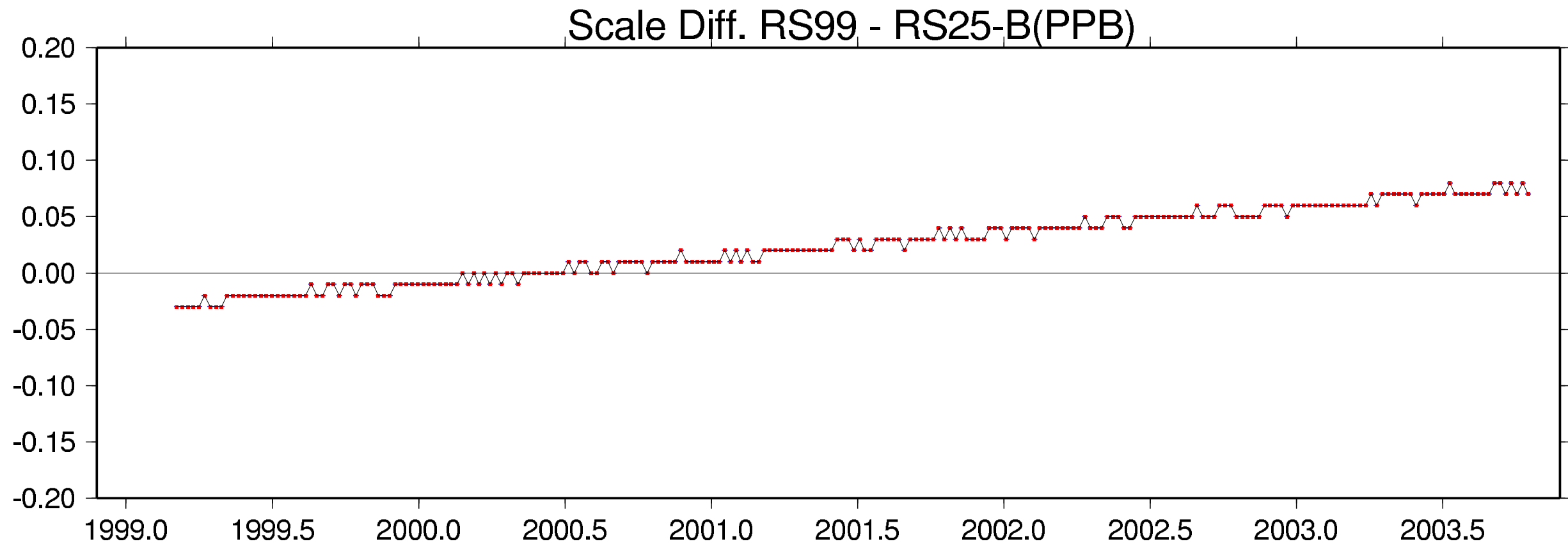
6 Networks of ~ 50 stations



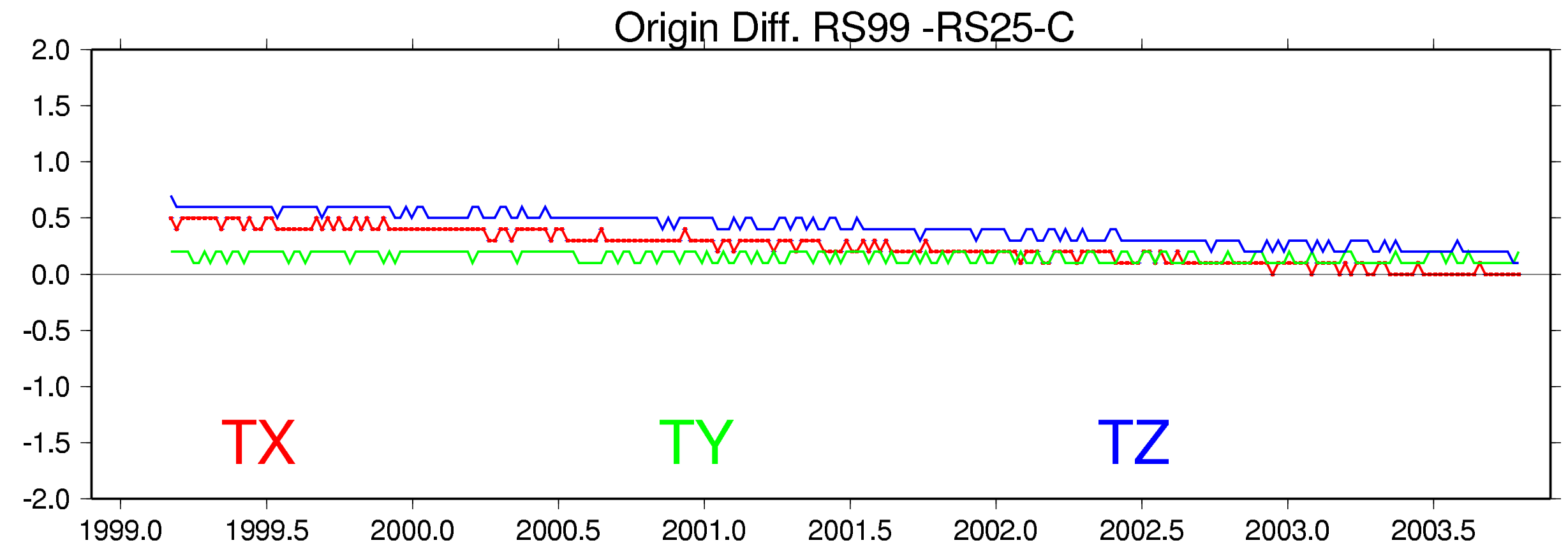
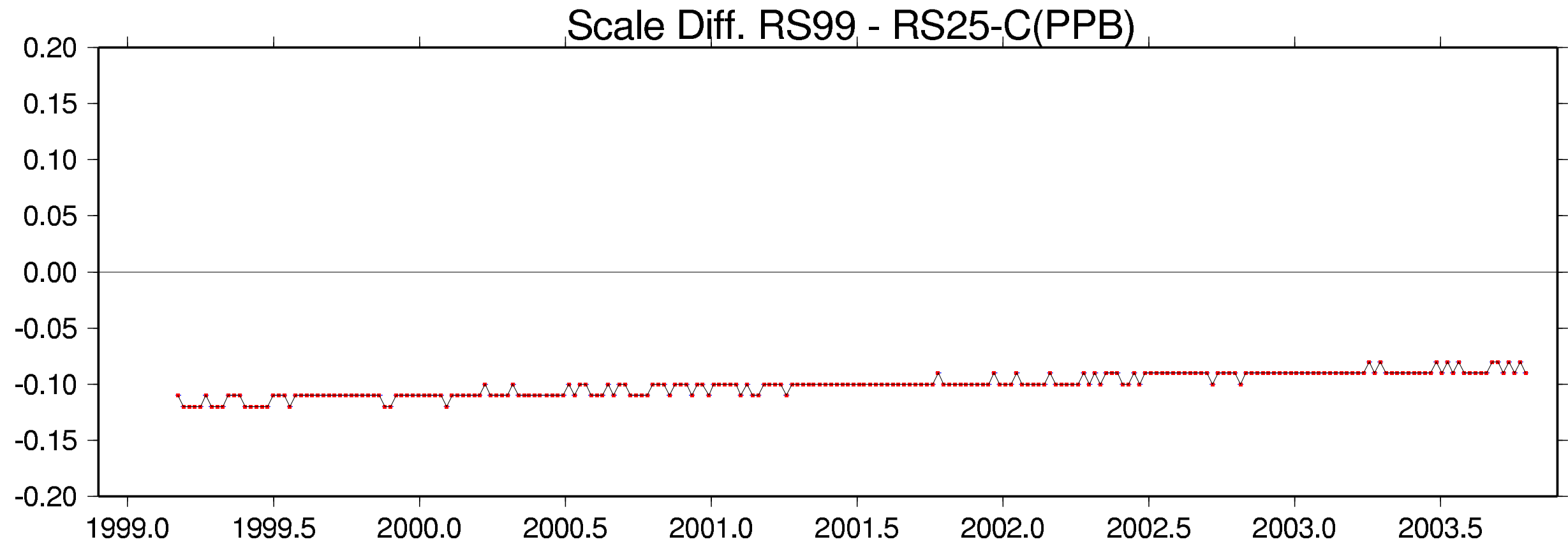
Scale & origin differences wrt RS99



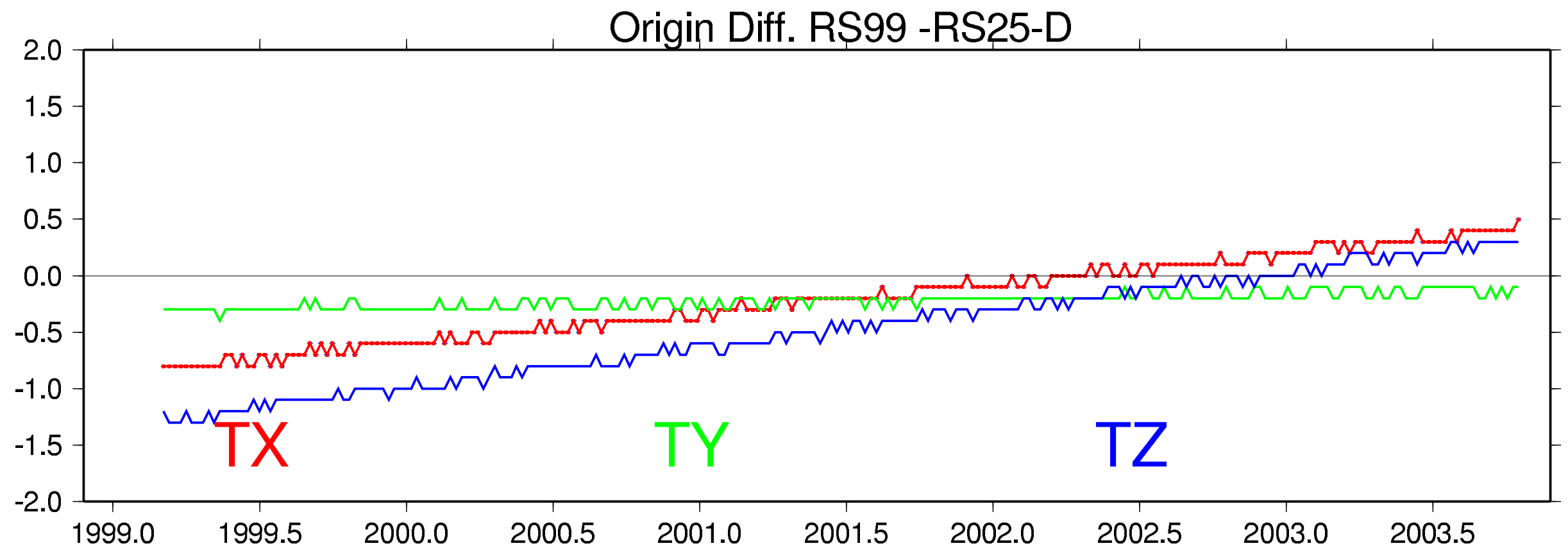
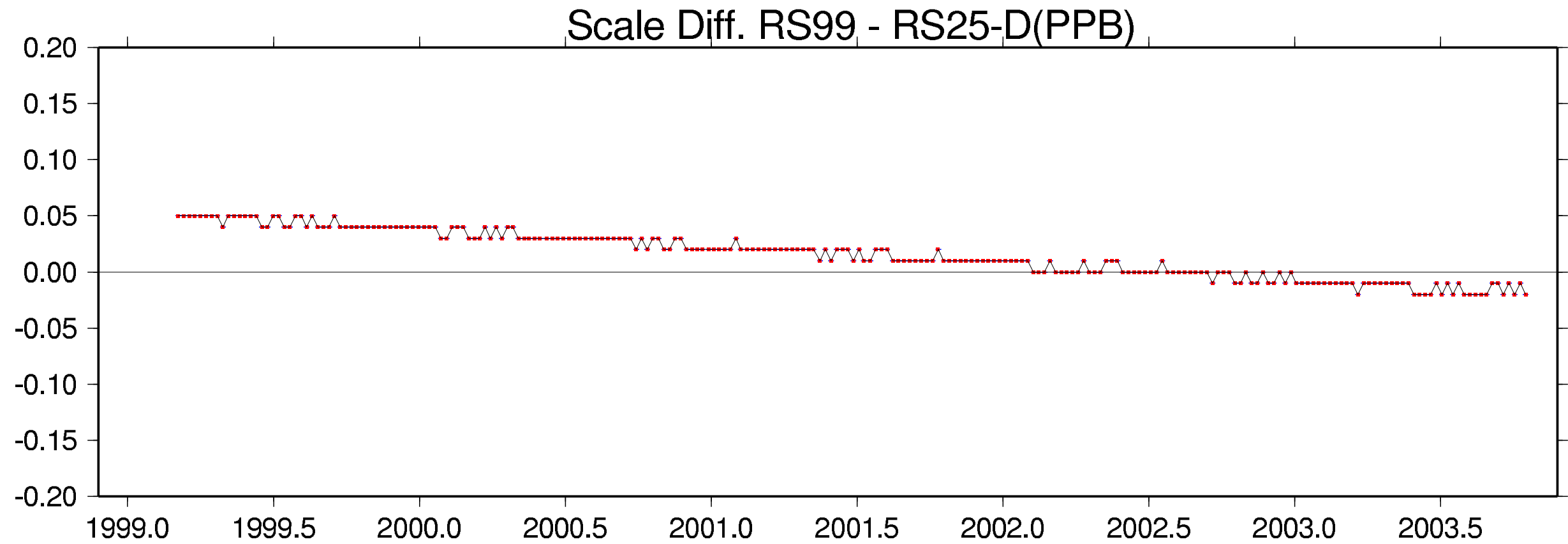
Scale & origin differences wrt RS99



