

Institute of Geodesy and Photogrammetry

## GNSS Earth System Monitoring: Present Examples and New Developments

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ETH Zurich, Institute of Geodesy and Photogrammetry Double Jubilee, AIUB/Uraniae, 25.11.2022





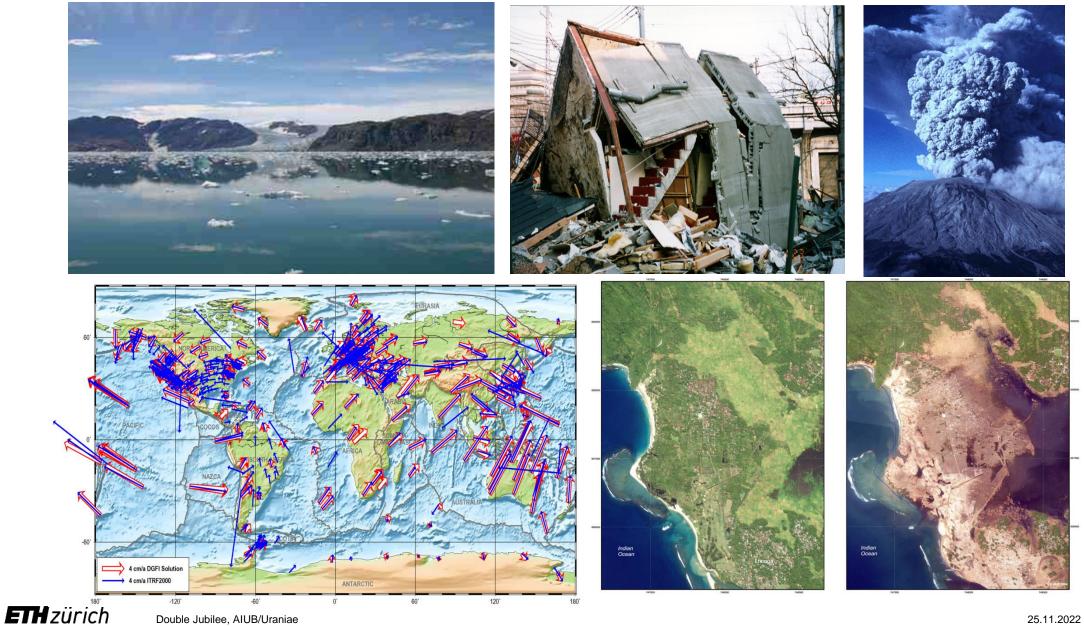
#### **Overview**

- Motivation: Monitoring of the Earth's System
- A few Examples of GNSS Earth Monitoring
- Three Ways to Overcome Limitations:
  - Turn Nuisance into Signal
  - Make Use of Low-Cost and Miniaturization
  - New Technologies
- Conclusions

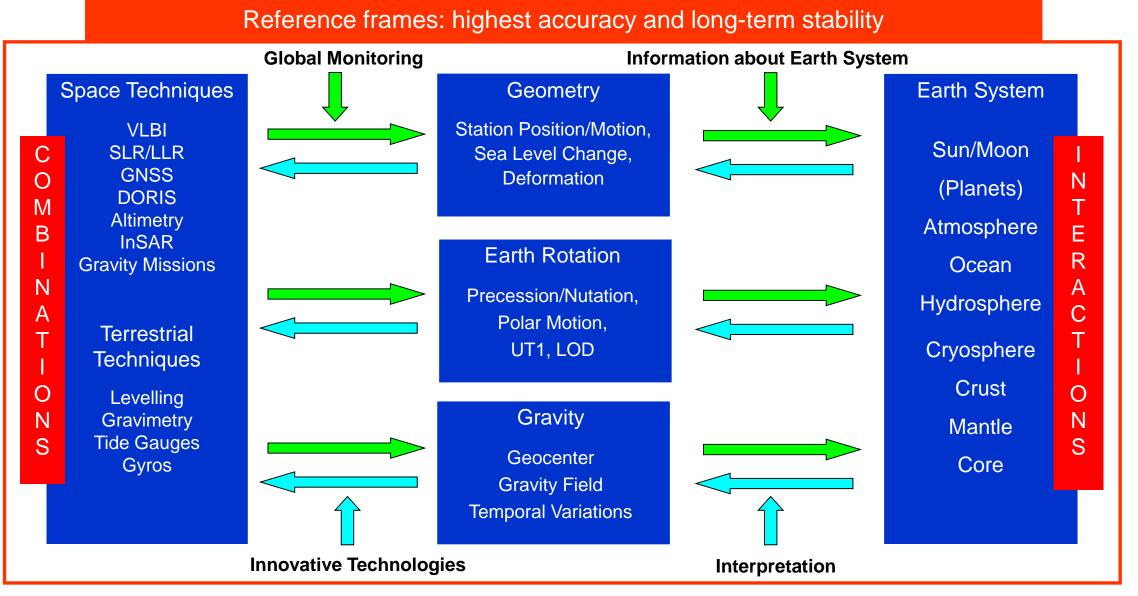
## **Motivation:**

**Monitoring the Earth's System** 

#### **Processes: Millions of Years** $\leftrightarrow$ **Fractions of Seconds**



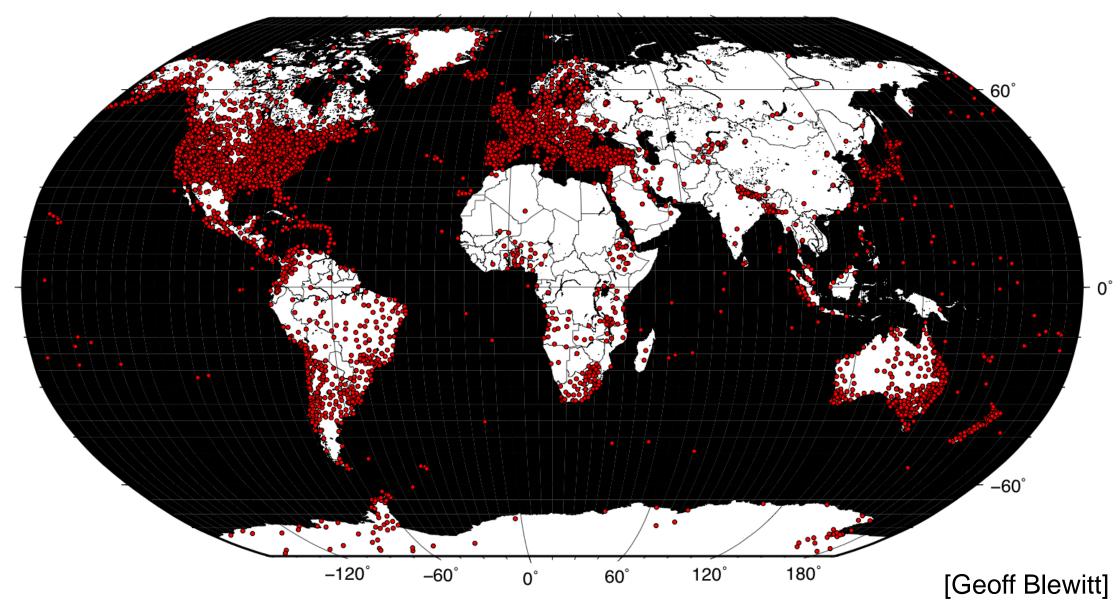
## **Monitoring and Modelling of System Earth**



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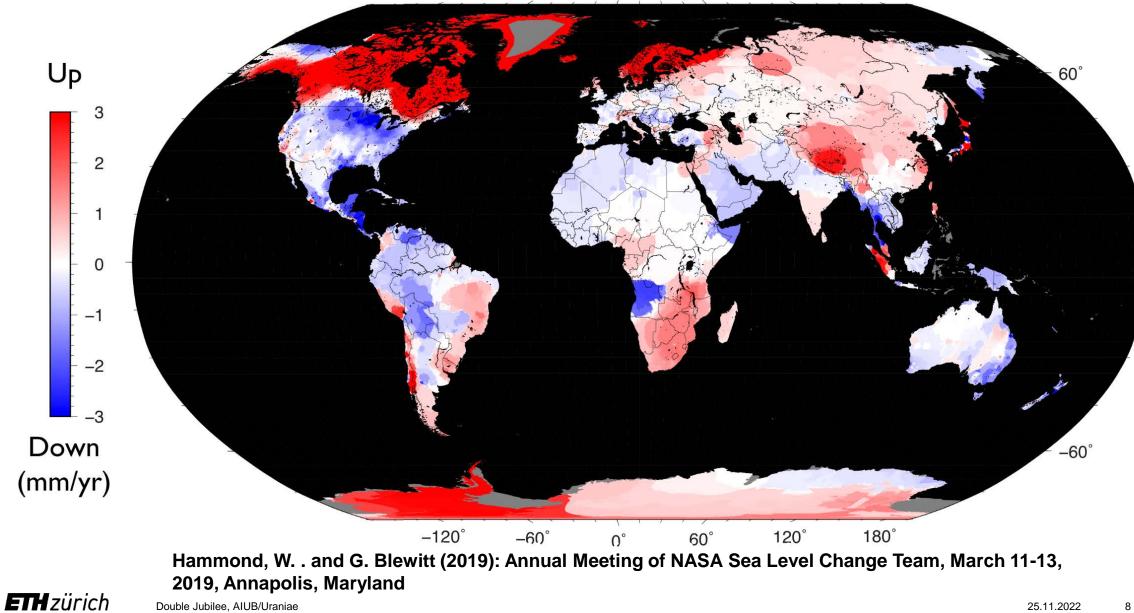
## Examples of GNSS Earth Monitoring: Small Long-Term Trends and Fast Events

#### The Global Picture: >18'000 permanent GNSS Stations



#### **Global Vertical Land Movement from GNSS**

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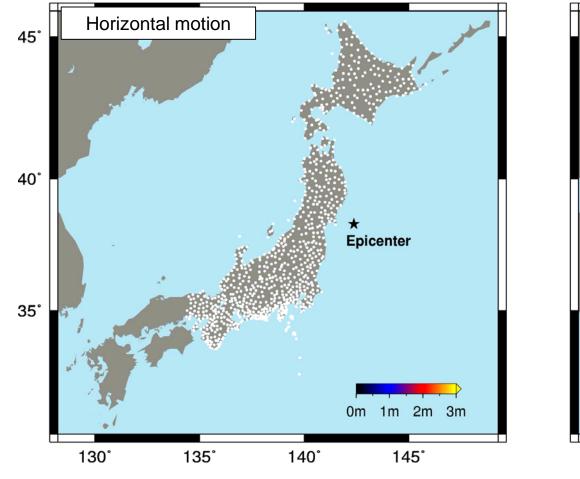
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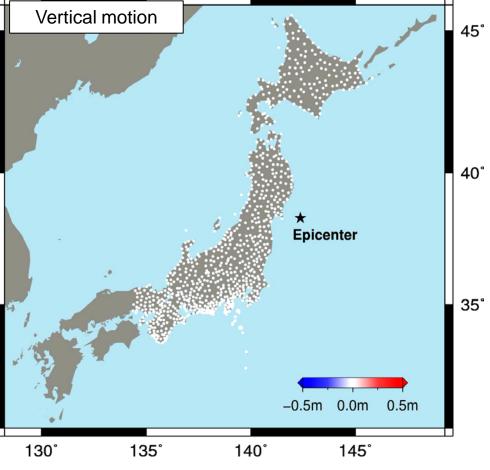
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## Fast Event Detection: Closer and Closer to Real-Time

#### Earthquake ground displacements with GNSS, early warning

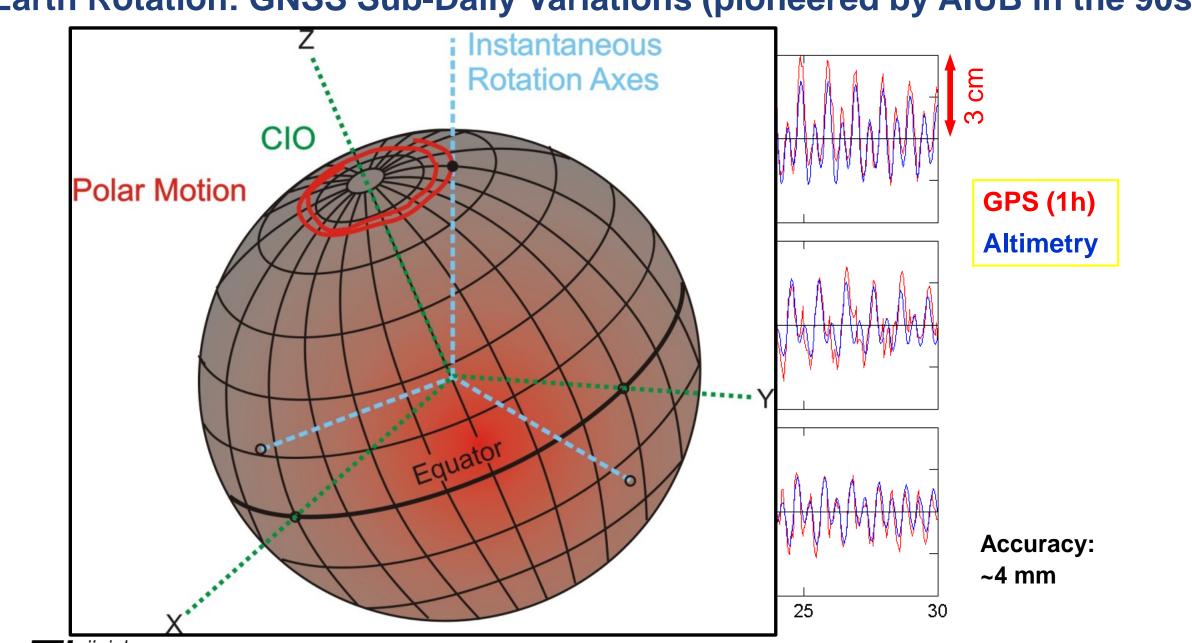
Time since earthquake: 00 m 00 s





 $\rightarrow$  rapid magnitude determination etc.