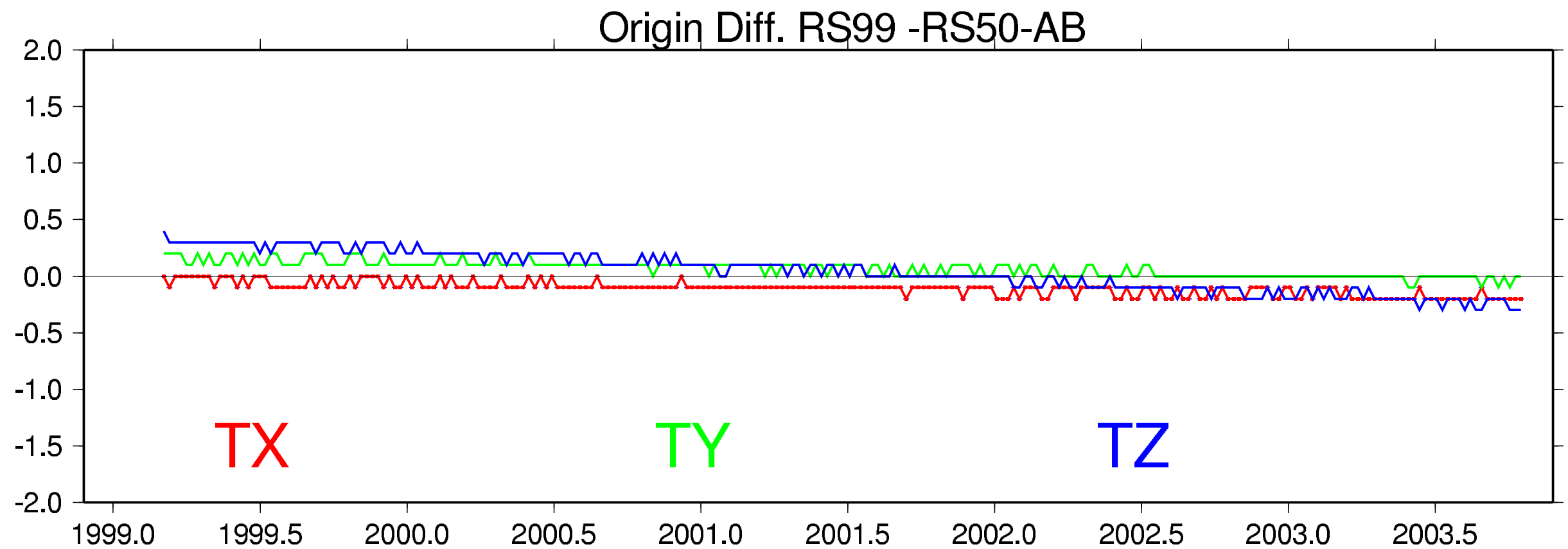
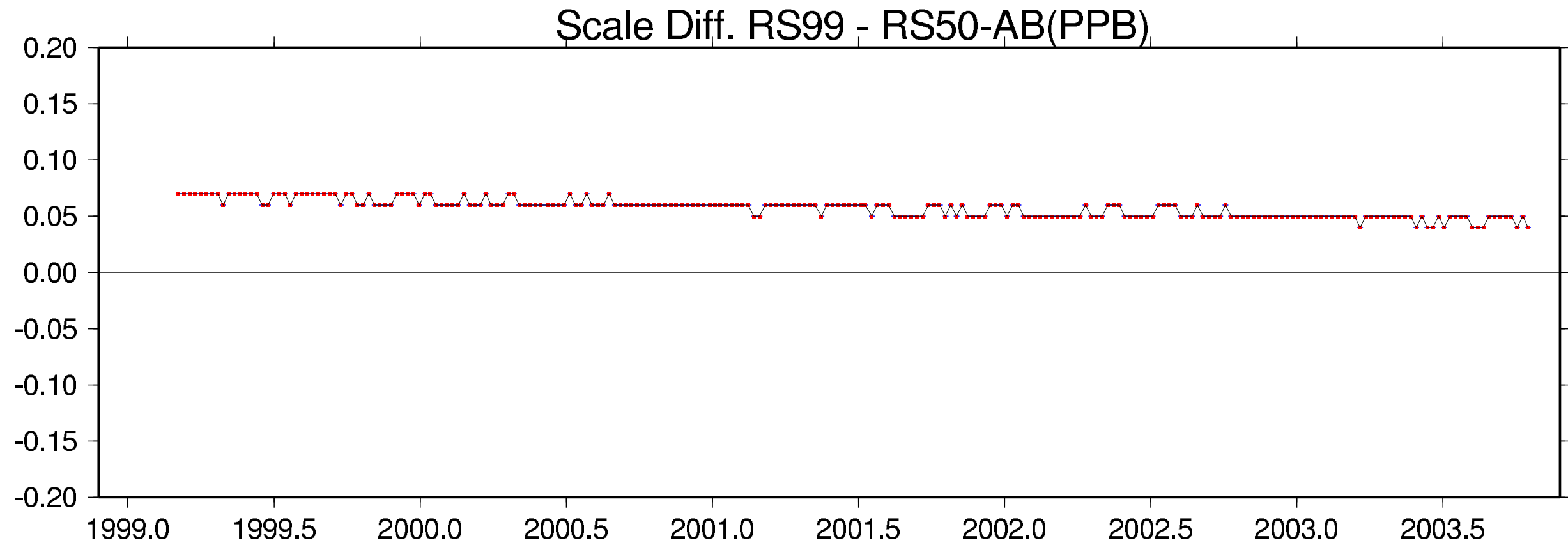
Scale & origin differences wrt RS99



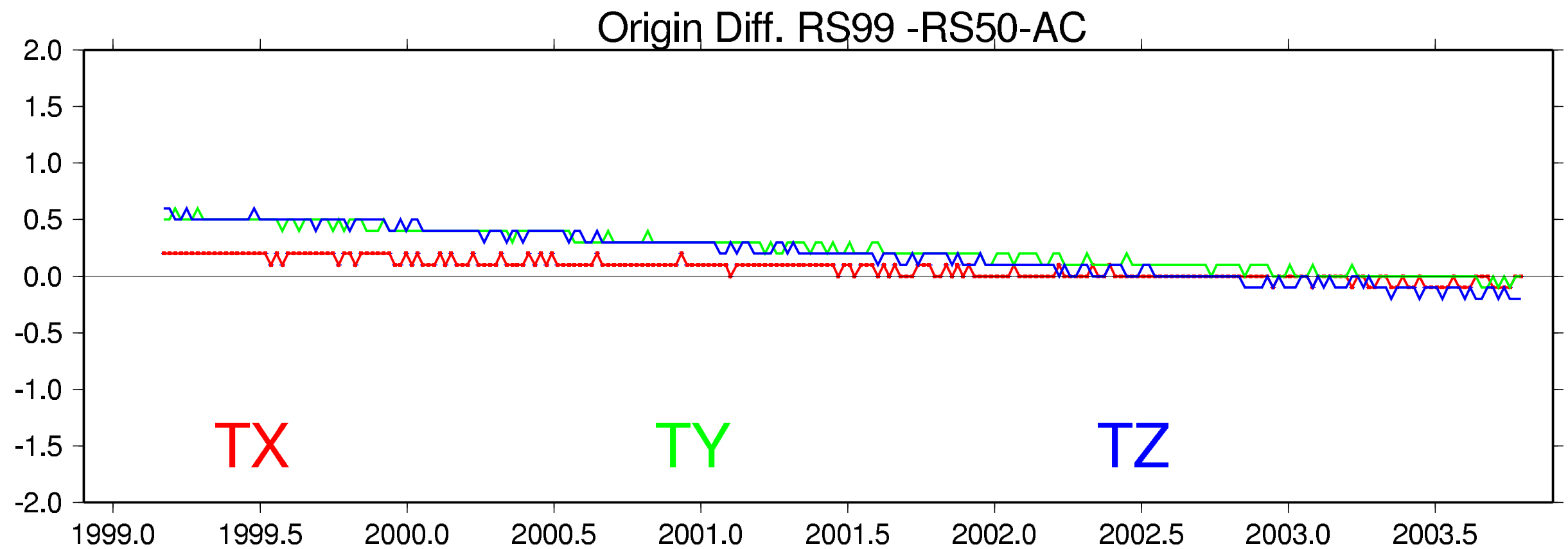
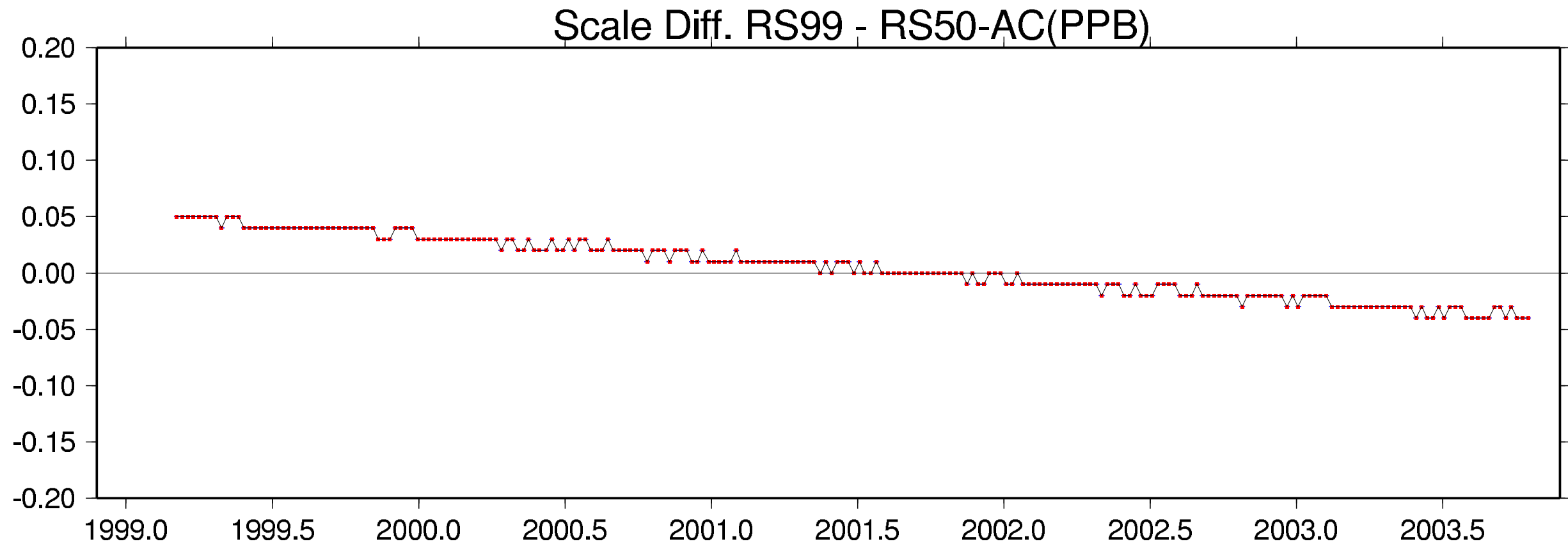
Scale & origin differences wrt RS99



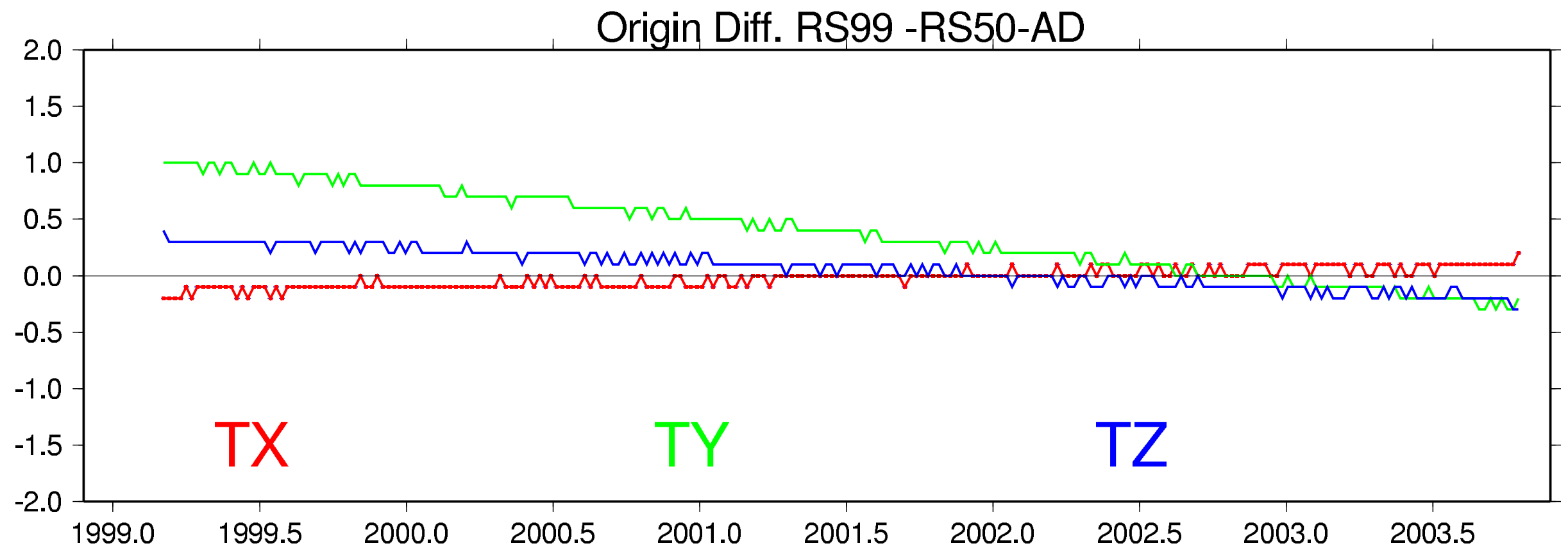
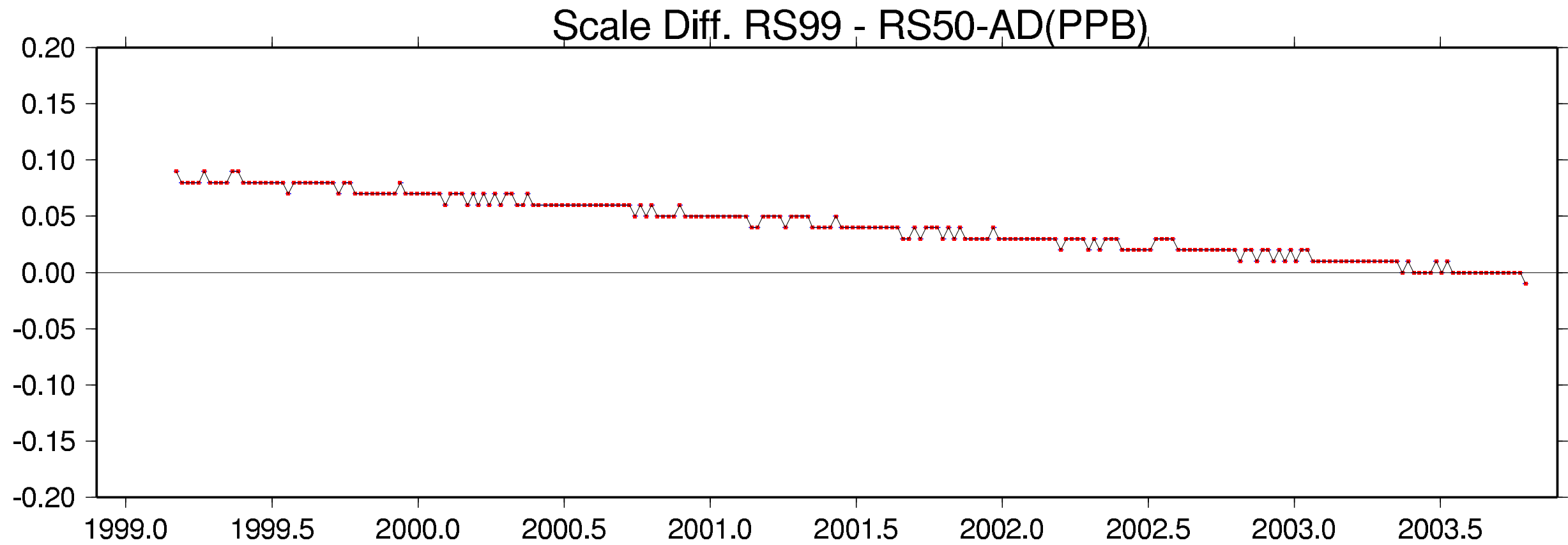
Scale & origin differences wrt RS99