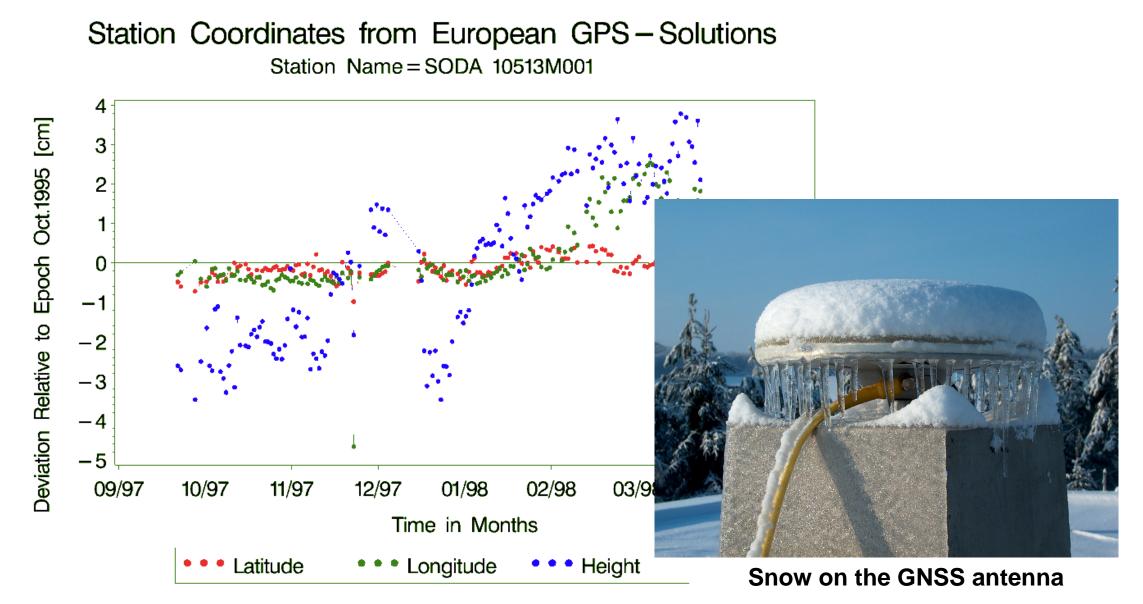


#### Earth Rotation: GNSS Sub-Daily Variations (pioneered by AIUB in the 90s)

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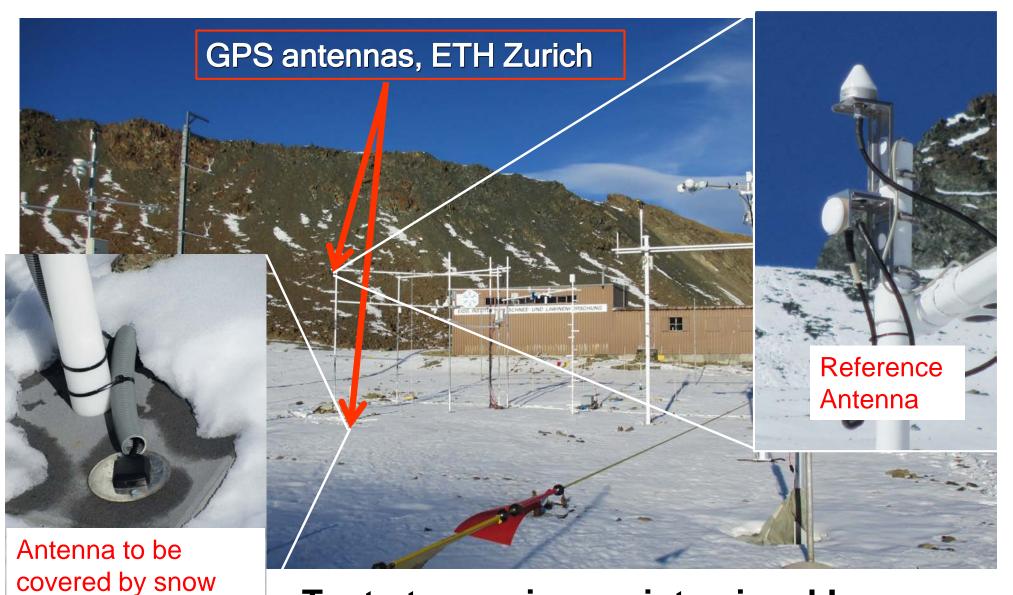
# Overcome Limitations: → Nuisance to Signal

#### **Nuisance/Limitation: Environmental Effects**





#### Snow Monitoring at SLF Weissfluhjoch, Davos



Try to turn nuisance into signal !

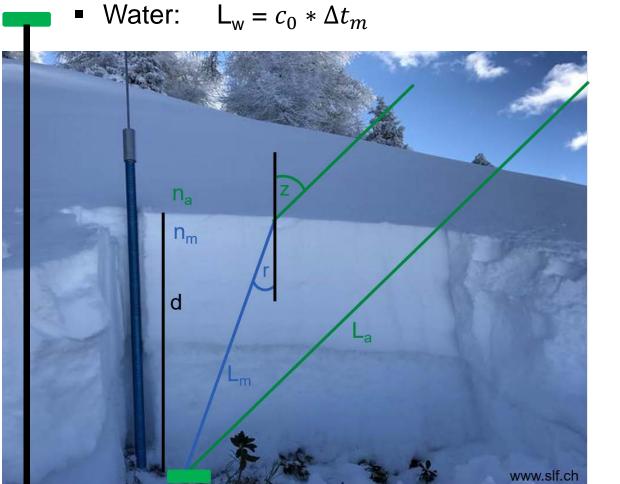
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#### **Estimation of Snow Water Equivalent (Single Layer Model)**

Excess path length δL:

Electrical path length in:

• Air:  $L_a = c_0 * \Delta t_a$   $\delta L_w = L_w - L_a = d * (\sqrt{n_w^2 - sin^2 z} - cosz)$ 



 Introduce additional parameter in GPS observation equation and estimate (SWE):

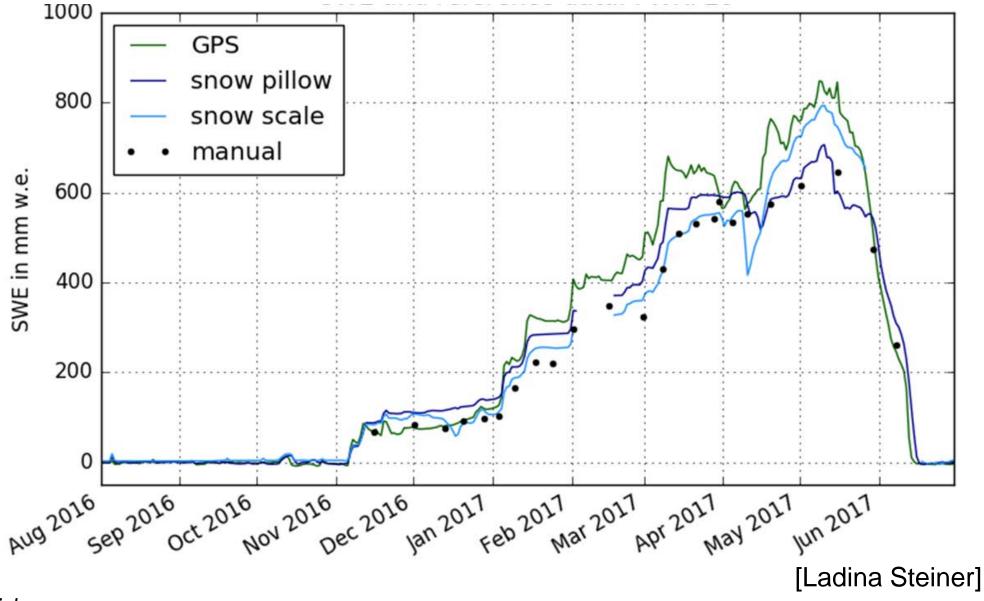
$$L = \rho + \delta \rho + \delta L_w + \lambda N + \varepsilon$$

[Ladina Steiner]

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#### **Snow Water Equivalent Estimation with GPS**





## **Progress in GNSS / Overcome GNSS Limitations: Turn Nuisance into Signal**

- Basis for all high-accuracy GNSS applications: extreme accuracy of the phase measurements (1-2 mm)
- More and more applications by turning nuisance into signal:  $\bullet$ 
  - Ionospheric refraction  $\rightarrow$  Space weather assessment, ionosphere physics

  - Clocks
  - Multipath
  - Snow on antennas

- Tropospheric refraction  $\rightarrow$  Water vapor for weather predictions and climatology
  - $\rightarrow$  Time and frequency transfer, relativity tests
  - $\rightarrow$  Reflectometry and scatterometry, soil moisture, biomass mapping
  - $\rightarrow$  Snow water equivalent, snow height



## Overcome Limitations: -> Miniaturization and Low-Cost

## MPGNET: Multi-Purpose low-cost GNSS NETwork

Motivation: GNSS: a very versatile sensor for monitoring

- Environmental processes
- Natural hazards
- □ Climate change

Especially in remote/alpine areas!

#### Several applications/products:

Ground movements (for landslide or seismic monitoring)

- □ Tropospheric delays (ZTD, ZWD) and integrated water vapor (IWV)
- □ Soil moisture and snow (snow-water-equivalent (SWE))



#### Pilot study in cooperation with MeteoSwiss: Collocation of GNSS payload at SwissMetNet (SMN) sites

- □ Pilot project with 10 dedicated sites (5 stations already deployed)
- □ Test setup at prototype site
- □ Long-term vision: collocation at > 200 sites in Switzerland

Build-up of a low-cost, sustainable GNSS network, providing a variety of highquality products for environmental monitoring

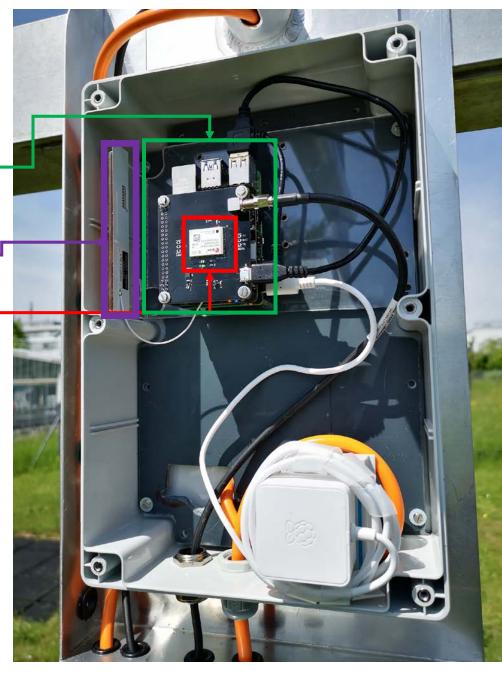
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## **MPGET: Instrumentation**

## Data logging system:

- Raspberry Pi 4: for data logging/transfer and basic scripting
- LTE modem and antenna for data transfer
- u-blox ZED-F9P dual-frequency, multi-GNSS board (GPS, GLONASS, Galileo, BeiDou, QZSS)
- Septentrio PolaNt\* MC multi-frequency, multi-GNSS antenna





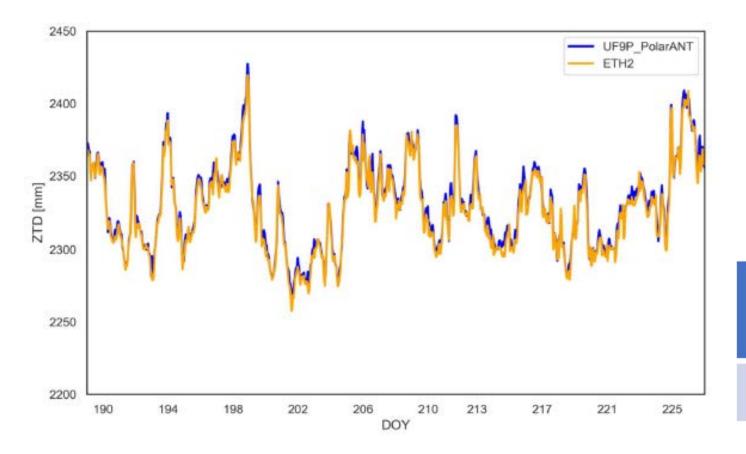
[Matthias Aichinger]

MPG-Aktivitäten (SGK-Meetinng)

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## **Quality of Water Vapor Determination with Low-Cost GNSS**