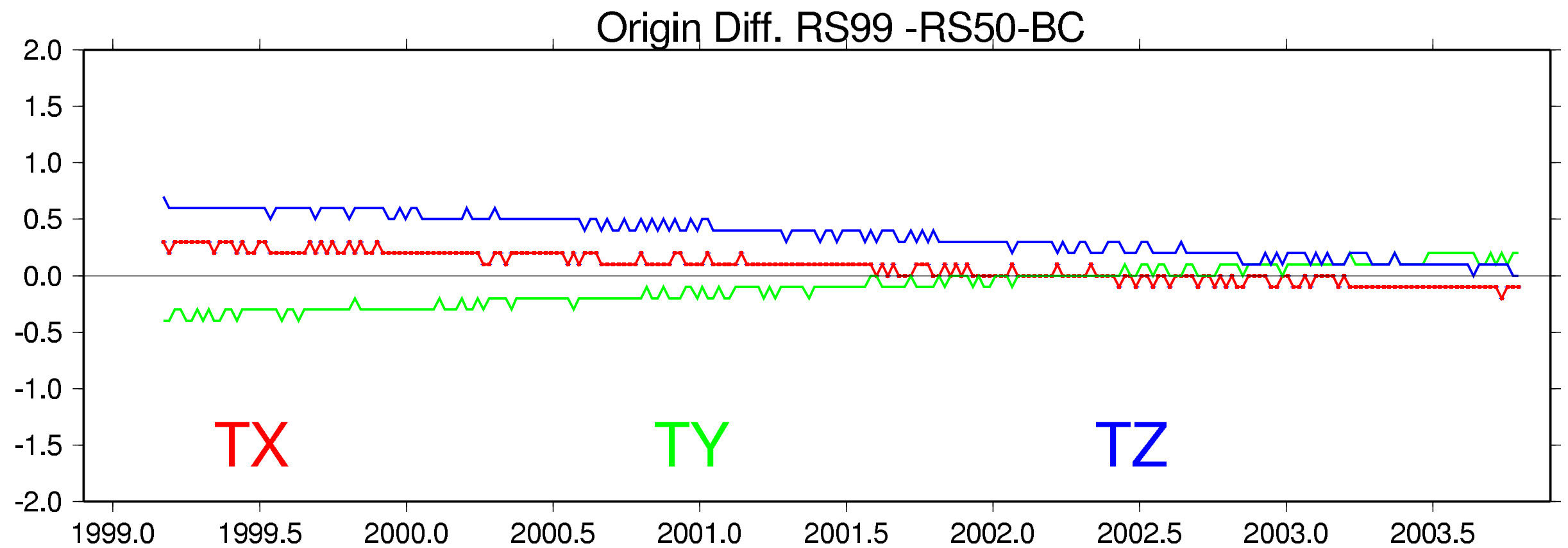
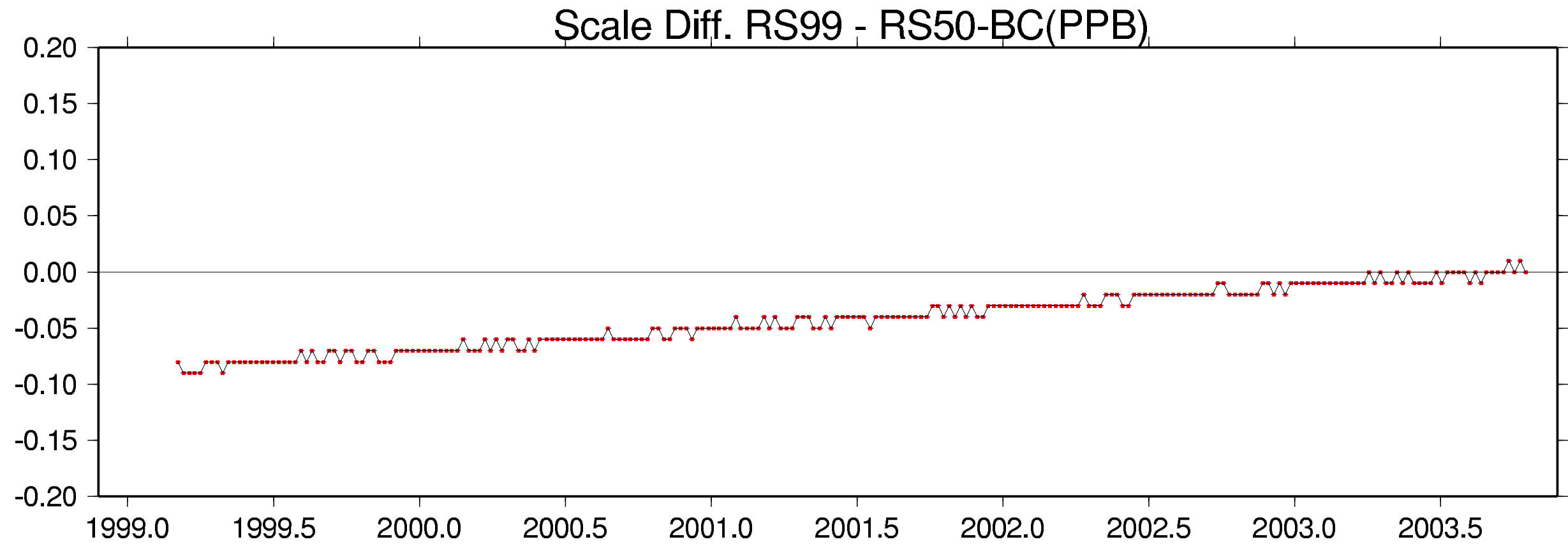
Scale & origin differences wrt RS99



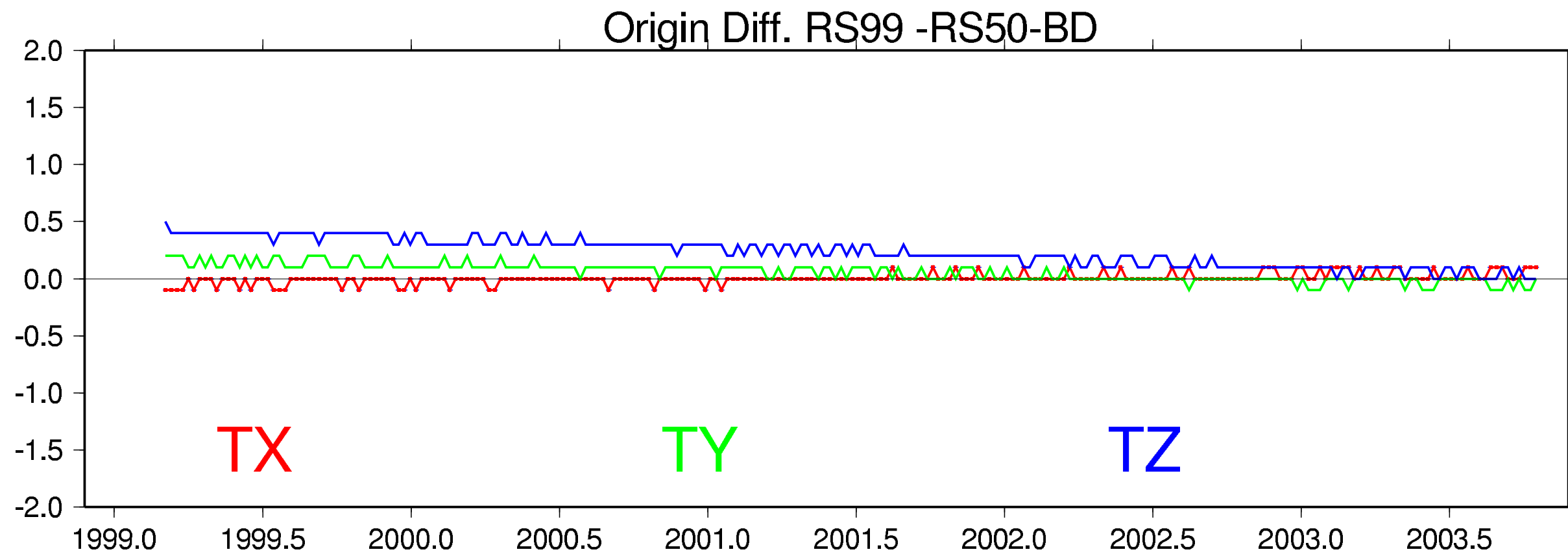
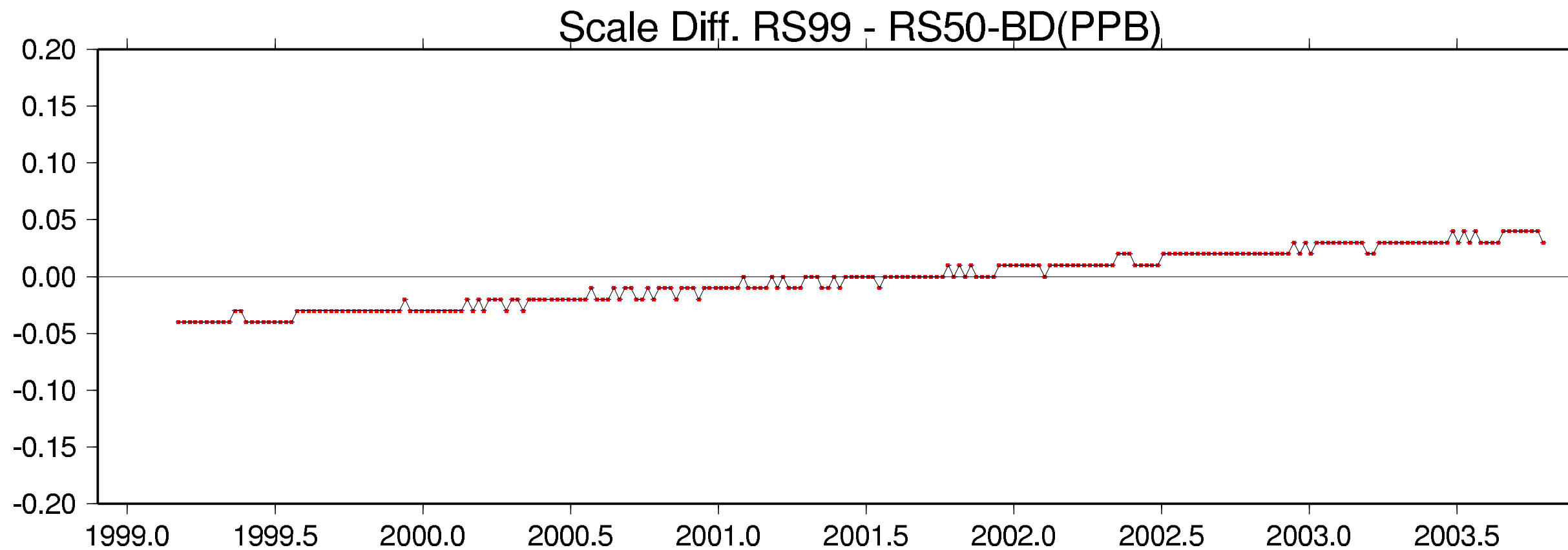
Scale & origin differences wrt RS99



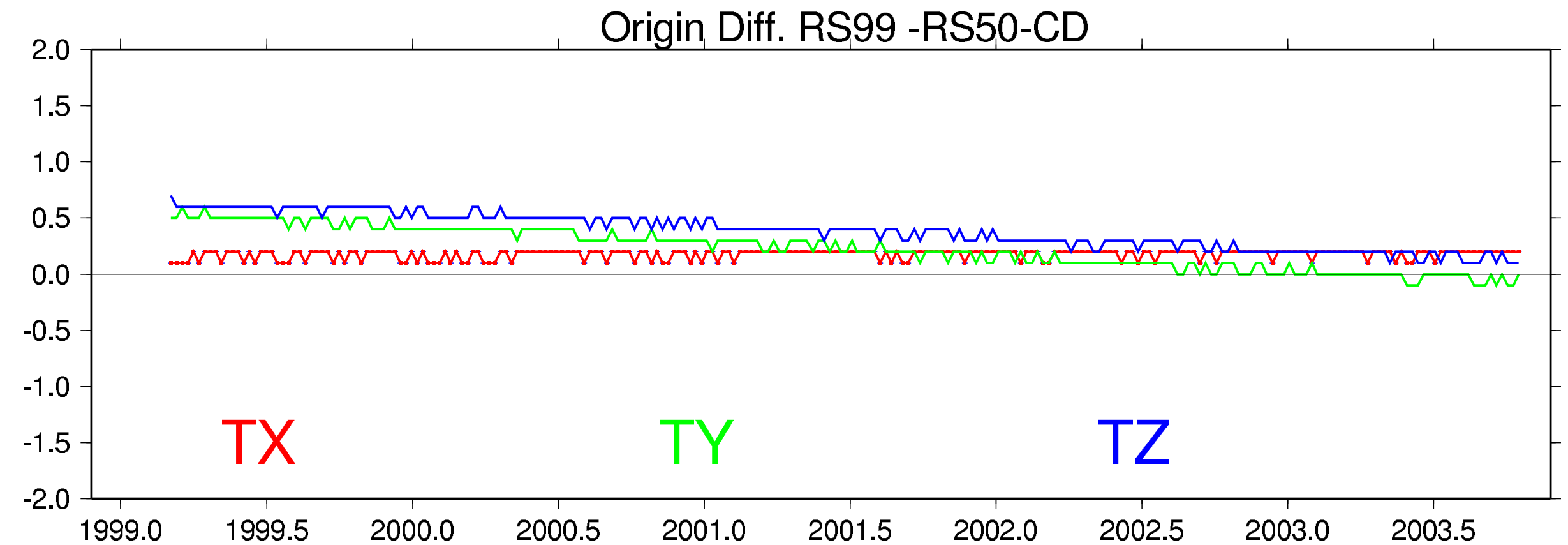
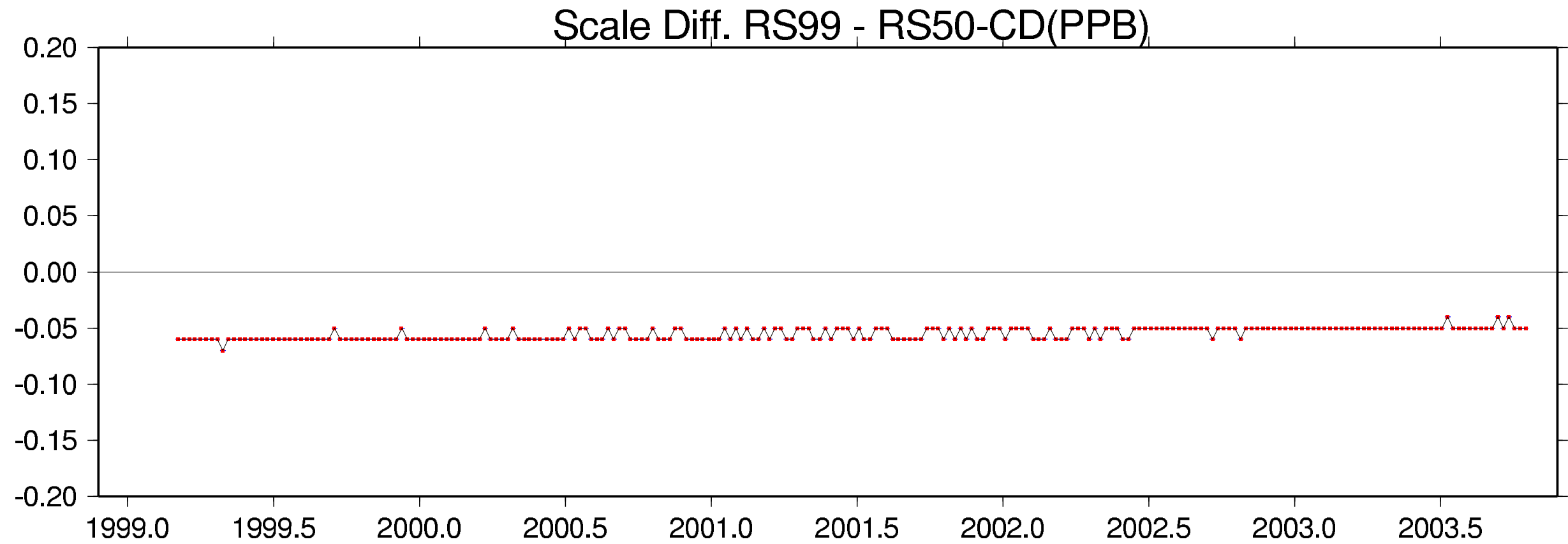
Scale & origin differences wrt RS99