Comparison of troposphere parameters from low-cost and geodetic-grade equipment





Bias [cm]	SD [cm]	RMS [cm]	R
0.29	0.34	0.44	0.99

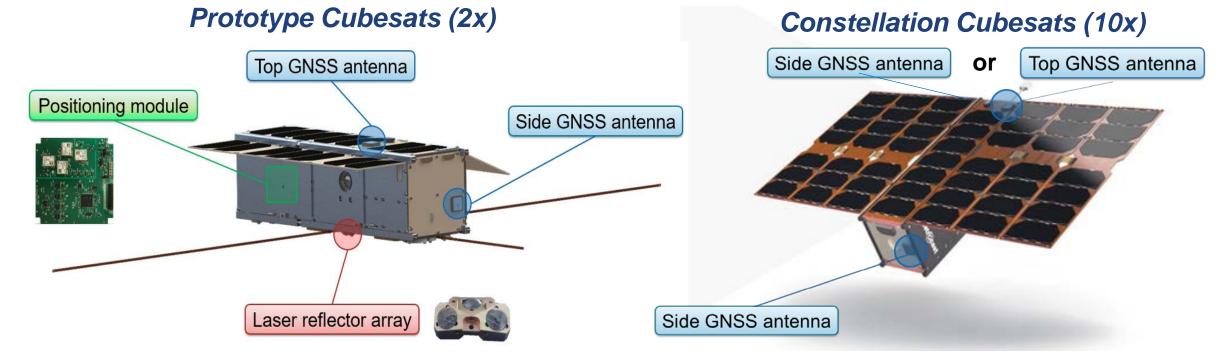
[Matthias Aichinger]

#### Low-Cost GNSS Receivers on CubeSats: Vision

- GNSS (Global Navigation Satellite Systems) have become a very important tool for satellite missions
  - 1. GNSS precise positioning in space is essential to most Earth observation and science missions
  - 2. GNSS for time synchronization in space (e.g. ACES)
  - **3. Earth observation** directly based on GNSS sensors in space: Water vapor, electron content in ionosphere, gravity field, ocean surface, tsunami early warning
- Vision: perform these GNSS measurements with very efficient, small, low-cost, low-power GNSS receivers (miniaturization, small is smart)
  - Geodetic type space receiver  $\sim \in 300'000$ , 3000 g, 15 W, 30 cm
  - u-blox low-cost receiver ~ € 100, 8 g, 0.16 W, 1.5 cm
- Is it possible to do **state-of-the-art science** with low-cost GNSS sensors in space?
- Small satellites/sensors are a must for future formation flying / large constellations

### **Astrocast Cubesats and COTS GNSS Payload**

Collaboration with Swiss company Astrocast



- 4 NEO-M8T u-blox multi-GNSS single-frequency receivers (redundancy)
- 2 taoglas GNSS antennas
- 1 retro-reflector with 3 corner cubes for Satellite Laser Ranging (SLR)

→ GNSS payload: 100 g, 160 mW, €500



## **GNSS Payload Board Development and Testing**

#### **Receivers need a modified firmware**

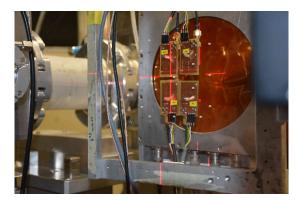
- Altitude and speed limits removed
- Tracking below horizon enabled
- Dynamic model and tracking adapted
- Increased Doppler search range for acquisition

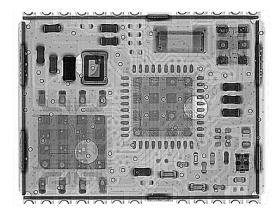
#### **Receivers tested for space capability**

- Performance tests based on simulated GNSS signals in a Low Earth Orbit (DLR)
- Vacuum and temperature tests (RUAG)
- Proton irradiation tests (PSI)
- Destructive physical analysis (ESTEC)



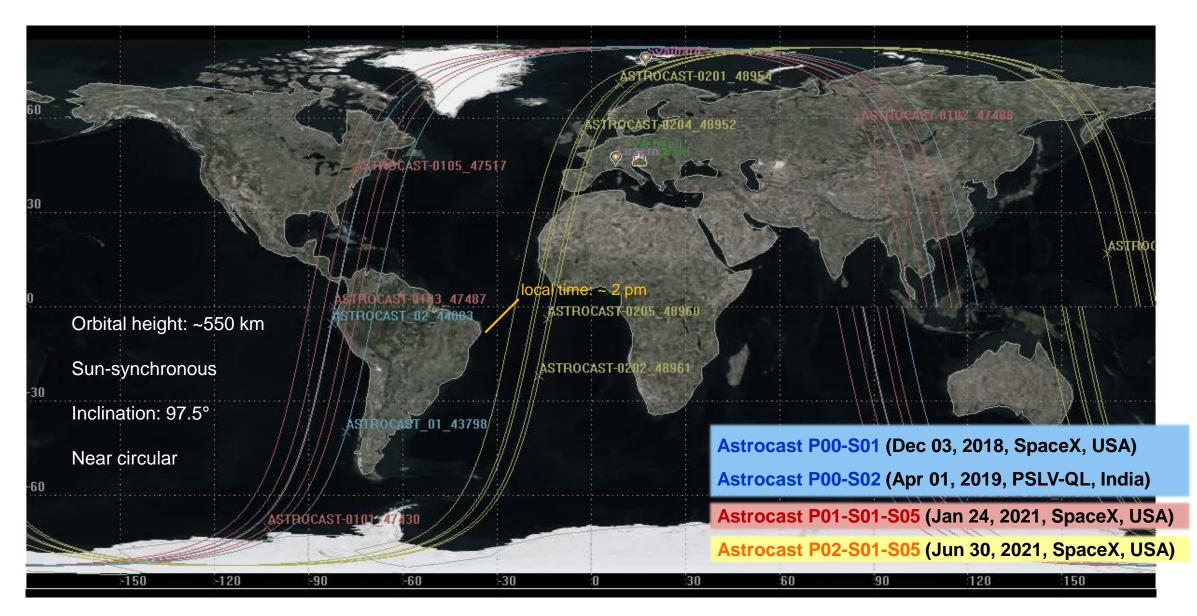








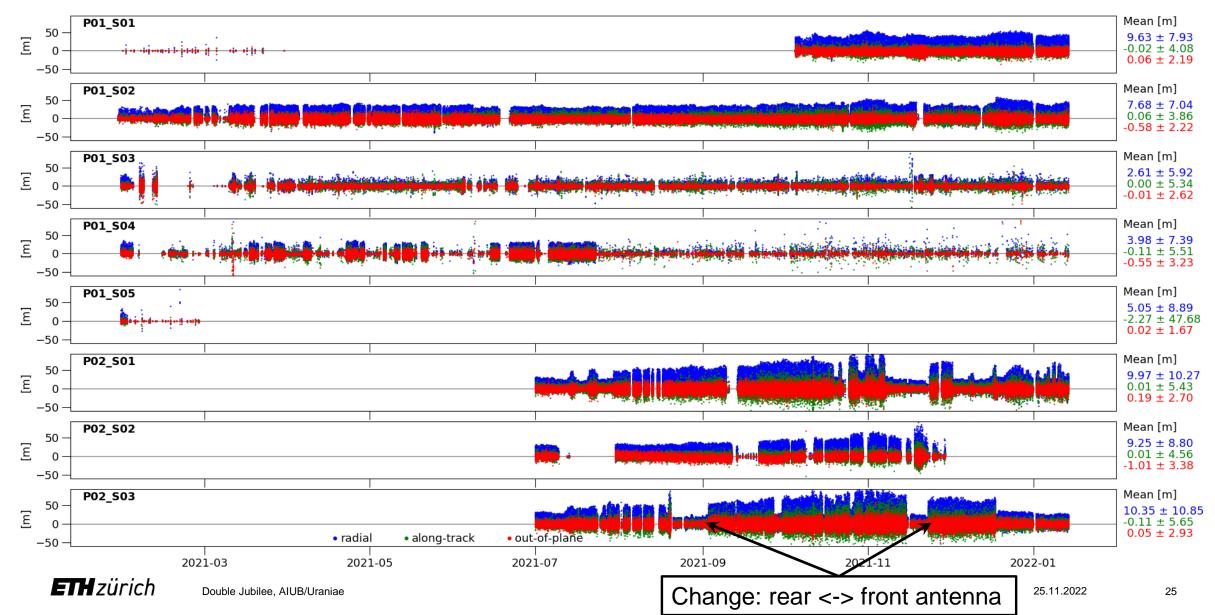
#### **Present Astrocast Cubesat Constellation (12 Cubesats)**



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#### **Constellation CubeSats: Navigation Solutions in Real-Time**

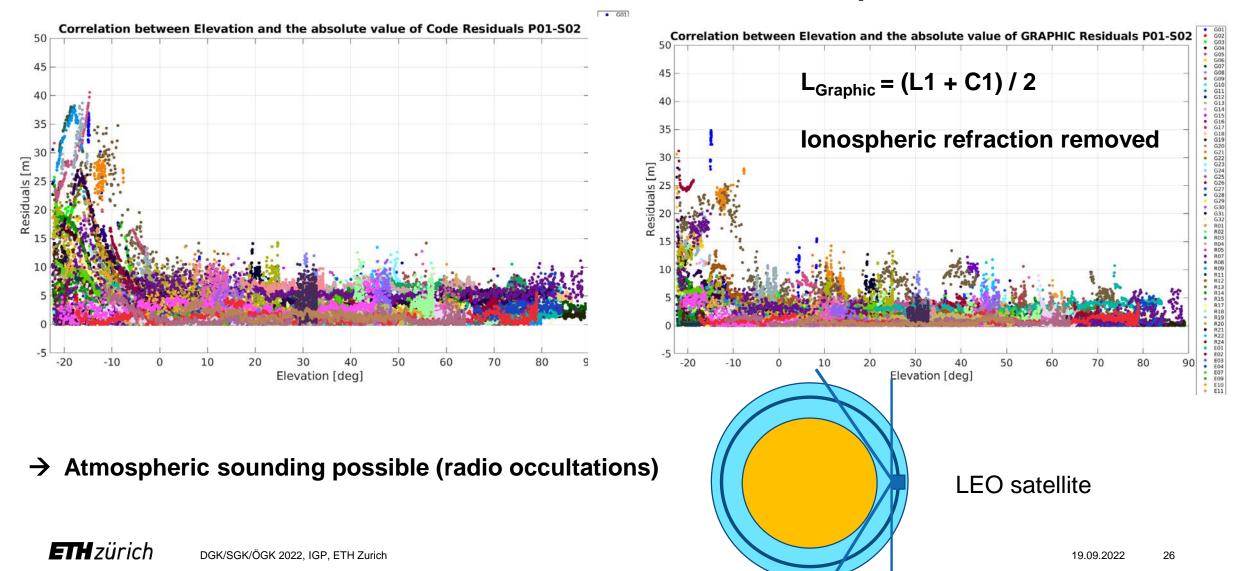
#### Validation with a reduced-dynamic orbit fit over 1 day



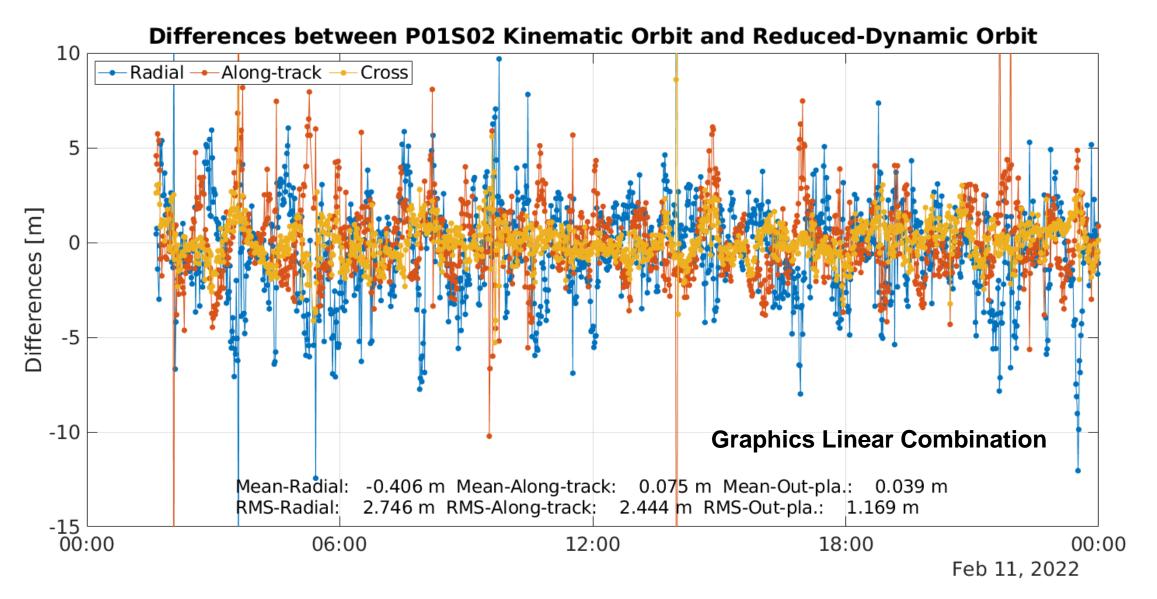
#### GNSS Raw Data Analysis: 100 minutes, 1Hz GPS + GLONASS + Galileo