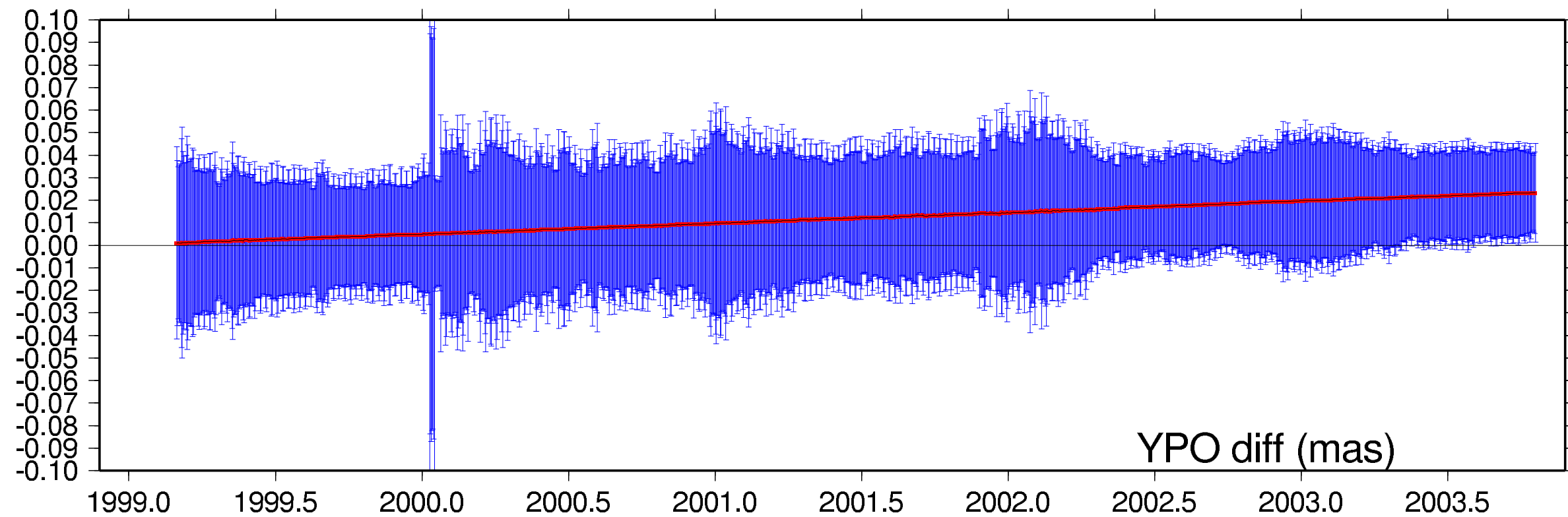
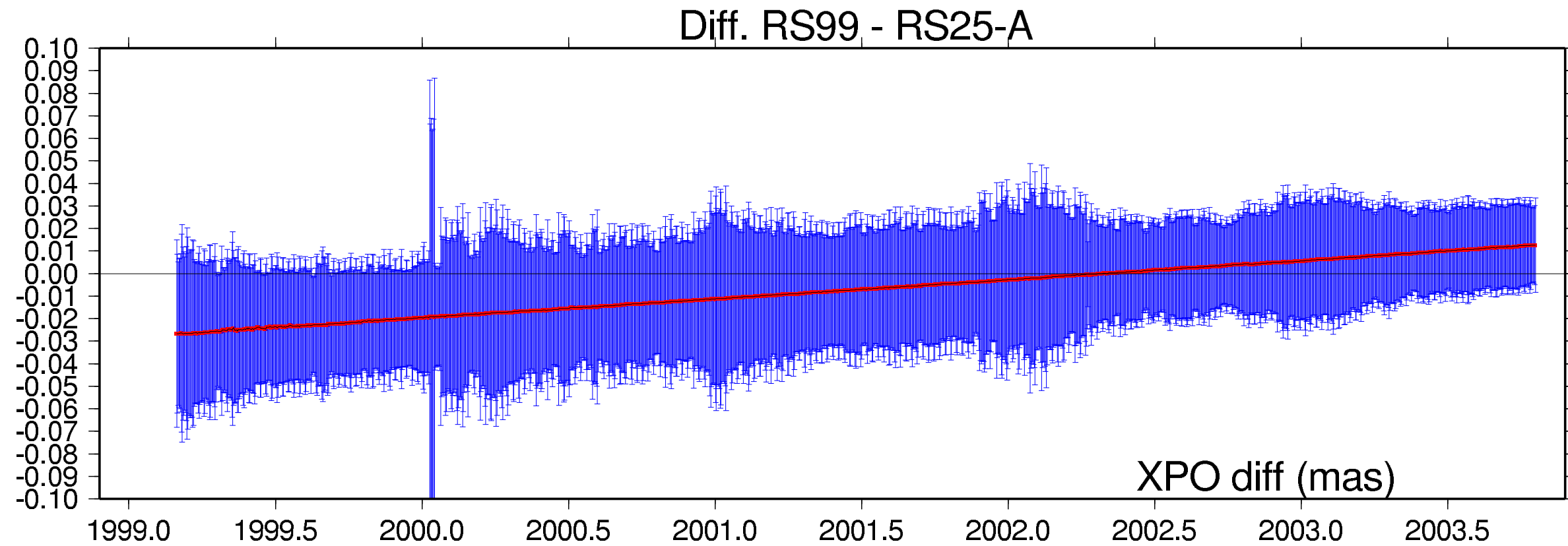
Scale & origin differences wrt RS99



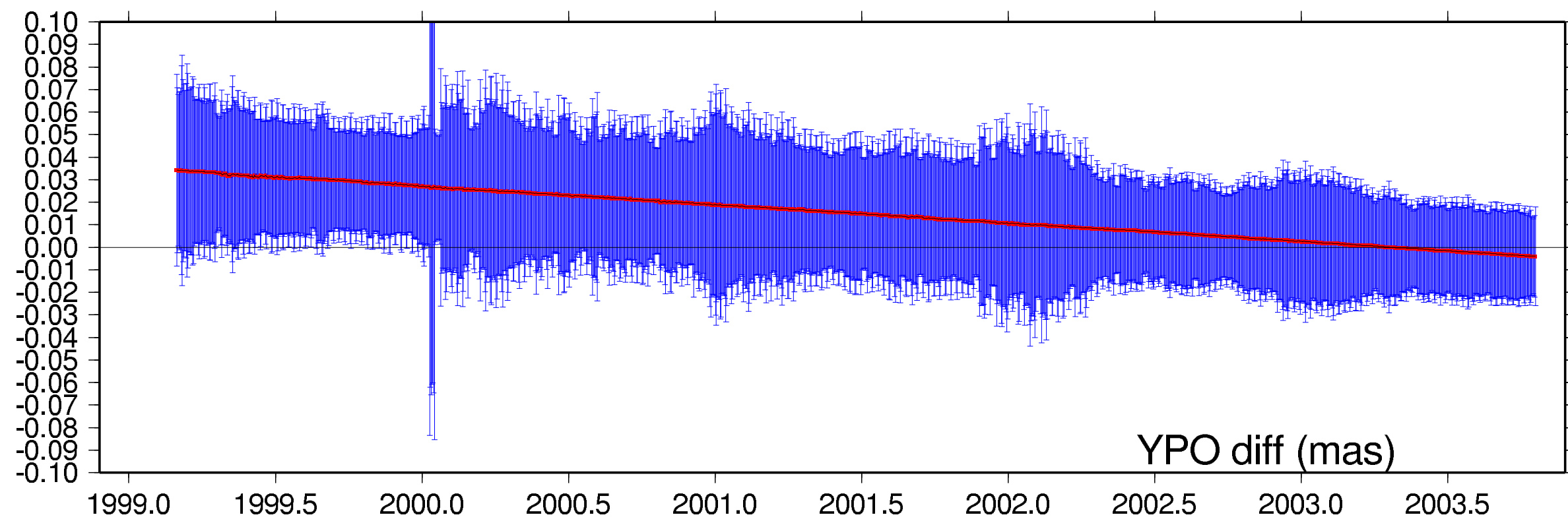
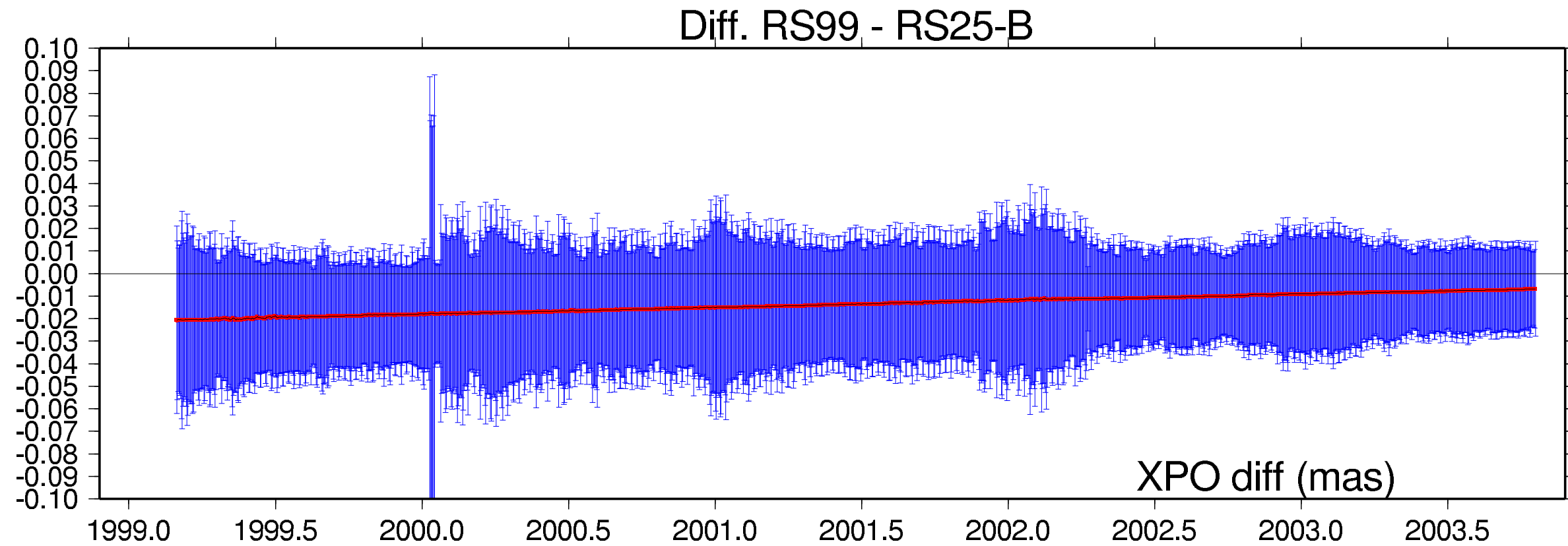
Scale & origin differences wrt RS99



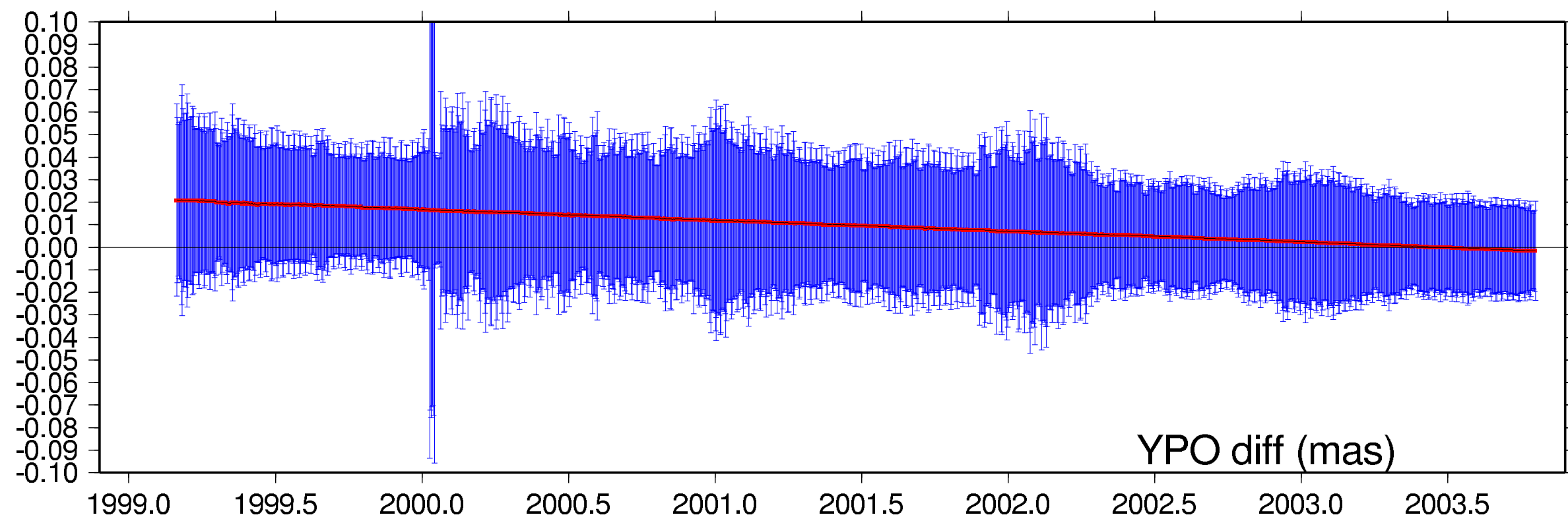
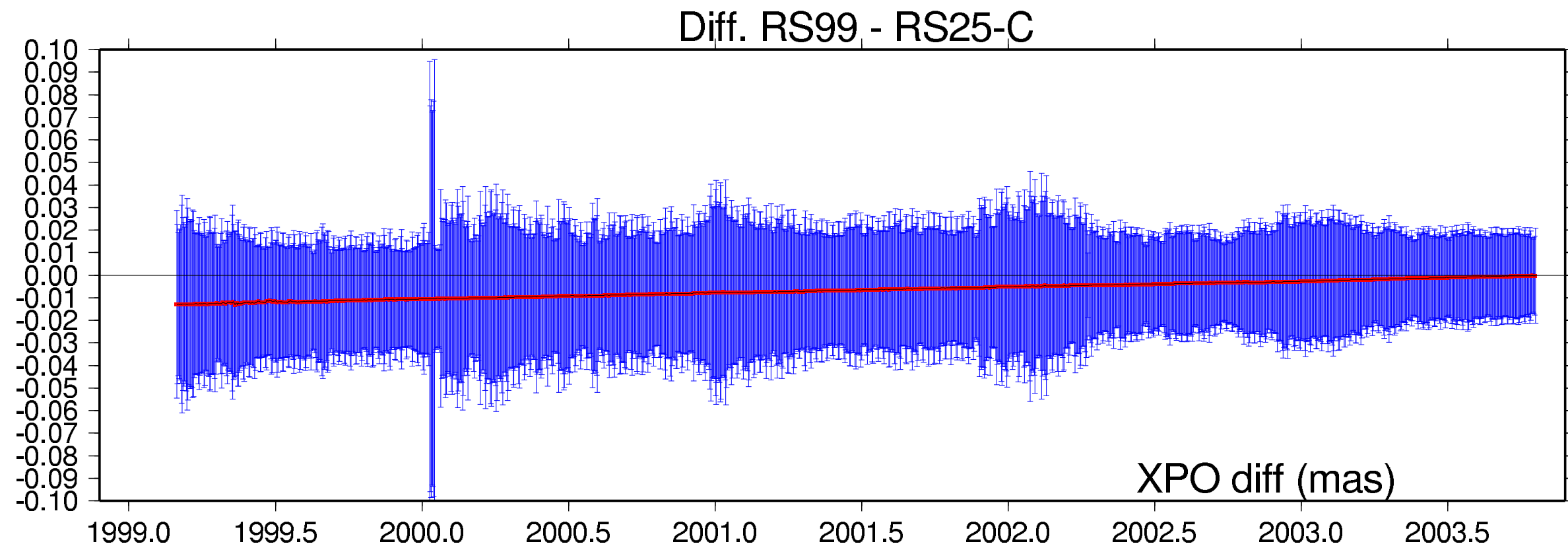
Polar Motion Differences wrt RS 99