#### **Code residuals**

**Graphic residuals** 



#### **GNSS** Raw Data Analysis: 23 hours, 1 min, GPS + GLONASS

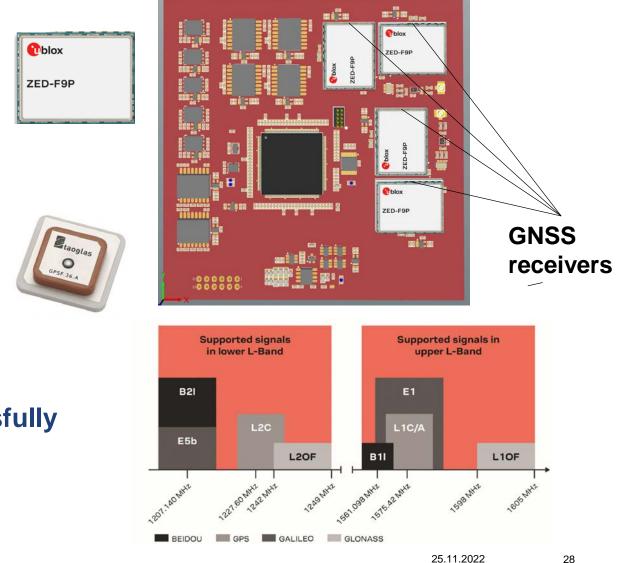


## **Next Generation: Dual-frequency multi-GNSS Payload (COTS)**

#### **Selected COTS hardware components**

- 4 u-blox ZED-F9P receivers
  - Dual-frequency, multi-GNSS
  - Dimensions: 17.0 x 22.0 x 2.4 mm
  - Power consumption: 110 mA @ 3.0V
  - Sampling: up to 20 Hz
- Passive GNSS antenna
- Bandpass filters, LNA and signal splitter

**Environmental tests have already successfully** been performed: vacuum, temperature, radiation, GNSS signal generator tests



## **Future: Cubesat Constellation**

- First dual-frequency GNSS payload:
  - Launch Q1/2023
- Constellation of ~100 Astrocast satellites → network in space
- Earth observation applications foreseen:
  - Tomography of the ionosphere
  - Radio occultation measurements
  - Air density from air drag
  - Gravity field of the Earth
  - Antenna phase center variations of GNSS satellites

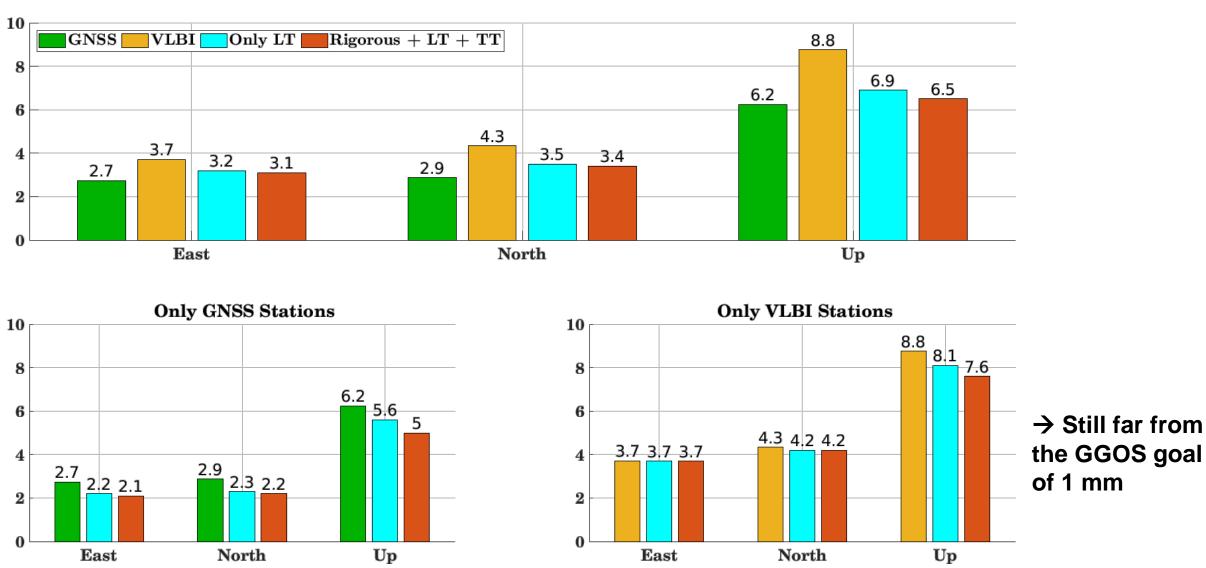


In the near future low-cost COTS GNSS equipment will be sufficiently accurate to perform state-of-the-art science that is nowadays performed with geodetictype receivers and antennas

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# Overcome Limitations: → New Technologies

### **Rigorous Combination of GNSS and VLBI with Local Ties (LT) and Tropospheric Ties (TT): Site Coordinate Repeatabilities for CONT'17**



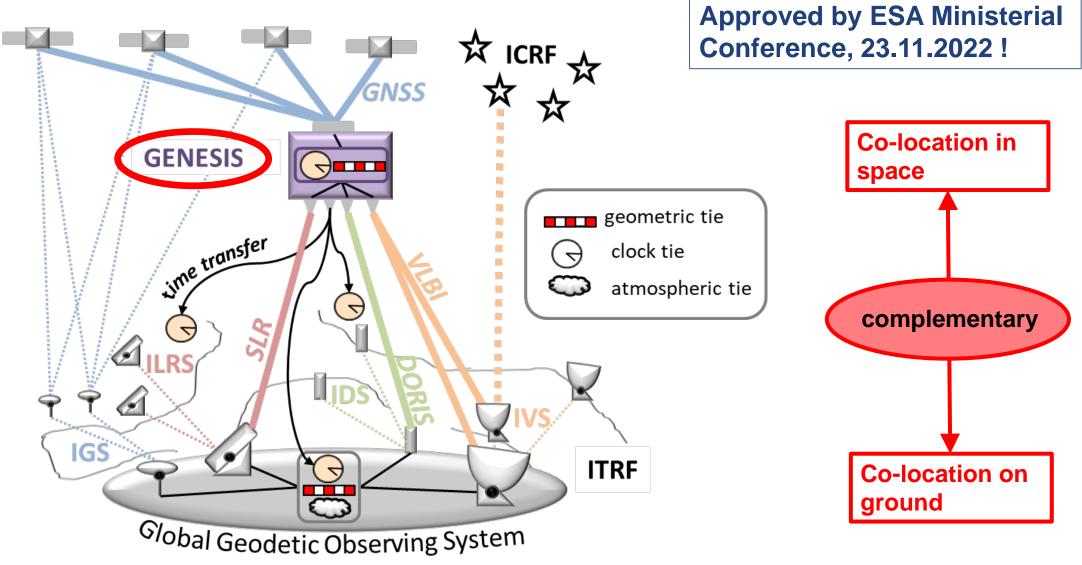
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[Iván Herrera Pinzón]