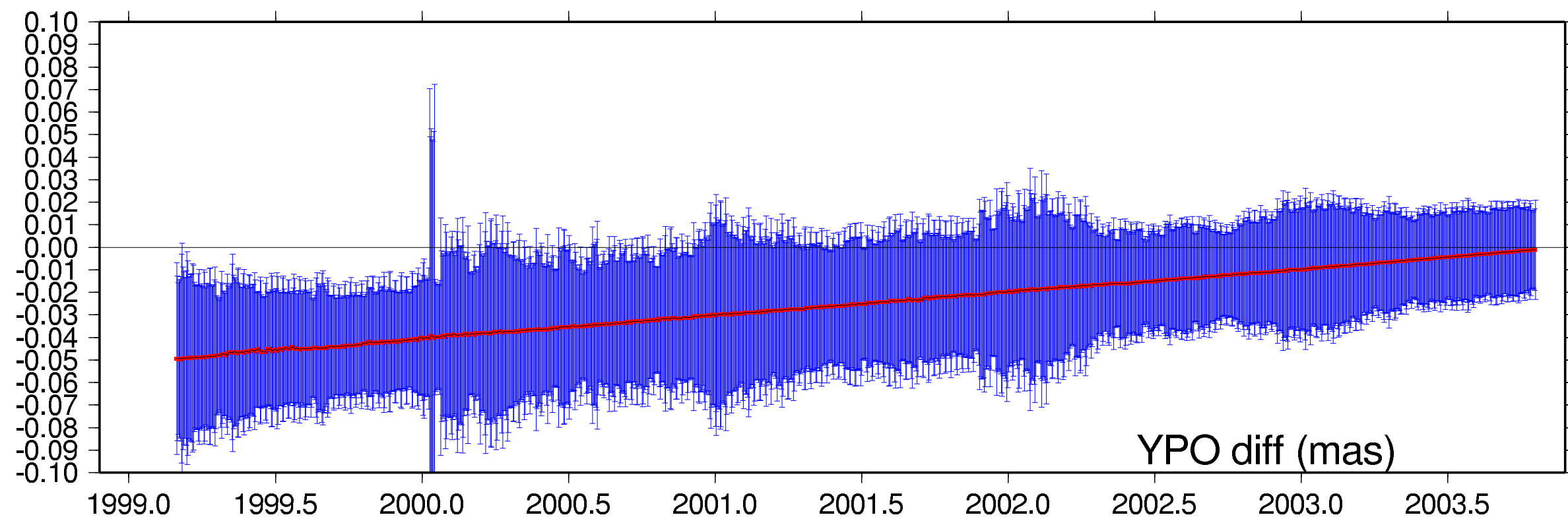
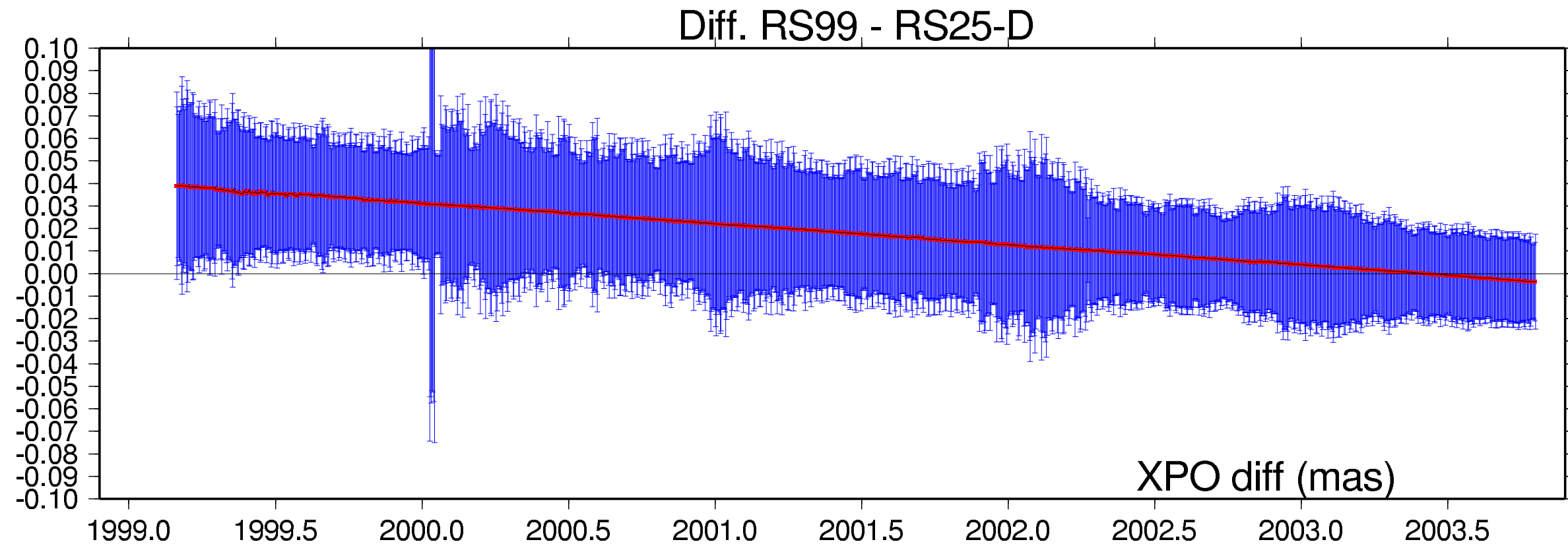
Polar Motion Differences wrt RS 99



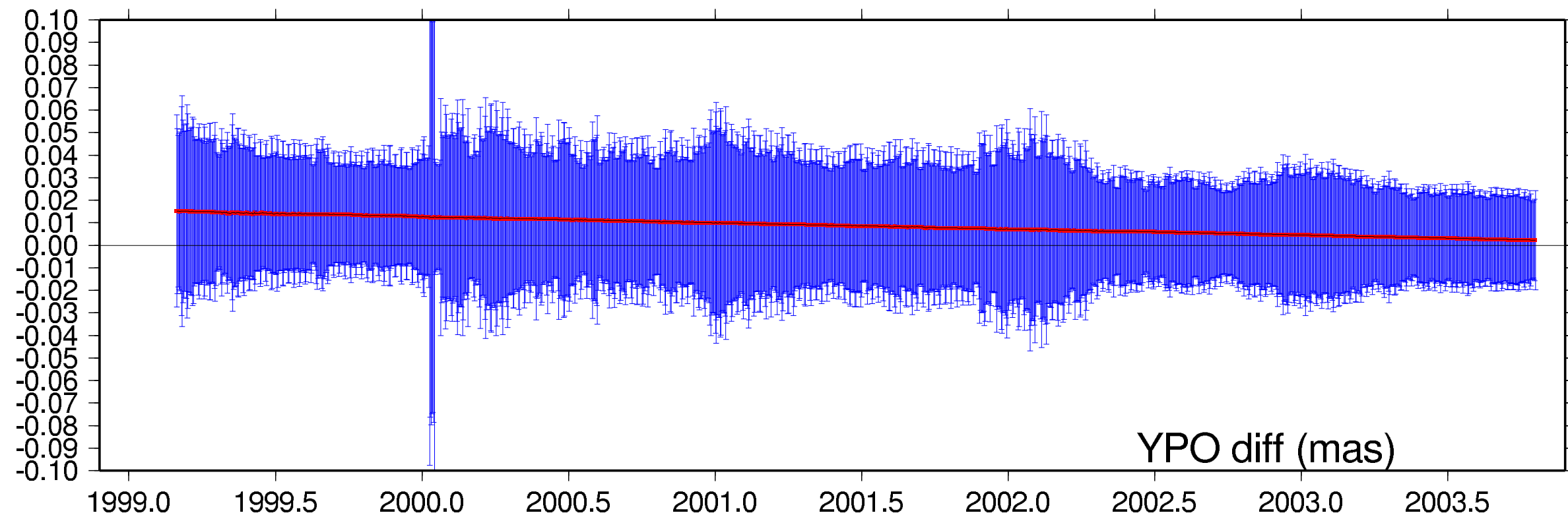
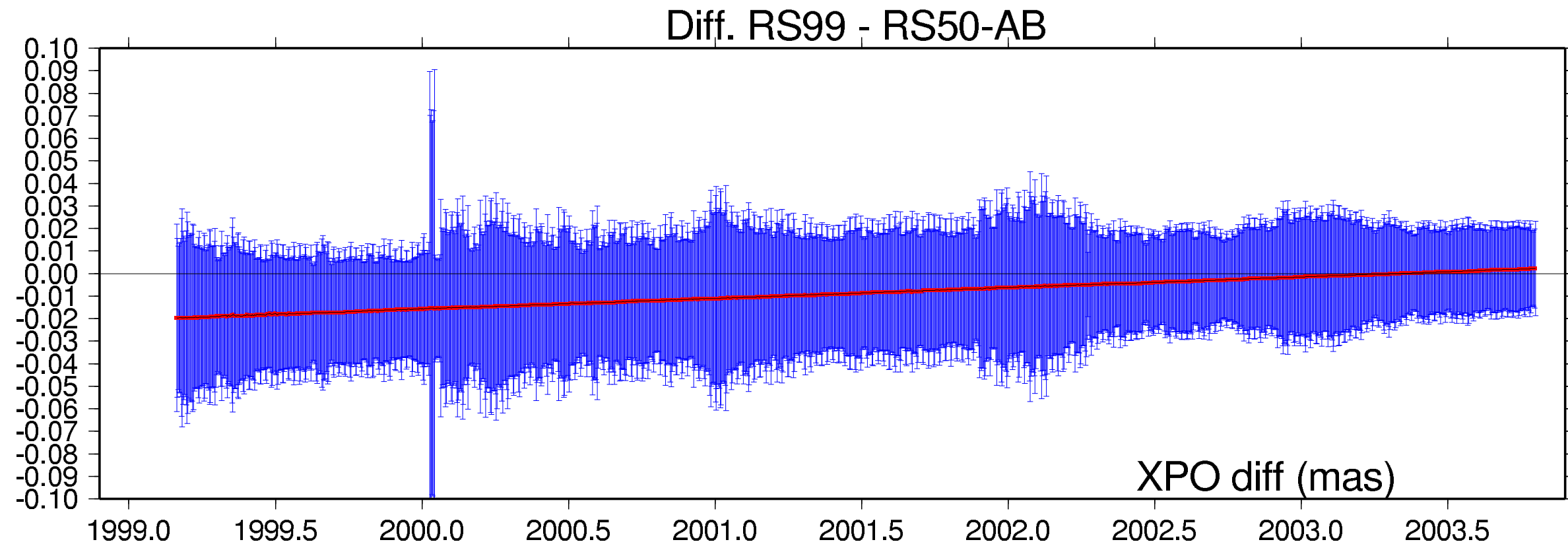
Polar Motion Differences wrt RS 99



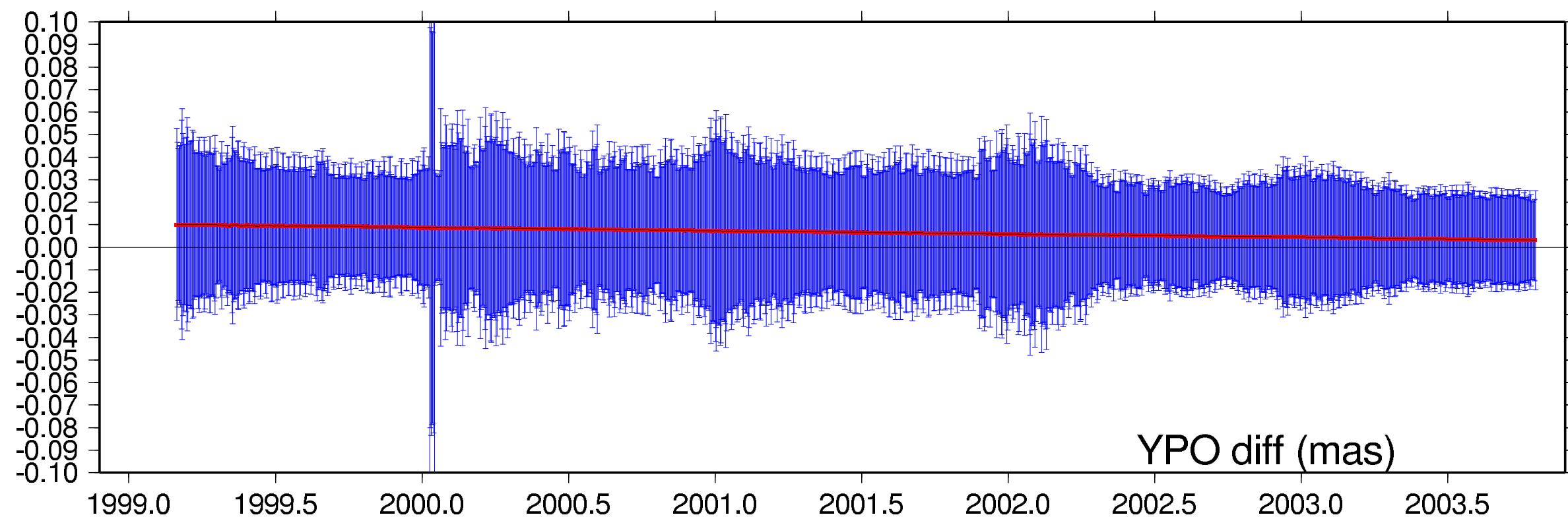
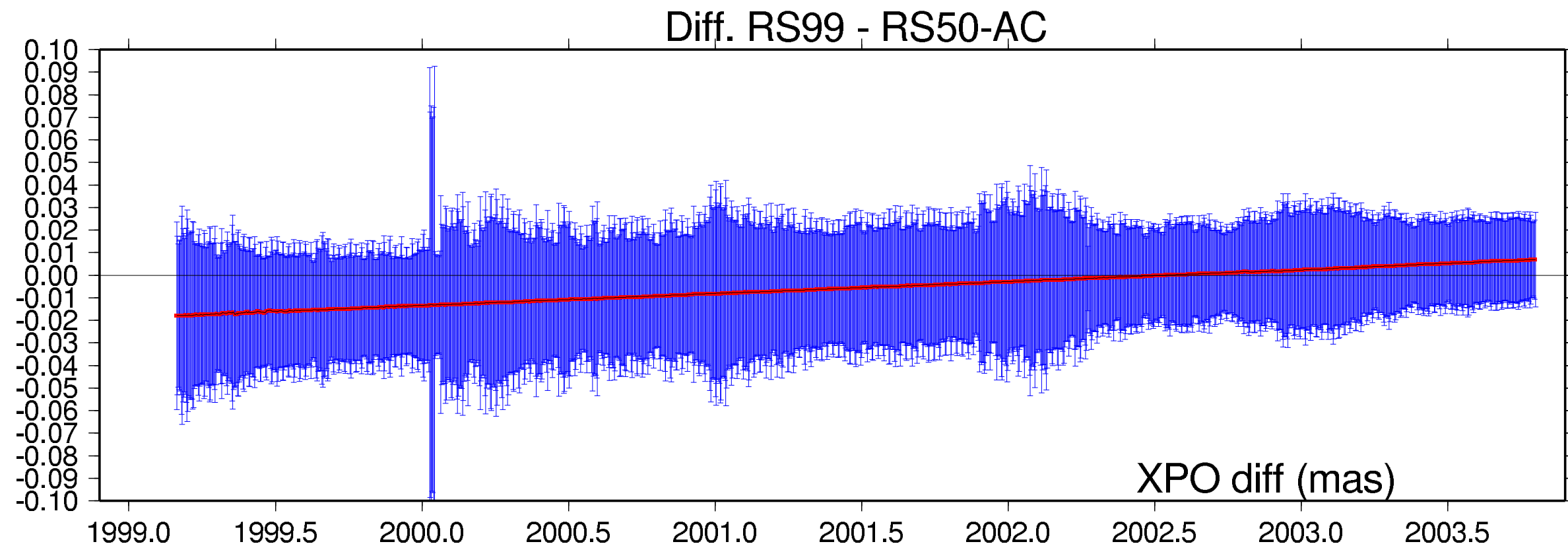
Polar Motion Differences wrt RS 99



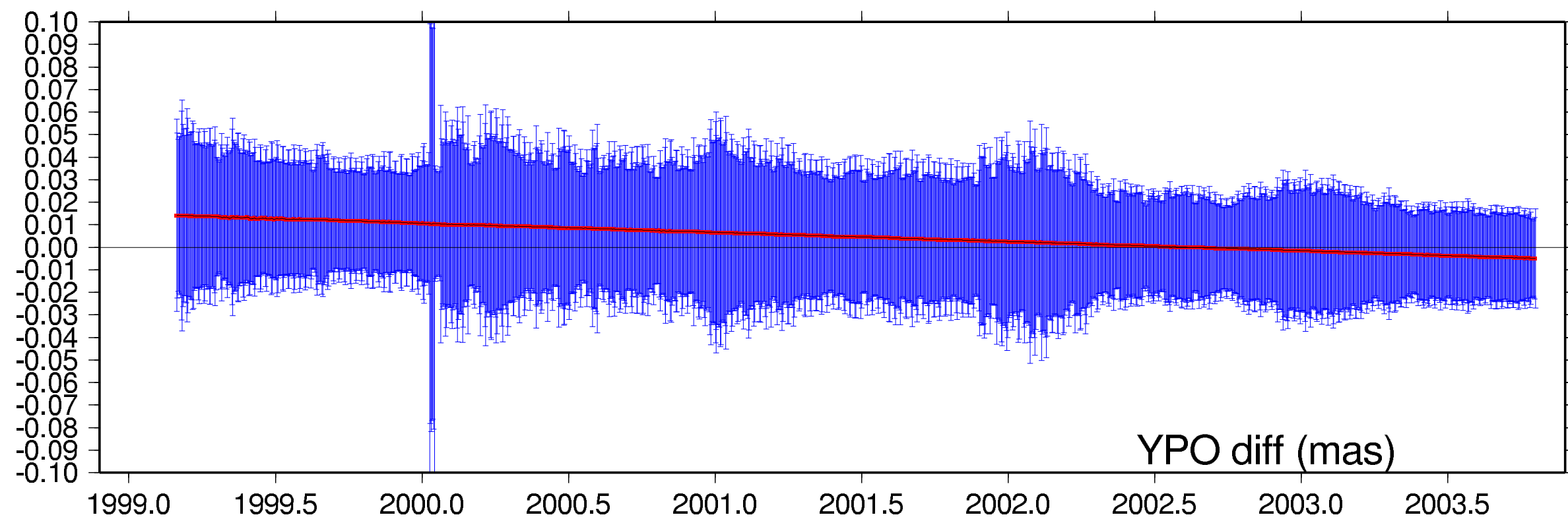
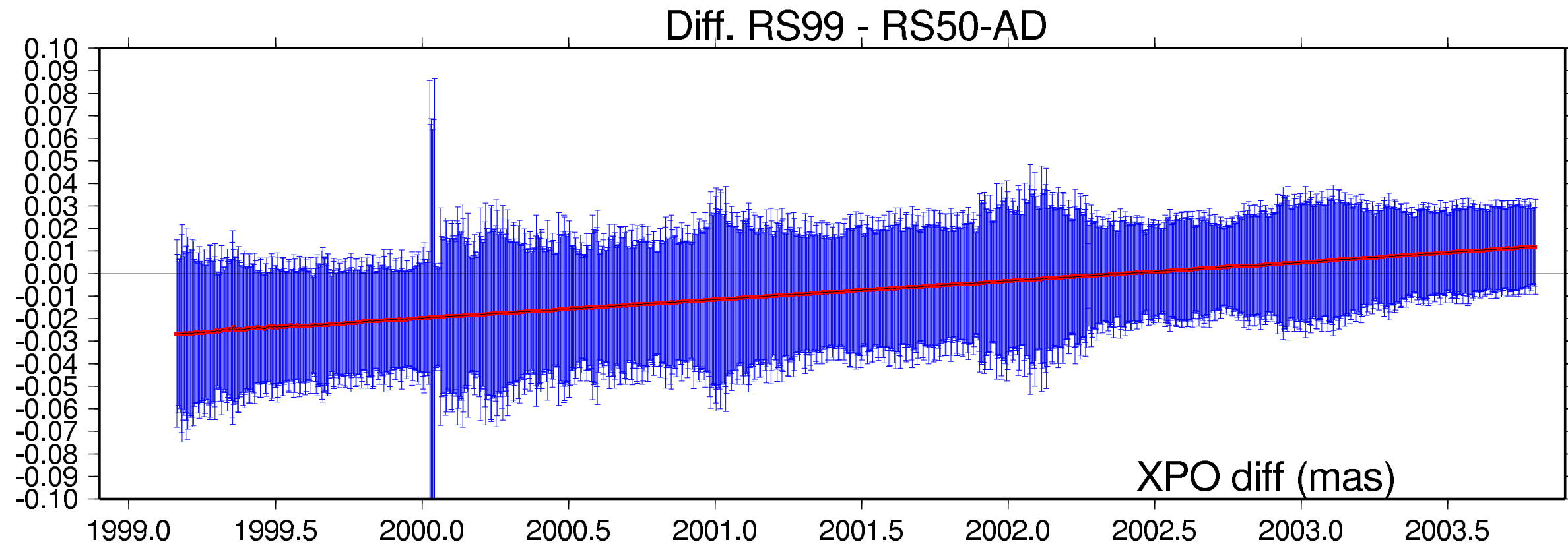
Polar Motion Differences wrt RS 99



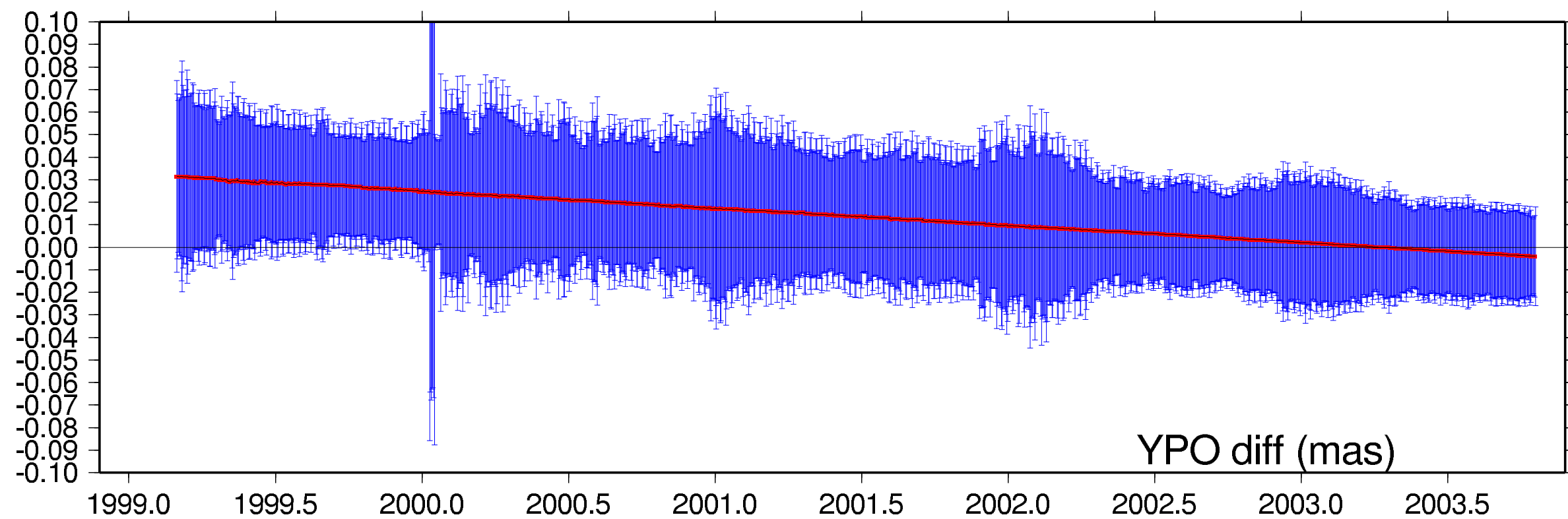
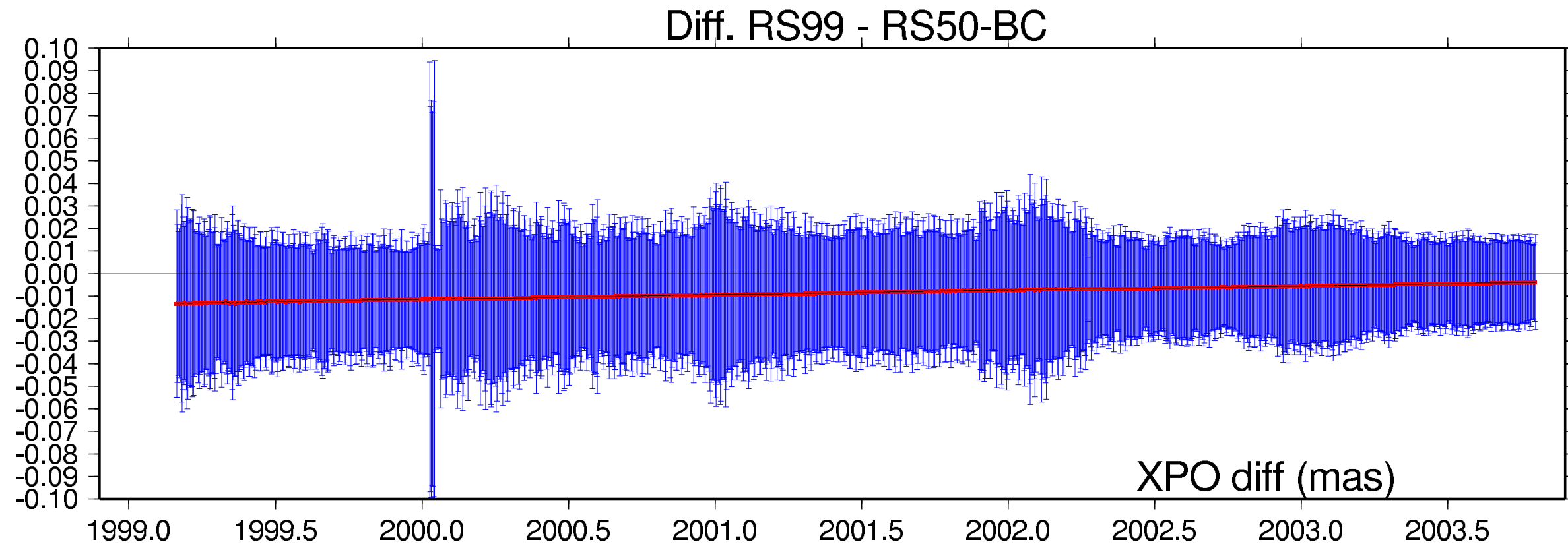
Polar Motion Differences wrt RS 99



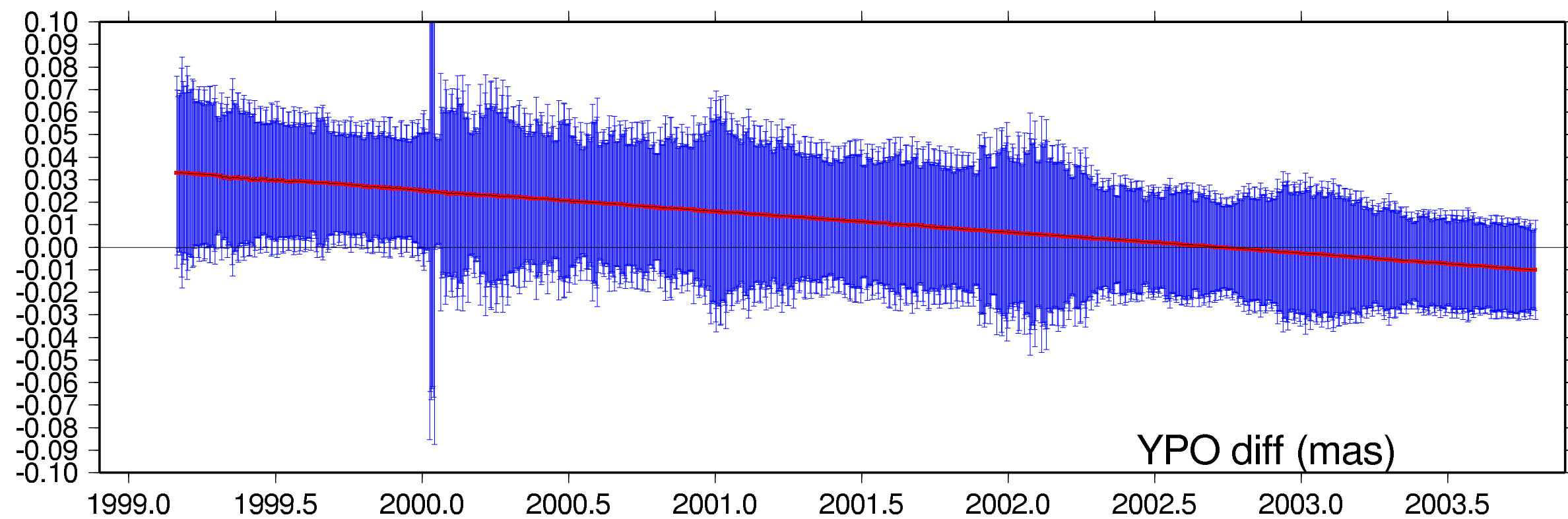
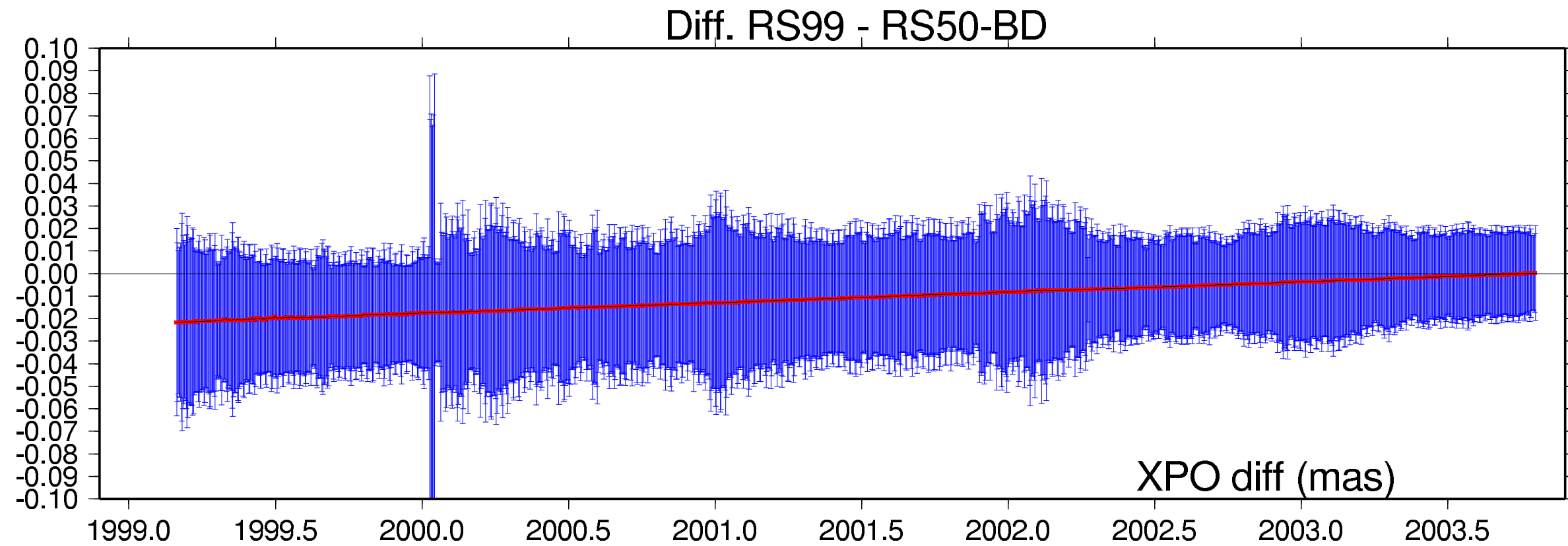
Polar Motion Differences wrt RS 99