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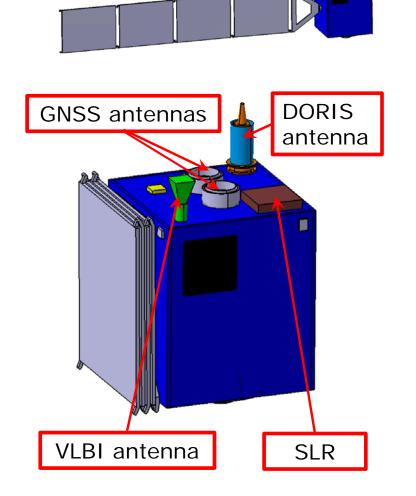
## Future Technologies: GENESIS, Unification of Space and Time Reference Systems





## Future Technologies: GENESIS Characteristics and Orbit Injection

(ESA CDF Study confirmed mission feasibility)



Orbit	6000km circular 95.5° inclination Direct injection Harsh radiation environment		
Wet Mass with system margin	220 kg incl. adapter		
<b>Power</b> with system margin	190 W during nominal mode		
Dimensions Stowed	Max Height	1460mm	
	Max Width	950mm	
	Max Depth	1015mm	
Payloads Mass & power with maturity margin (~ 40 Kg and 75 W)	GNSS 12.2kg, 21W VLBI 2.4kg, 17.4W SLR 1.6kg, passive DORIS 21kg, 26.3W USO 1.8kg, 12W		
Communication/GSO	S-Band used for TT&C LGA Ground station: ESTRACK Station		



## Future Technologies: GENESIS Science Objectives (White Paper)

#### **Reference Frames and Earth Rotation**

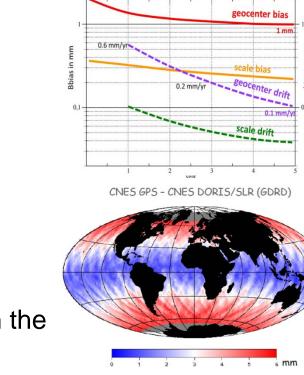
- Unification of reference frames and Earth rotation
- Geocenter and scale (factor 5-10)

#### **Earth Sciences**

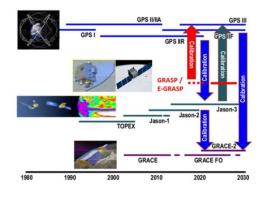
- Long-wavelength gravity field
- Altimetry and sea level rise
- Determination of ice mass loss
- Geodynamics, geophysics, natural hazards
- Thermospheric density measurements, improvements in the Earth radiation budget

#### **Positioning and Navigation**

- Improvement in global positioning
- GNSS antenna phase center calibration
- Positioning of satellites and space probes
- Time transfer over intercont. distances

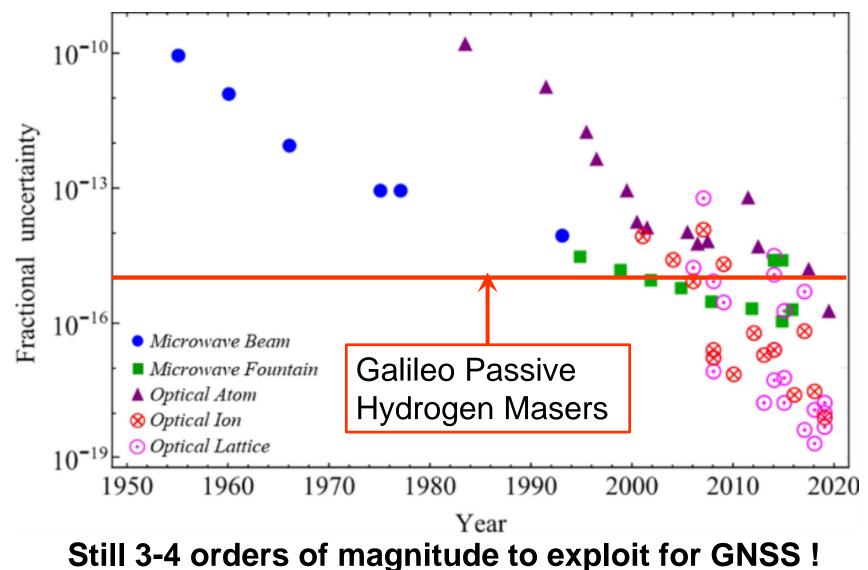


3D-geocenter and scale bias/drift



#### **Future Technologies: Optical Clocks**

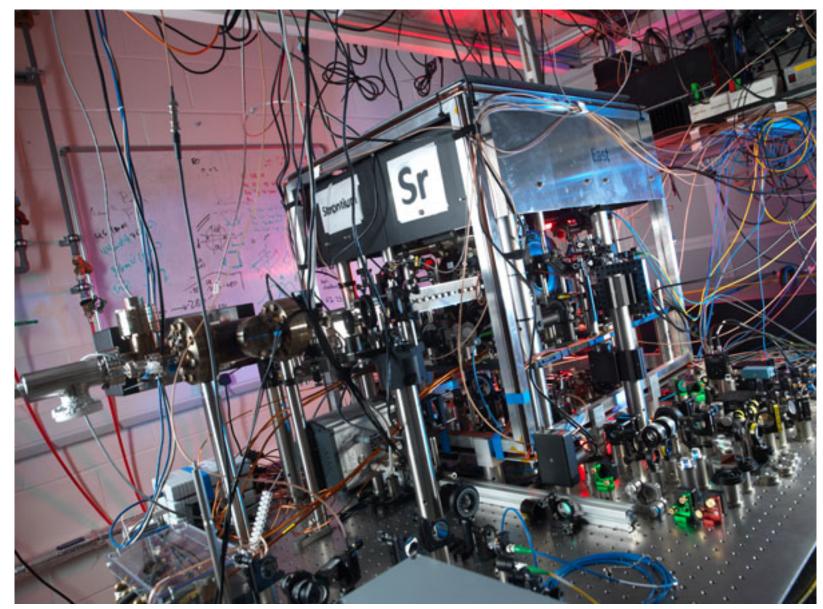
**Clocks are at the heart of GNSS** 



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#### **Future Technologies: NPL Strontium-Lattice Optical Clock**



- Not yet portable and not yet ready for space
- Improvements in navigation signals
- Direct measurement of the gravitational potential (10<sup>-18</sup> ~ 1 cm in height)
- Clock ties (optical fibers), clock modeling
- Time transfer

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#### **Conclusions**

- GNSS can contribute in fascinating ways to a multitude of Earth Sciences (small trends as well as fast events)
- Three ways to overcome limitations: turn nuisance into signal, use miniaturization and low-cost ("small is beautiful"), new technologies
- Small efficient and low-cost GNSS receivers/antennas will largely replace the older legacy instrumentation (in space and on ground)
- GENESIS and optical clocks with 3-4 orders of magnitude to go: Thrilling challenges for young scientists !



## Thanks for your attention ! Congratulations to AIUB and Uraniae !