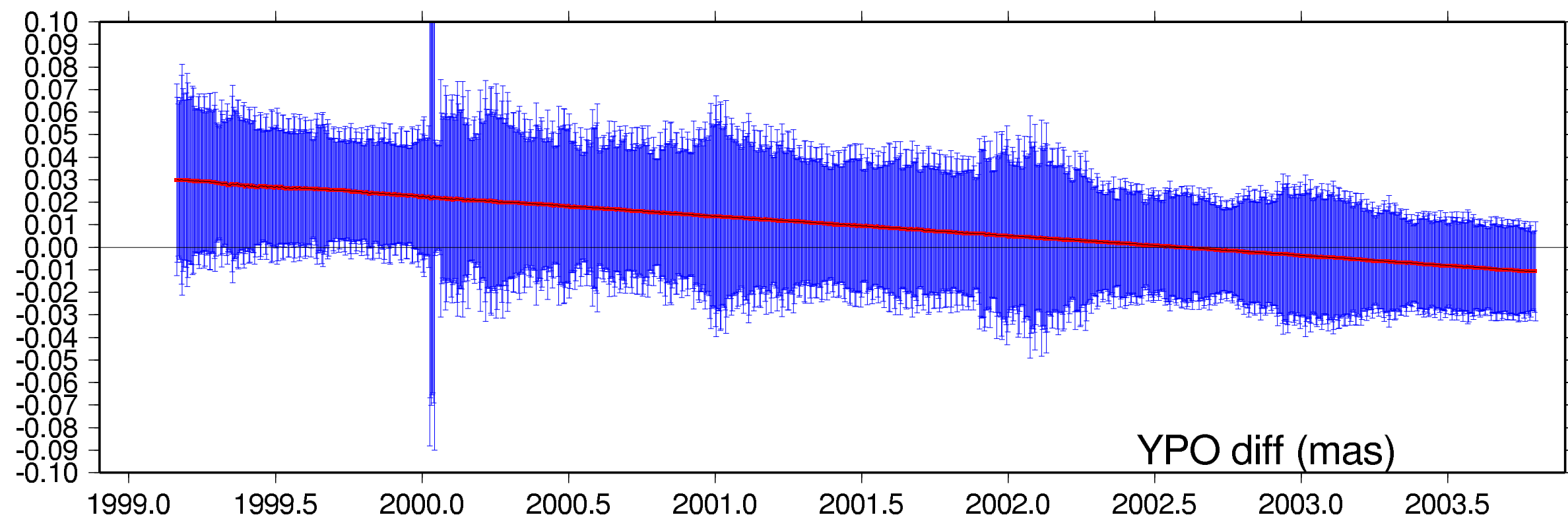
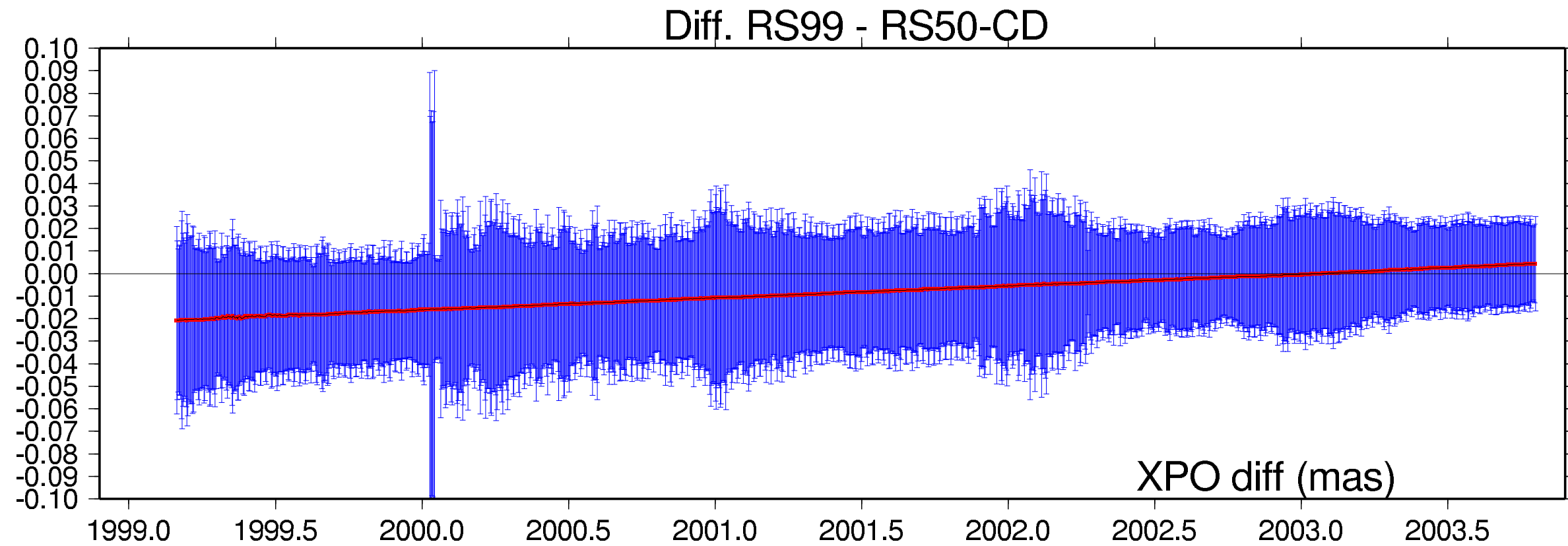
Polar Motion Differences wrt RS 99



Polar Motion Differences wrt RS 99

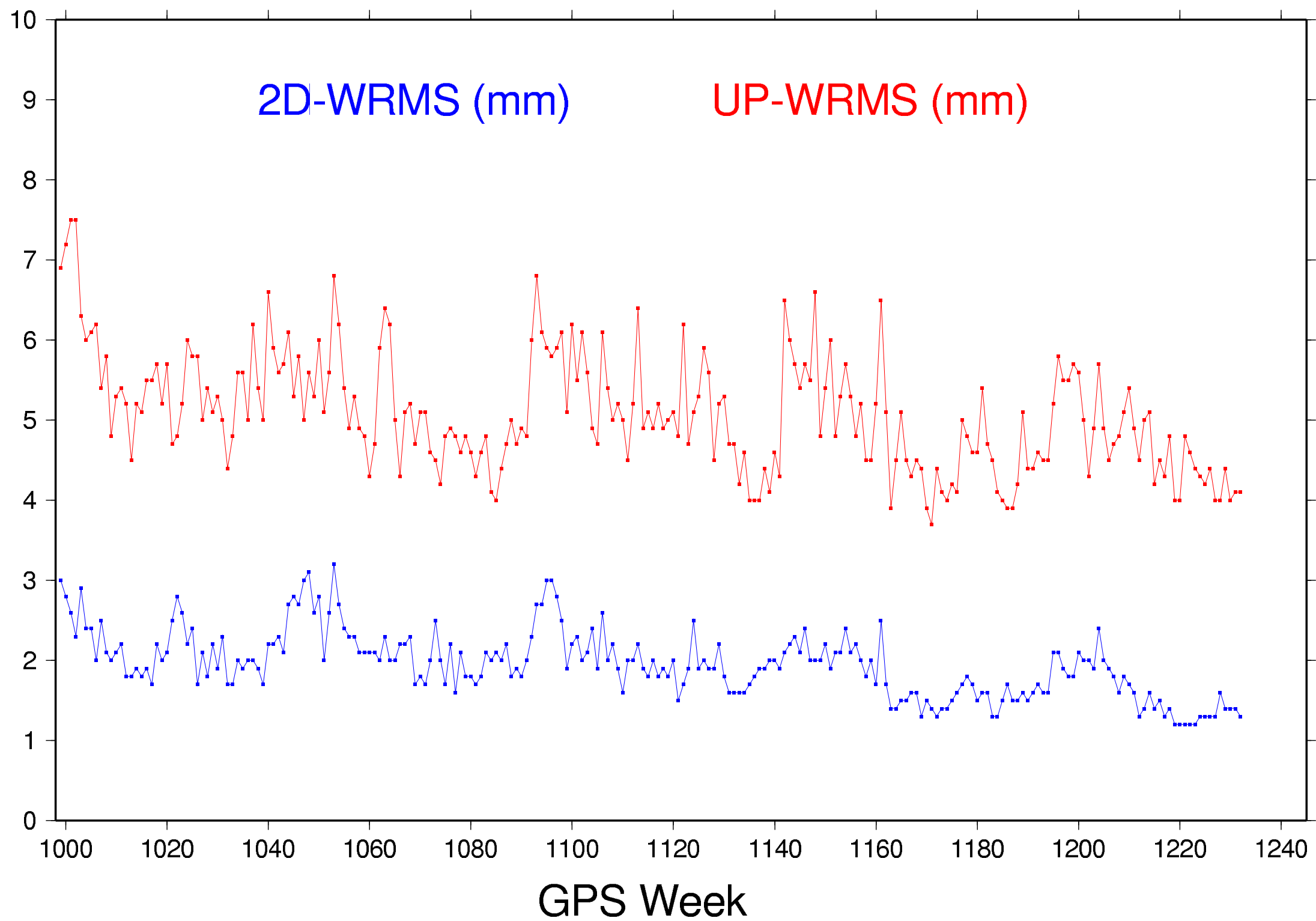


Polar Motion Differences wrt RS 99



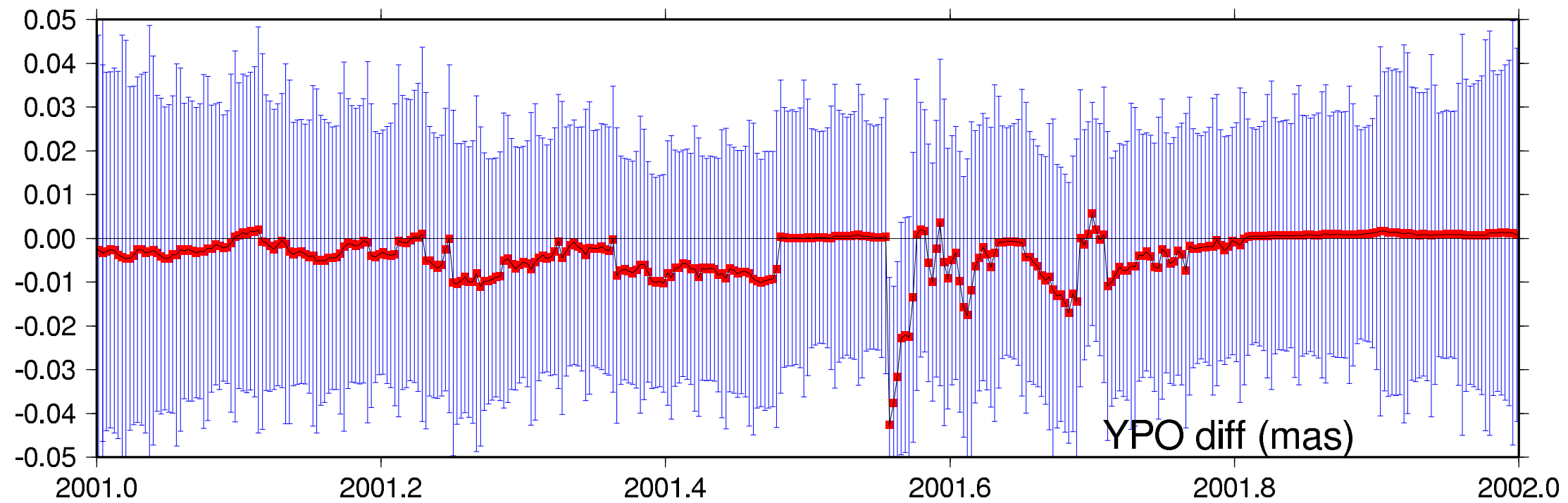
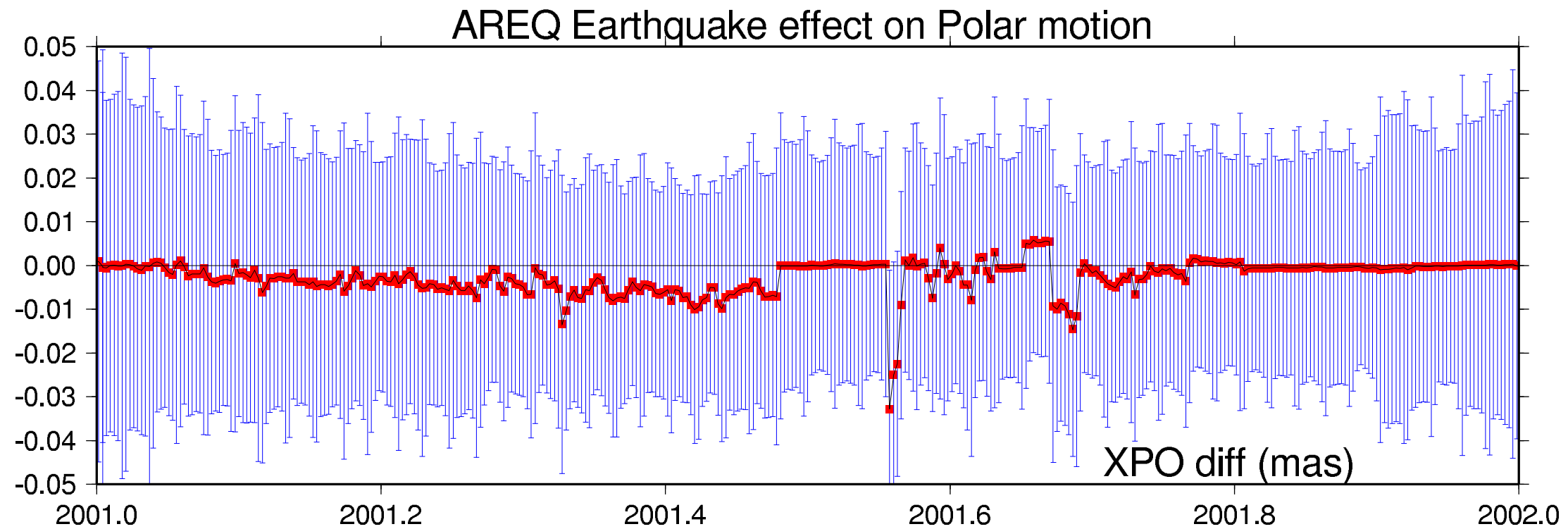
Weekly WRMS

IGS Weekly WRMS



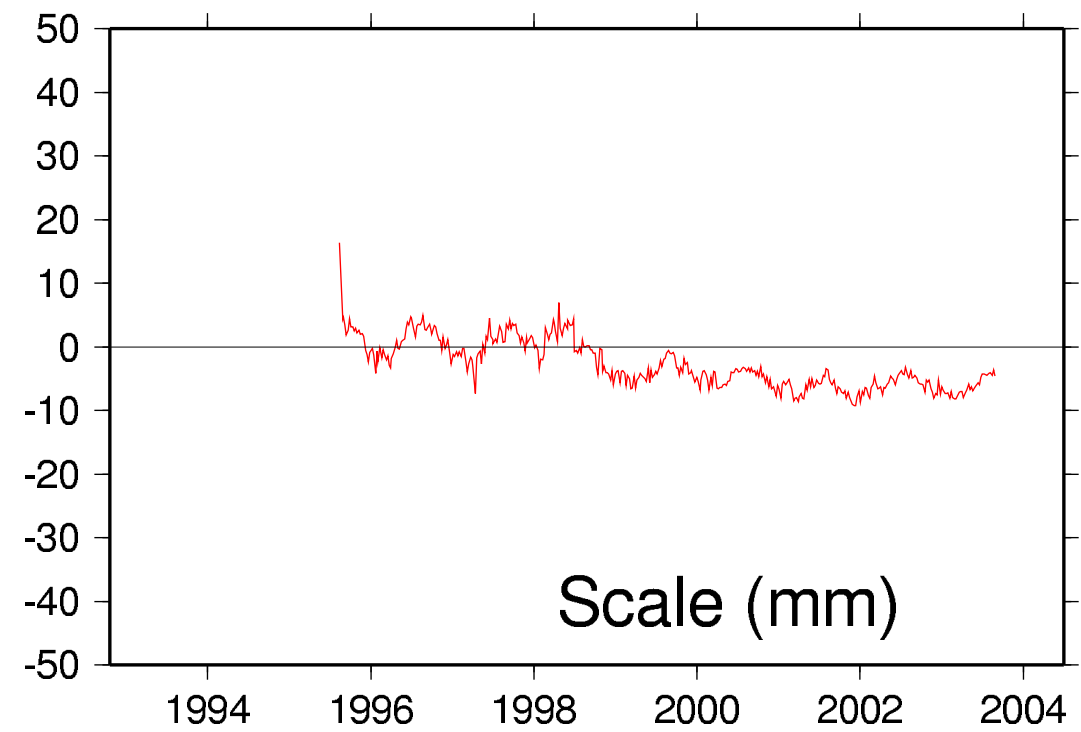
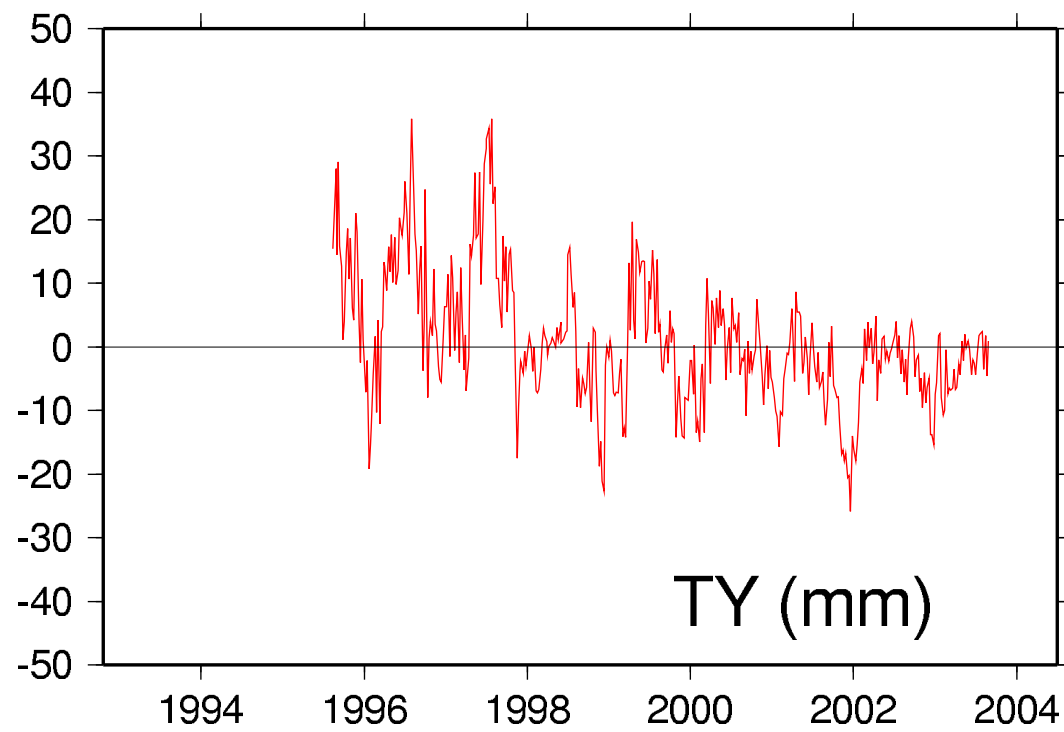
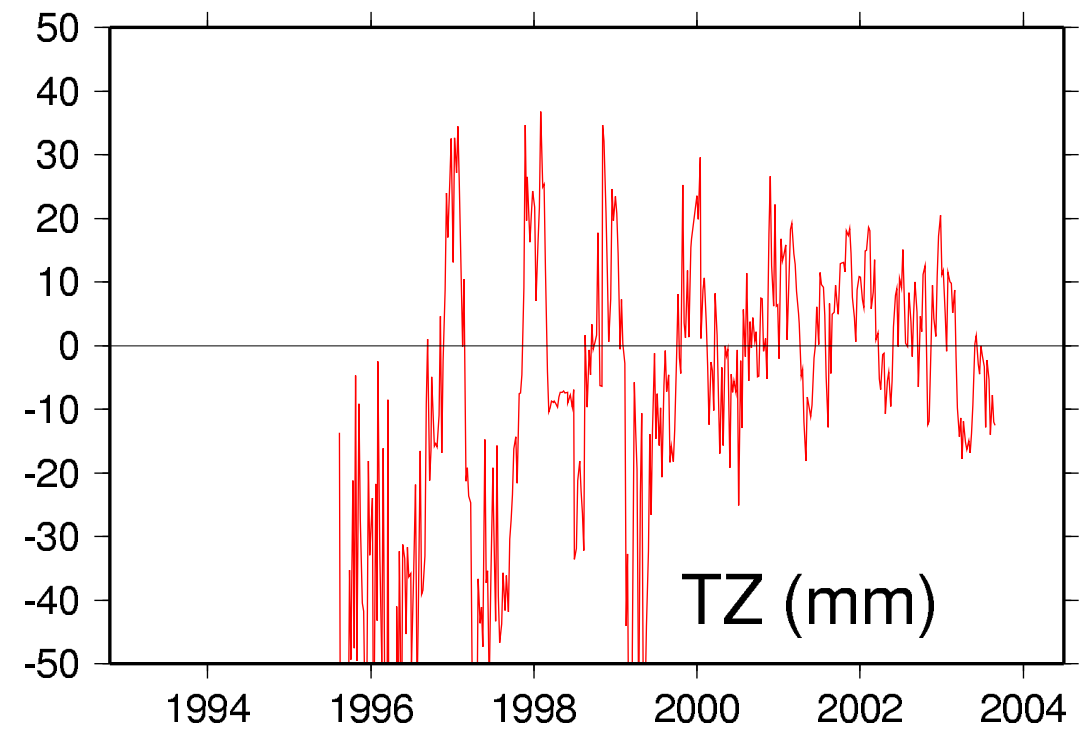
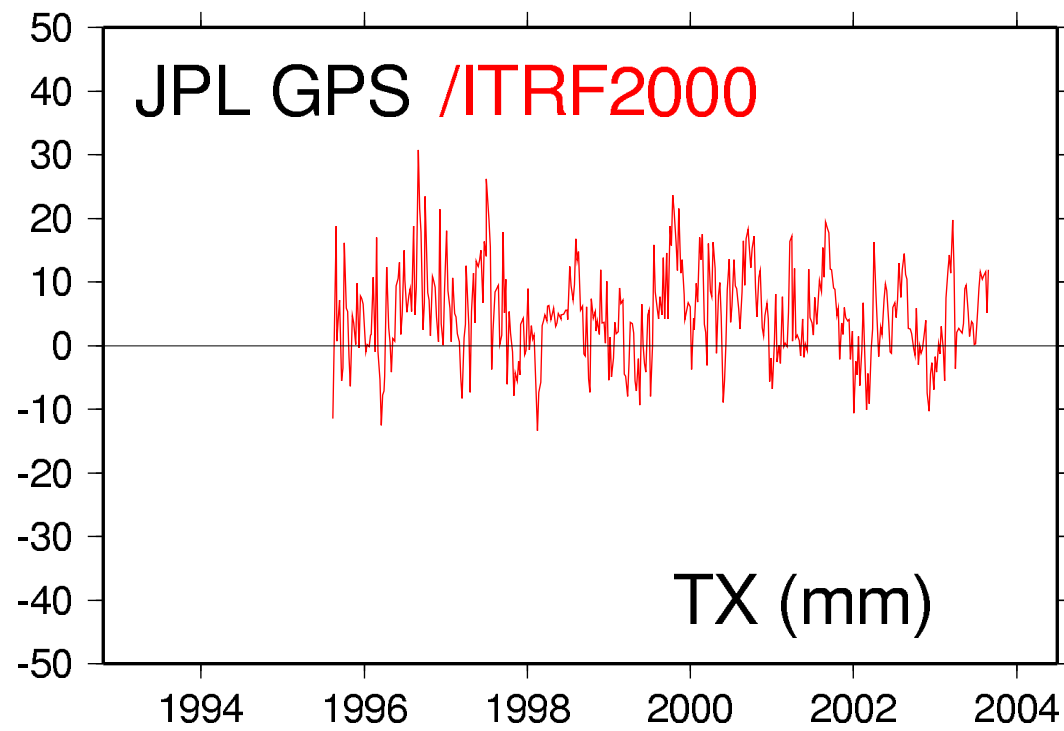
Impact of AREQ Earthquake on Polar Motion

If pre & post station velocity is constrained to be the same



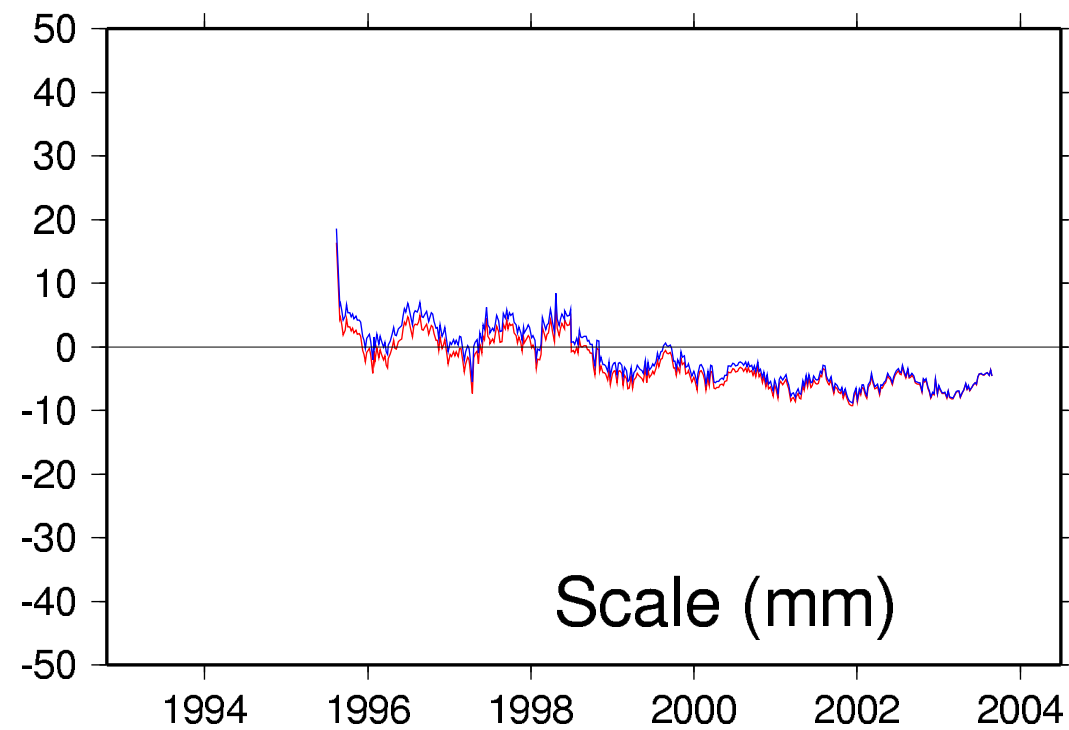
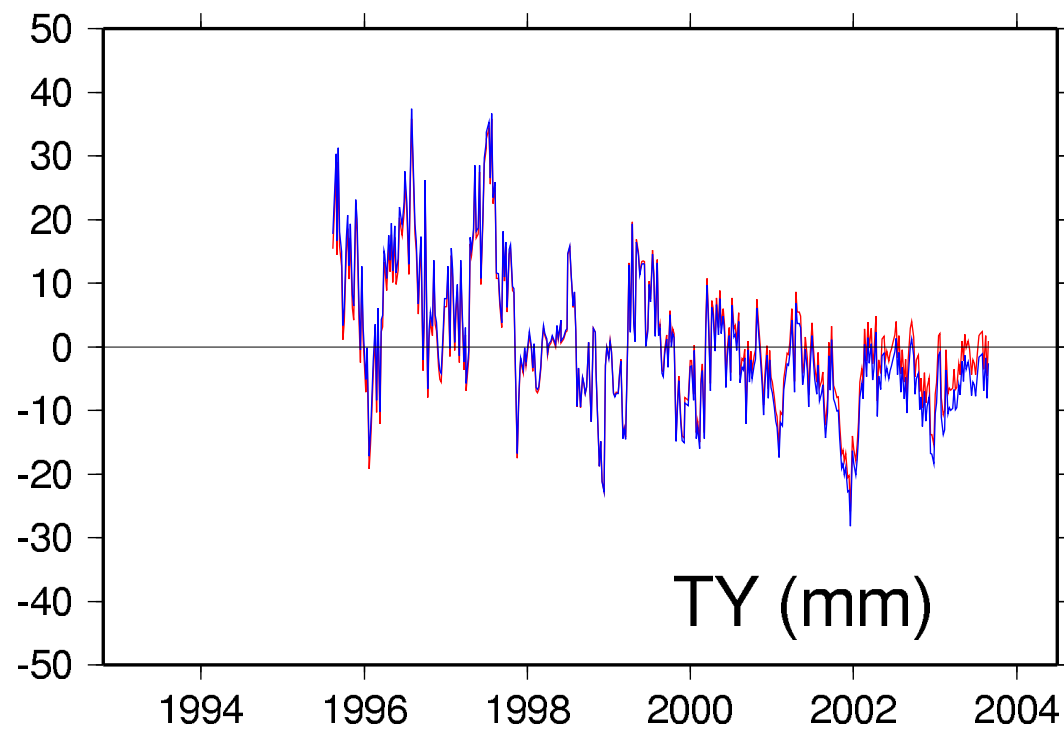
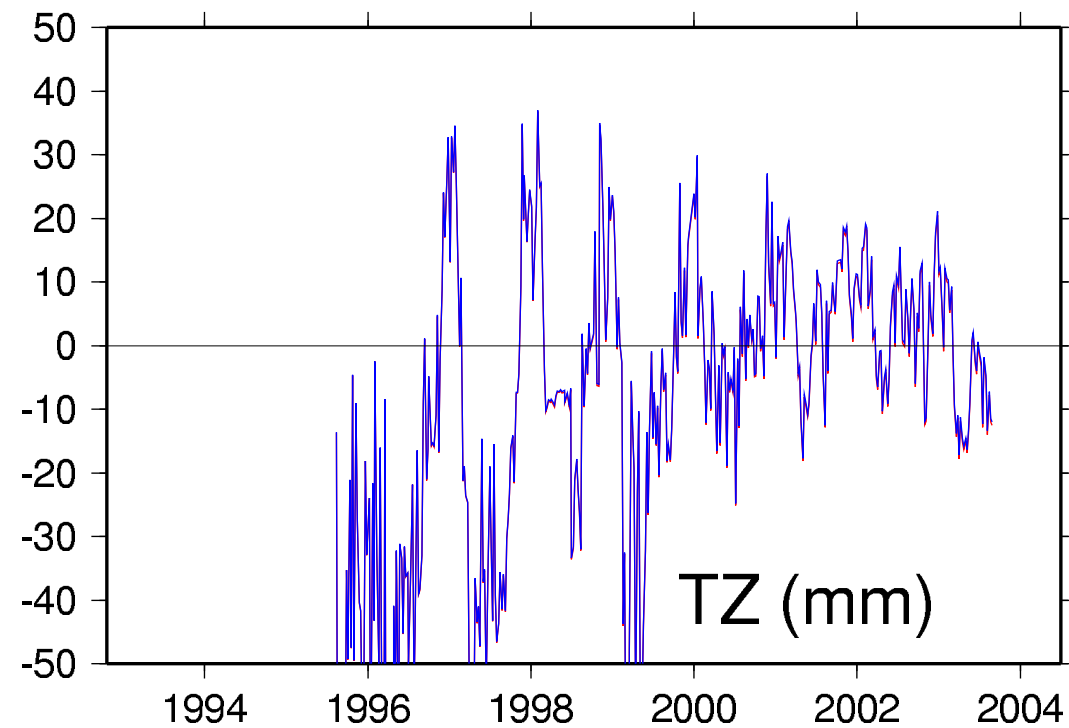
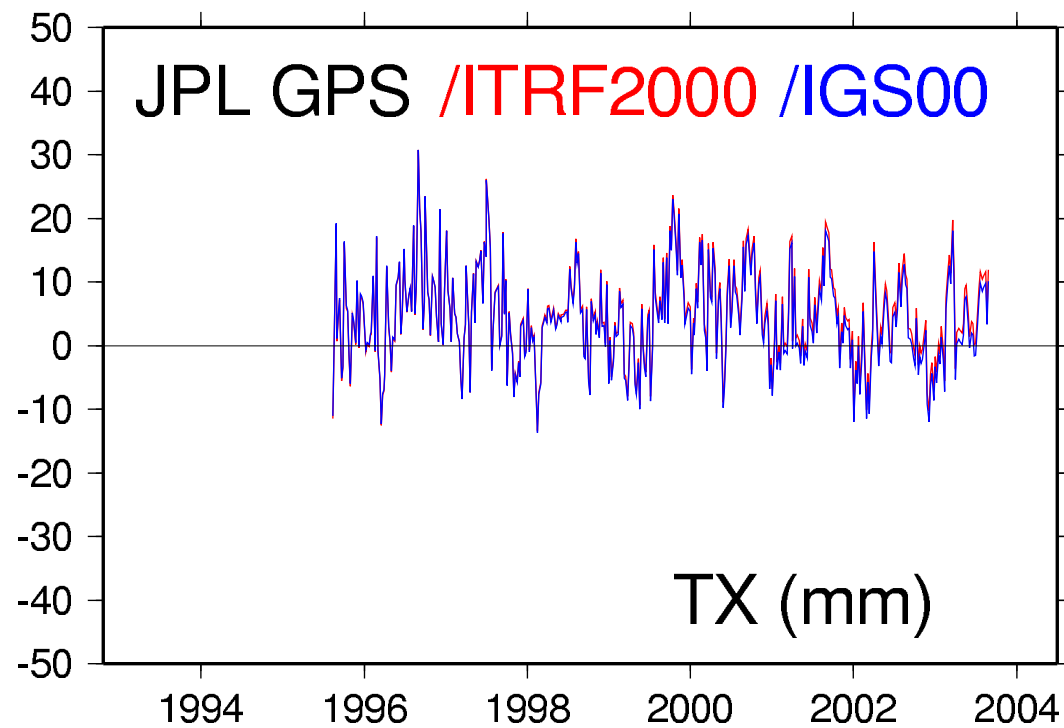
What about GPS Geocenter and TRF Scale ???

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ITRF2000 datum using 21 stations

What about GPS Geocenter and TRF Scale ???



ITRF2000 datum using 21 stations

IGS00 datum using 21 stations

Conclusions

- **Changing the RS set may produce changes up to:**
 - **0.5 mm/yr in origin and scale rates**
 - **10 μ as/yr in Polar Motion**
- **The overall IGS TRF stability is at the 1 mm level**
- **The Weekly WRMS are:**
 - **2 mm in horizontal**
 - **5 mm in vertical**
- **Discontinuities should be handled with care (impact on EOP)**
- **GPS Geocenter and Scale estimates is still an open question**

On TIGA TRF Application (See Poster by Wöppelmann et al.)